

PROGRAMMING
MANUAL

MARK I
COMPUTER

LINK DIVISION

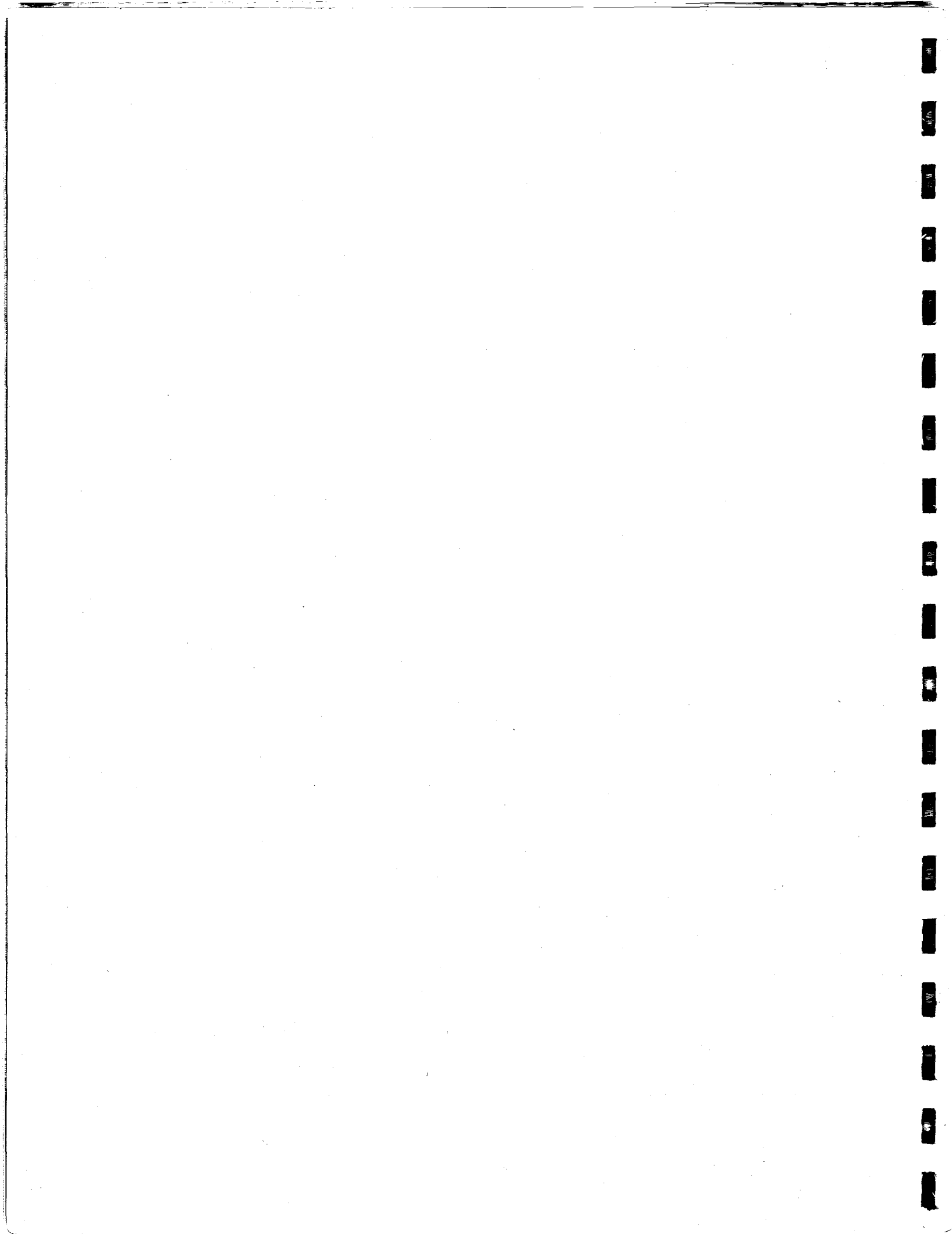
 **GENERAL
PRECISION INC.**

SIMULATION & CONTROL GROUP
BINGHAMTON, NEW YORK

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PROGRAM MANUAL
TWA

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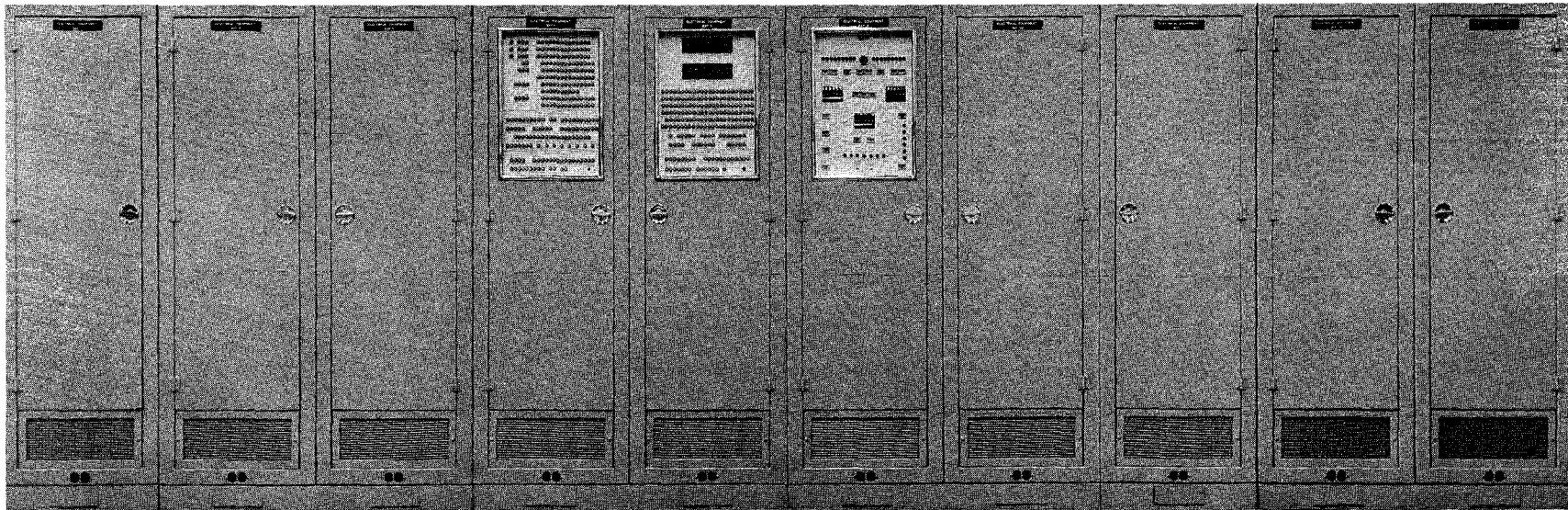
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Figure 1-1. Mark I Digital Simulation Computer

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SECTION I

COMPUTER CHARACTERISTICS

1-1. **GENERAL.** The Mark I computer (figure 1-1), operates according to a written program stored on a magnetic drum. The instructions constituting a typical flight simulator program are stored on the drum, using a paper tape reader and drum loader, in the order in which they are to be performed. In this way, during the operation of the computer, these instructions are read and performed in the order in which they were written without waiting and without the necessity of addressing the location of the next instruction.

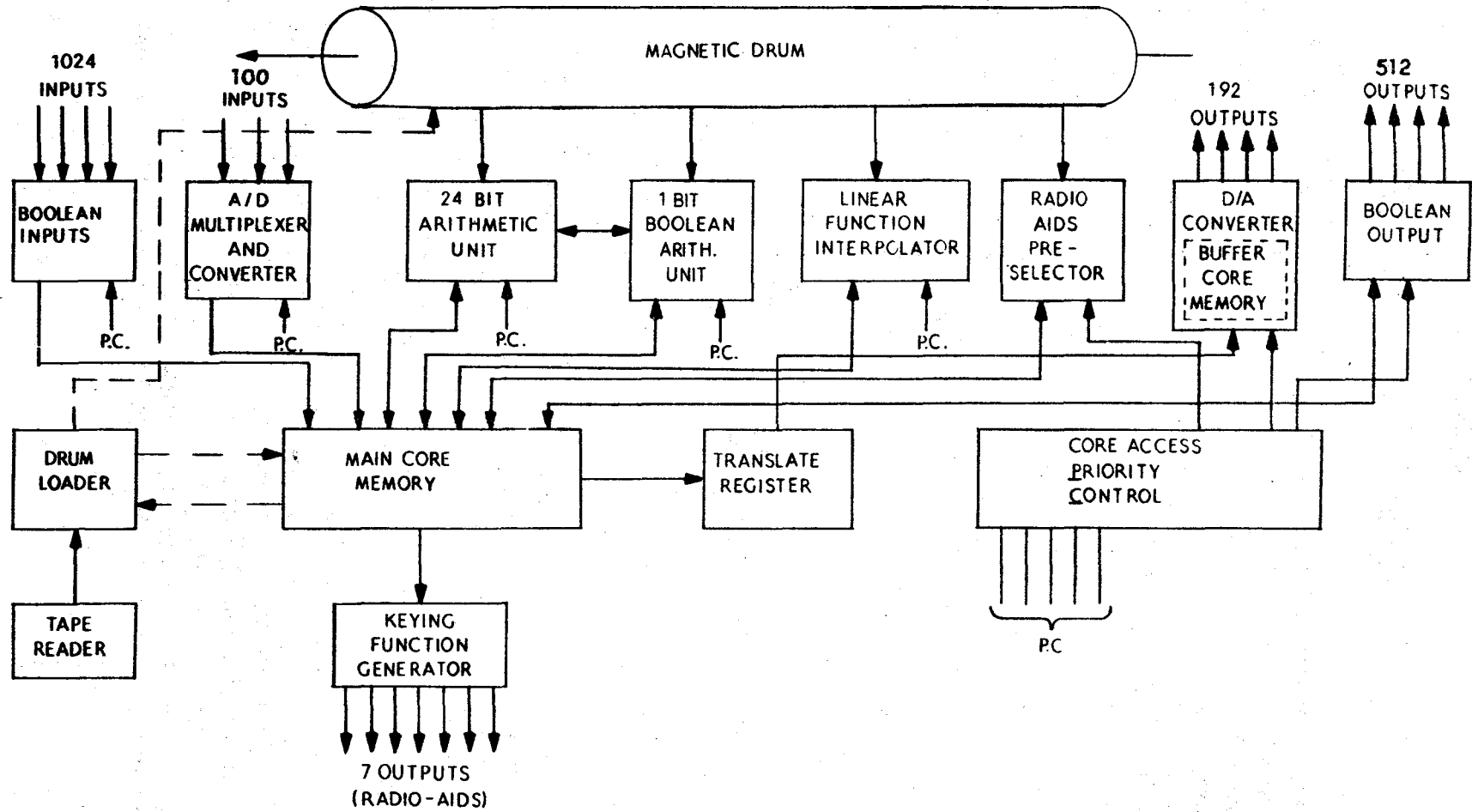
1-2. If an instruction is read indicating an arithmetic operation, this operation is performed in the main arithmetic unit. This unit contains the registers and logic circuitry for performing all arithmetic operations. Similarly, instructions indicating Boolean operations are performed in the Boolean arithmetic unit. The source of all numerical and Boolean data words for these operations is the main core memory, a fast, random-access storage unit that serves as the working memory of the Mark I.

1-3. The Mark I also includes a 16,384 word linear interpolator that operates in parallel with the main program to generate instantaneous values of the many complex functions encountered in aircraft flight and engine computations. These functions are constantly being calculated, recalculated, and stored in preassigned memory locations in the main core memory for use by the main program. Since this is a parallel operation, there is no time lost in the main program calculating these quantities.

1-4. In the Mark I input system, analog and Boolean inputs from the outside world (i.e., simulator controls) are written into preassigned core memory locations, where they may be used by the main program. The output system reads calculated analog and Boolean data out of core memory to activate simulator equipment. These systems also operate in parallel with the main program, eliminating the need for program time to achieve operations.

1-5. Also operating in parallel with the main program is a radio pre-selection unit. This unit compares the location of the aircraft and the frequency to which each of its receivers is tuned with the location and frequency of 350 possible radio transmitters. It then selects the best possible transmitter, if any, that each receiver should be picking up, and stores numerical data concerning the selected transmitters in preassigned core memory locations for use by the main program. Since this is a parallel operation, there is again no time taken up in the main program.

1-6. Figure 1-2 is a simplified block diagram of the various processes within the Mark I.



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Figure 1-2. Mark I Parallel Processes (Block Diagram)

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1-7. MAIN ARITHMETIC UNIT.

1-8. General. The main arithmetic unit acts as the operating center of the computer. This unit consists of a 24-bit accumulator for holding the numerical results of arithmetic operations, all of the necessary logic circuitry for performing arithmetic operations and transferring numerical data, and a salvage register which salvages the old contents of the accumulator when a new word is loaded into it.

1-9. Organization. All numerical operations in the main arithmetic unit are of the fixed-point, binary form. All numbers handled by the main arithmetic unit, either as inputs to or results of arithmetic operations, are in the form of an absolute value and a sign. Sign processes are performed in all arithmetic operations and signs are preserved in the results. All number words are 24 bits in length, the first bit being the algebraic sign and the remaining 23 bits being the absolute value of the binary number.

1-10. If the sign bit is a zero, the number is positive; if it is a one, the number is negative. A typical numerical word in the Mark I is shown in figure 1-3.

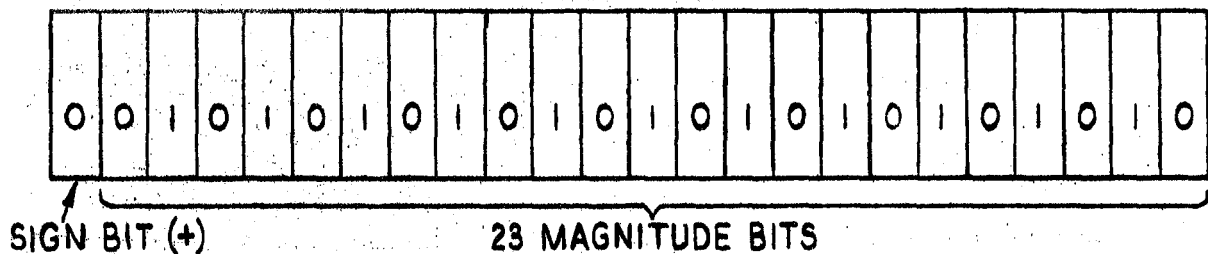


Figure 1-3. Typical 24-Bit Arithmetic Word

1-11. In fixed-point arithmetic, the binary point is assumed to be to the left of the most significant bit (MSB); therefore, the magnitude of the number is always less than 1.0. That is, if the binary point is to the left of the MSB, then the largest magnitude that may be represented is .9999..... in decimal notation or .1111..... in binary notation. All numbers handled by the Mark I must be scaled with the fixed point notation in mind.

1-12. If the result of any arithmetic operation in the Mark I is a number whose magnitude is greater than 1.0, then an automatic overflow process sets each bit of the number equal to one and preserves the sign of the operation. Overflow is possible in the execution of the following instructions: Add, Subtract, Divide, Square Root Step, and Scale Left.

1-13. 24-Bit Arithmetic Accumulator. Almost 60 percent of the instructions for the Mark I cause some operation to be performed on the numerical data contained in the arithmetic accumulator (e.g., add, subtract, multiply, etc.).

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1-14. The bit to the left of the binary point in the accumulator is reserved as a sign bit. This bit gives the algebraic sign of the number defined by the remaining 23 bits-zero for a positive number, and one for a negative number.

1-15. Numerical data may be loaded into the accumulator from the core memory and, by virtue of a special instruction, from the drum. Data contained in the accumulator may be stored only in core memory.

1-16. Most operations performed on data in the accumulator may be initiated and finished in one machine cycle (6.105 microseconds). A few of these operations (e.g., multiply or divide) require several machine cycles to complete; therefore, once initiated, care must be taken that no new instructions arrive requiring operations on data in the accumulator until the previous, more lengthy operation has been completed.

1-17. 24-Bit Salvage Register. Associated with the arithmetic accumulator is a salvage register, 24 bits in length. If an instruction is read that directs a data word be loaded from some source into the accumulator, whatever data happens to be in the accumulator at that time would be lost when the new word is loaded. It is the function of the salvage register to store the data word which has been in the accumulator prior to a "LOAD" instruction. Hence, if the number X is in the accumulator at the time an instruction is read directing that Y be loaded into the accumulator, then one machine cycle later Y will appear in the accumulator and X will appear in the salvage register. The previous contents of the salvage register will be lost.

1-18. The salvage register is an addressable location (0000). That is, it may act as a source of data with which to perform arithmetic operations on the contents of the accumulator. However, the salvage register may not be addressed for a "LOAD" instruction.

1-19. MAGNETIC DRUM.

1-20. General. The drum of the Mark I contains sixteen bands of instructions and constants. Once this information has been written onto the drum the "write" equipment may be disconnected and no further information can get into the drum. The design of the Mark I deliberately prevents any further writing on the drum or modification of information contained on the drum.

1-21. Once the computer selects a band of instructions to read, then every word on that band is read in order, at a rate of one word every machine cycle, until all the words on that band have been read. At this time another band is selected and all of those words are read, etc. As each instruction is read, the operation it indicates is performed. If the operation requires more than 6.105 microseconds to complete, it is then necessary to make the immediately following instructions no-operation instructions (NO-OP), until enough time has been allowed to complete the operation.

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1-22. The 16 bands on the drum are made up of 240 data tracks, each track being one bit wide and 4096 bits in length around the circumference of the drum. Thus, there is a total storage capacity on the drum of over 983,000 bits. The drum rotates at 2400 RPM and requires 25 milliseconds to complete one revolution.

1-23. All of the bits comprising a word are read in parallel (e.g., if the first word in a band of the main program were being read, then the first bit in each of the 16 data tracks making up that band would be read simultaneously). The read rate of the drum is approximately 164 kilocycles or 6.105 microseconds per word, enabling all words in a band to be read in one drum revolution.

1-24. Of the 16 bands of words written around the drum, (figure 1-4) 11 are for the general program, four contain instructions and constants for the linear interpolator, and one is for radio aids.

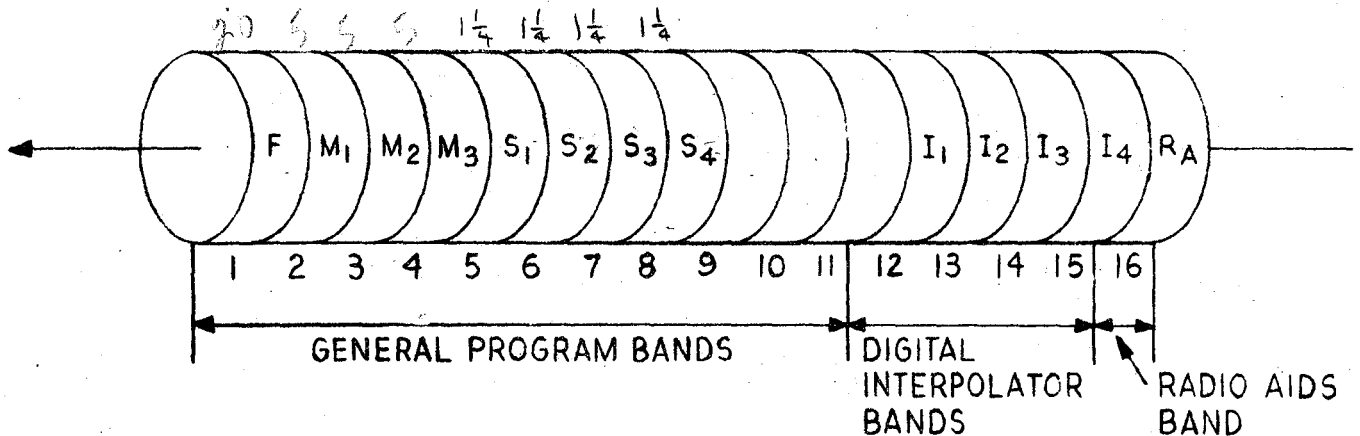


Figure 1-4. Magnetic Drum

1-25. All of the words in the general program portion of the drum are 16 bit words. There are over 45,000 possible words for this portion of the drum (4096 words per band x 11 bands). The four bands of the digital interpolator portion are made up of 11-bit words at 4096 possible words per band. This gives a total of over 16,000 possible words in this section. The 4096 possible words on the radio aids band are all 20-bit words.

1-26. Each time the drum makes one revolution, three bands of instructions and constants are read simultaneously; one band is read and performed by the general program section of the computer, one band by the digital interpolator, and one by the radio aids band.

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1-27. The bands comprising the general purpose portion of the drum are not simply read in order from one through 11. The reason for this is that in simulator work some quantities change much more rapidly than others, and consequently, they require a higher frequency response of the computer (i.e., it is essential to recalculate these quantities much more frequently than is necessary for many other computations in the simulation program).

1-28. The Mark I handles these various computations by dividing the general program bands into three categories; fast, medium, and slow bands. Fast band calculations are performed on every other drum rotation (20 times per second). The instructions for the calculation of those quantities which require frequent updating are all placed on this band. Medium fast band instructions will be performed on every eighth revolution of the drum (5 times per second), and slow bands are each read at intervals of 32 drum revolutions (1 time per every 0.8 second).

1-29. Figure 1-5 illustrates the final order in which all of the general program bands are read.

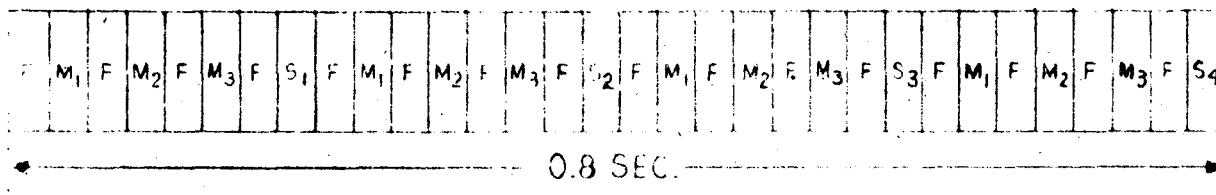


Figure 1-5. General Program Readout Sequence

1-30. Two other bands on the drum are being read simultaneously each time a band of the general program is read (i.e., on each drum revolution). One of these bands is the radio aids band which is read every drum revolution, and the other band is one of the four digital interpolator bands. The four interpolator bands are read in sequence at the rate of one band per drum revolution. Any given interpolator band is read once on every fourth drum revolution.

1-31. Figure 1-6 illustrates the final order in which all of the bands on the drum are read.

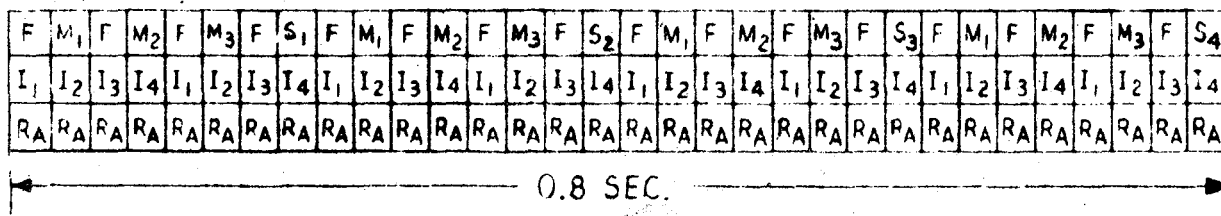


Figure 1-6. Drum Readout

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1-32. CORE MEMORY.

1-33. General. The core memory of the Mark I is a 2048 decimal word, random access memory, each of whose 2048 decimal words is an addressable location. Numerical information may be stored in any word location or the information contained in any word location may be read out on command (non-destructive readout). Only one word location in the core may be read out of, or written into during any given machine operate cycle (approximately 6 micro-seconds). Each word of the main core is 24 bits long, of which the most significant bit is the sign bit.

1-34. It is the function of the main core memory to act as the working storage of the computer. That is, all quantities stored in the main core can be changed, updated, erased, etc.

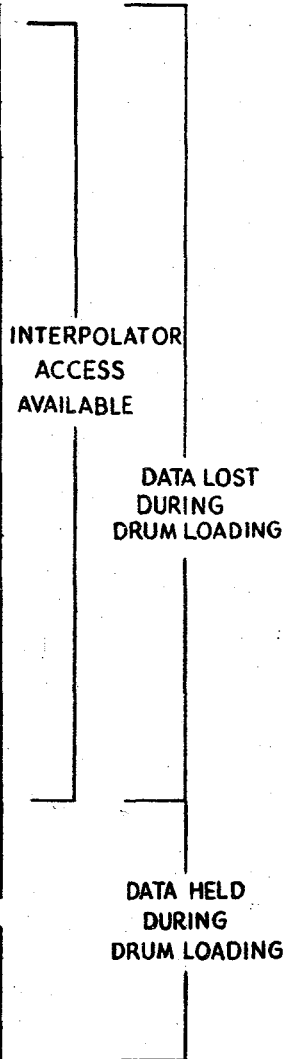
1-35. All the variables in the simulator system equations are each, individually, assigned locations in the core storage, and as each of these variables is re-calculated, or changed, the new value is inserted into the proper core location, thus replacing the old outdated value. All inputs to the Mark I computer from the outside world (e.g. cockpit, instructor's station) come to preassigned storage locations in the main core. All outputs from the Mark I to the rest of the simulator system are read out from their preassigned storage locations in the main core. Independent variables which are used by the linear interpolator for the purposes of function generation are read from their assigned location in the core memory. The linear interpolator also stores computed functional values $[f(X), f(X, Y)]$, in preassigned core memory locations. Figure 1-7 shows the core locations for the various quantities stored in the core memory.

1-36. All mathematical quantities that are needed for a simulator program (with the exception of constants which may be stored on the drum), are stored in core memory.

1-37. Priority. Only one word of the entire core memory may be interrogated or written into during any one machine operate cycle. The many parallel processes of the computer (function generation, radio pre-selection, input-output reading, main program arithmetic, etc.) all require memory access. It becomes necessary, therefore that these various processes be given a priority rating. Any operation of the main program requiring memory access takes first priority. Any operations or instructions in the main program that do not require memory access are considered to be "holes" in the main program and it is during these

MAIN CORE

OCTAL WORD ADDRESS	FUNCTION
0000	NOT USED
0001	DIGITAL SWITCH INPUTS (1,024 BOOLEAN WORDS)
0100	BOOLEAN WORKING MEMORY (496 BOOLEAN WORDS)
0101	BOOLEAN WORKING MEMORY (496 BOOLEAN WORDS)
0137	DIGITAL SWITCH OUTPUTS (512 BOOLEAN WORDS)
0140	DIGITAL SWITCH OUTPUTS (512 BOOLEAN WORDS)
0177	A/D INPUTS - 100 WORDS
0200	A/D INPUTS - 100 WORDS
0375	EXPANDABLE BY 28 WORDS 0376-0377 FOR WORKING MEMORY
0400	D/A OUTPUTS - 128 WORDS
0677	EXPANDABLE BY 64 WORDS
0700	WORKING MEMORY - 64 WORDS
0777	WORKING MEMORY - 64 WORDS
1000	RADIO AIDS - 80 WORDS
1117	WORKING MEMORY - 432 WORDS
1120	WORKING MEMORY - 432 WORDS
1777	WORKING MEMORY &
2000	CONSTANTS - 1024 WORDS
3777	CONSTANTS - 1024 WORDS



DETAIL OF BOOLEAN CORE

OCTAL WORD ADDRESS		
MAIN CORE	BOOLEAN CORE	
0000	0-0017	NOT USED
0001	0020	BOOLEAN INPUTS 64 WORDS X 16 BITS PER WORD = 1024 INPUTS
0100	2017	
0101	2020-2037	BOOLEAN WORKING STORAGE 31 X 16 = 496 WORKING STORAGE LOC.
0137	2777	
0140	3000	BOOLEAN OUTPUTS
0177	3777	32 X 16 = 512 OUTPUTS

MARK I

NOTE:

- OCTAL WORDS 3766-3777 ARE RESERVED FOR THE ARITHMETIC SCRATCH PAD.
- BOOLEAN WORDS 2760-2777 ARE RESERVED FOR THE BOOLEAN SCRATCH PAD.

137 - 2760 - 2777

Figure 1-7. Core Memory

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"holes" that the auxiliary processes of the computer gain access to the core memory. Instructions in the main program such as SCALE, SHIFT, ABSOLUTE VALUE, INVERT, ZERO SLICE, FLAG NEGATIVE, and NO-OPERATION are operations which do not require memory access and thus act as "holes" to auxiliary sections of the computer. Priority for all of the parallel processes of the Mark I is as follows:

- a. Main Program
- b. Digital Function Interpolation
- c. Radio Aids Data Preselector
- d. Analog Input Scanning
- e. Analog Output Scanning
- f. Boolean Output Reading
- g. Boolean Input Scanning

1-38. **Boolean Storage.** Of the 2048 words of memory in the main core, the first 128 words are reserved for use as Boolean storage locations. Only the first 16 bits in each of the 128 words is used for this purpose. This results in a total of 2048 bits of Boolean storage, since a Boolean word is only 1 bit long. The computer is set up to appear as if there were two separate core memory blocks; one being a 2048 word arithmetic core and one being a 2048 word Boolean core. (See figure 1-7.)

1-39. There is a separate Boolean arithmetic unit with its accumulator and salvage register in which all Boolean operations take place. Like its counterpart, the arithmetic core memory, the Boolean core memory acts as the working storage for all Boolean operations. Boolean variables are assigned storage locations here. All Boolean inputs from the rest of the simulator system are read into preassigned storage locations in this memory; and all Boolean outputs from the Mark I to the rest of the simulator system are read out from their assigned storage locations in the Boolean memory.

1-40. Since the Boolean core memory is really made up from 128 words of the main core memory, then any instruction requiring access to the Boolean memory is accessing the main core memory. Any instruction of the main program which requires access, whether it is Arithmetic or Boolean, represents a "highest priority" operation.

1-41. There is no protective circuitry in the Mark I to prevent using a non-Boolean instruction to address the entire contents of a Boolean storage location (the entire

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16 bits of one of the 128 main core words). However, if an attempt were made to address the contents of the entire block, it would be meaningless, if the bits had been used for Boolean storage purposes, to try to use it in an ordinary arithmetic operation. It is conceivable, however, that this sort of operation may be deliberately done in the case where it is desired to provide a direct 16-bit binary output of an ordinary arithmetic quantity without going through the Digital to Analog (D/A) converter. In this case, the main word location containing the 16-bits concerned would be "stolen" permanently from the Boolean section for use by the main arithmetic unit. Any attempt now to write Boolean information into any of the 16 bits of the main word location concerned would destroy the meaning of the arithmetic quantity now permanently stored in that main core location. Boolean storage locations may also be stolen (in blocks of 16) for the purpose of storing an externally coded, 16-bit binary word as an input.

1-42. It is important, if such operations as described in paragraph 1-41 are employed for the purpose of providing direct binary inputs and outputs of ordinary arithmetic quantities, that the programmer look on the entire Boolean core as being reduced in size, and must never address any of the bits concerned for any Boolean purpose. (Again, there is no protective circuitry to prevent the programmer from doing so.)

1-43. ANALOG TO DIGITAL CONVERTER.

1-44. General. It is the function of the A/D converter to take all of the analog inputs to the Mark I (from cockpit, etc.) and convert them into 14-bit binary numbers. There are 100 input lines, expandable to 128. Each of these inputs is converted sequentially to binary and stored in its own individual core memory location. This operation is a process which is carried on in parallel with the main program and is fully automatic. There is a block of core memory locations containing the digital equivalent of the various analog input quantities necessary for equations, and all that is required by the programmer is to address the appropriate core location to employ any of these quantities required in computation.

1-45. Scaling. All analog input quantities are scaled in the range of minus 10 volts to plus 10 volts; these reference voltages being provided by the Mark I. The A/D converter converts these numbers to binary numbers scaled from minus one to plus one.

1-46. Priority. The 100 multiplexed inputs of the A/D converter are sampled and converted into properly signed 14-bit binary words in two drum revolutions. The A/D converter will sample inputs only during the first and third quadrant of each drum revolution, and the 100 A/D channels are spread over the four allowed quarters of the two drum revolutions, so that approximately 25 channels are sampled, converted, and stored in each allowed quadrant. A counter provides the core memory addresses in which each quantity is stored.

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1-47. Memory access is required for storage, and the A/D converter is under the control of the priority circuitry. (Refer to paragraph 1-37 for A/D priority.) When an input has been sampled, the binary equivalent is converted and held until the next input is sampled. At that time the first input is stored in the address dictated by the counter. The counter is advanced, the next input is held and converted and the process continues until all of the inputs have been sampled. The process repeats endlessly, and occurs without programming attention or instructions.

1-48. DIGITAL TO ANALOG OUTPUT SYSTEM.

1-49. General. Digital to analog conversion in the Mark I operates in parallel with the main program. There are 128 independent analog outputs in the Mark I with the ability to expand to 192 outputs. The analog outputs are used to drive indicators, motion systems, recorders, etc. in the external simulator equipment.

1-50. The equations representing each analog output quantity is implemented in the general program to be computed by the Mark I. A fixed word location in the main core memory is reserved for each quantity, and as each quantity is recalculated in the main program, its new value is stored in its respective memory location. The block of core memory locations which contains the analog output quantities is up-dated twice every drum revolution and is sequentially transferred to a buffer core memory. The words in the buffer core are then fed to individual D/A converters whose outputs appear as analog voltages representing the digital quantities.

1-51. Storage locations in the main core which are reserved for output quantities are all sampled by the buffer core at a rate of 80 times a second. The buffer core, in turn, is sampled by the D/A converter 80 times per second, which represents the sampling rate of the D/A output system.

1-52. In order that a maximum of 192 words in the main core memory be read into the buffer core memory, 192 separate memory accesses are required. All of these words will be accessed once during the second quarter of drum revolution, and again during the fourth quarter of drum revolution. Since each word is read twice during each drum revolution (25 milliseconds), the sampling rate is 80 times per second. The drum plays no actual part in this process, but provides a time base for examining the D/A conversion.

1-53. The time required to read each word is 6.1 microseconds (basic machine cycle), therefore one-quarter revolution of the drum represents enough time for 1024 possible memory accesses. The D/A converter has access to core memory, only when the core memory is not being accessed by either the main program, the digital interpolator or the data preselector. There must be at least 192 "holes" in the total access requirements on the main core memory during the second and fourth quarters of a drum revolution or else all of the output words would not get sampled. A counter in the Mark I generates the core memory

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addresses of output quantities which are to be read into the buffer core. As soon as the first address is accessed, the counter advances to the next address and holds that address until an opportunity occurs to interrogate that word. The word is read into the buffer core and the counter advances again. This process continues until all 192 addresses have been interrogated.

1-54. Although the word length in the main core is 23 bits plus one bit for sign, only the sign and the nine most significant bits are read into the buffer core, utilizing only ten of the available 16 bits per word. As words are read out of the main core they are read into a 12 bit translate register. Bits 10, 11 and 12 go through a warbler circuit to produce the round-off bit while bits 1 (2^0), 2 (2^{-1}), and 3 (2^{-2}) are divided by two and drive the vertical wires strung through the three most significant and three least significant bit positions of all 192 words of the buffer core (see figure 1-8). The remaining bits drive the vertical wire, which is strung through the corresponding bit positions of all 192 words of the buffer core.

1-55. BOOLEAN ARITHMETIC UNIT.

1-56. General. The Boolean arithmetic unit is the Boolean counterpart of the main arithmetic unit. It is the purpose of this unit to perform all Boolean operations indicated by instructions in the general program. The logic circuitry of the Boolean arithmetic unit is arranged to perform the functions of "AND" (multiply), "OR" (sum), "INVERT" (compliment), "LOAD", and "STORE". As in the main arithmetic unit (paragraph 1-7), the Boolean arithmetic unit also has an accumulator and a salvage register. Boolean words are one bit in length, and the accumulator is a one bit register which is used to hold the results of all Boolean operations. Boolean words may be loaded into the Boolean accumulator from the main core, and information in the Boolean accumulator may be stored in memory locations in the main core. All Boolean operations indicated by instructions in the general program are performed on the contents of the Boolean accumulator by the contents of the address specified in the instruction.

1-57. Salvage Register. The Boolean salvage register performs the same function as the salvage register of the main arithmetic unit (i.e. to salvage the previous contents of the accumulator when a new word is loaded). Unlike the main arithmetic salvage register, which is only a one-word register, the Boolean salvage register can hold four one-bit words, all of which are addressable. By having a multi-word salvage register, this unit may act as an intermediate, temporary storage unit, thus reducing the core memory access requirements of the Boolean arithmetic unit.

1-58. For the purpose of explaining the operation of the salvage register, consider the sequence of events as a series of several "LOAD" instructions read off the drum (this is a most unlikely series of instructions). Assume the Boolean quantity A is in the accumulator when an instruction directing that the quantity B be loaded is read.

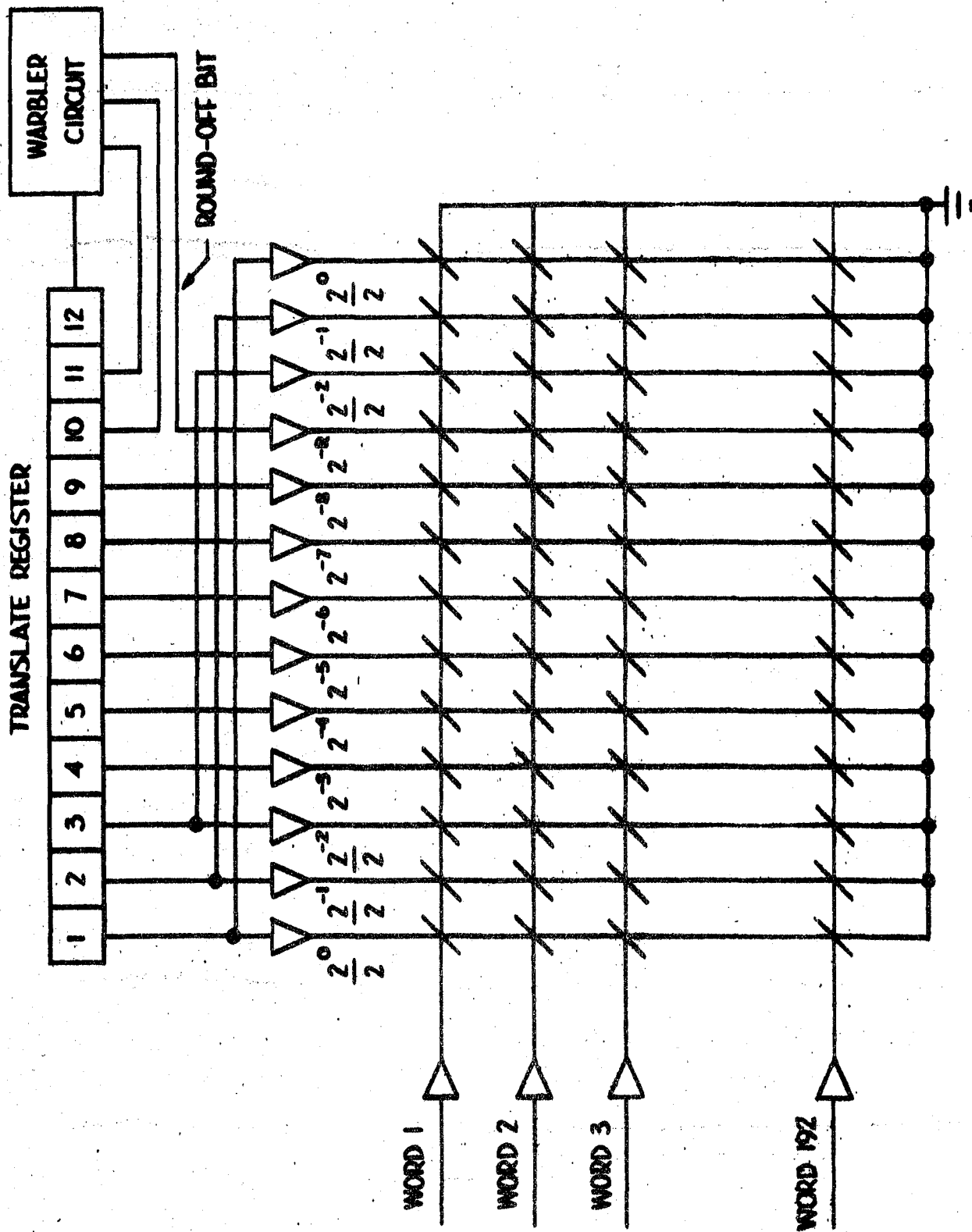


Figure 1-8. 192-Word Buffer Core and Translate Register

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<u>Instruction</u>	<u>Contents of Accumulator</u>	<u>Boolean Salvage Register</u>			
		<u>0000</u>	<u>0001</u>	<u>0002</u>	<u>0003</u>
	A				
Load B	B	A			
Load C	C	B	A		
Load D	D	C	B	A	
Load E	E	D	C	B	A
Load F	F	E	D	C	B

1-59. The four words of the Boolean Salvage Register have addresses 0000 through 0003 and the contents of any of these word locations may be used to perform a logical "AND" or "OR" with the contents of the Boolean accumulator. That is, they are addressable locations. The contents of any of these salvage register locations may be "loaded" into the Boolean accumulator. However, the contents of these locations may not be stored in the Boolean core. Only the contents of the accumulator may be stored in the core memory.

1-60. DIGITAL LINEAR FUNCTION INTERPOLATOR.

1-61. General. Function generation in the Mark I is a process which is done continuously, in parallel with the main program of the machine, and thus, because of the saving of computation time in the main program, contributes largely to the real-time dynamic response of the Mark I. Function generation is accomplished by means of linear interpolation between the ordinates of fixed "breakpoints". Figure 1-9 illustrates an arbitrary function of X whose X axis has been divided into eight equal segments. These eight segments are defined by nine breakpoints: 0, 1/8, 1/4, 3/8, 1/2, 5/8, 3/4, 7/8, and 1.

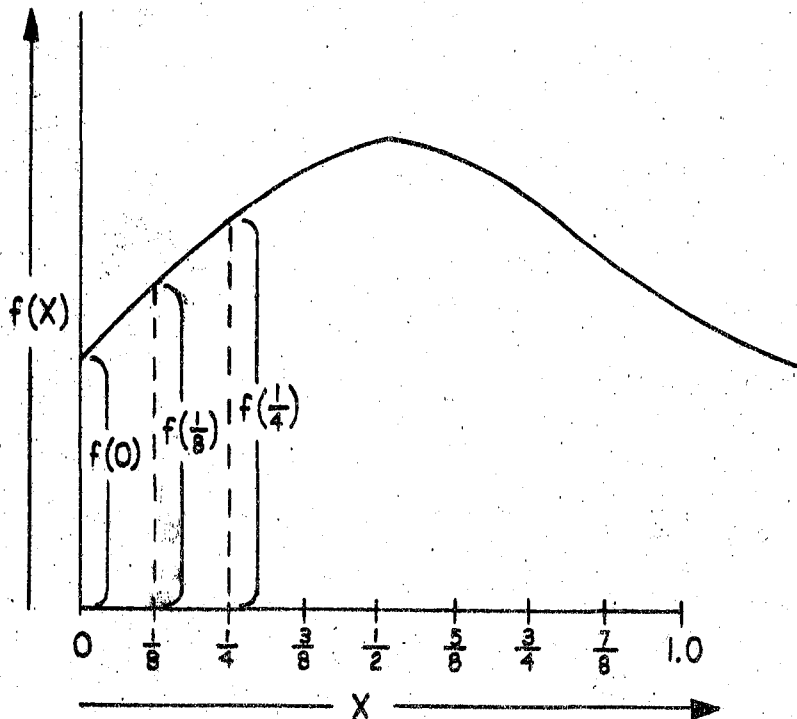


Figure 1-9. Linear Function Curve

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1-62. If the ordinates of these nine breakpoints are known, (e.g., $f(0)$, $f(1/8)$, $f(1/4)$, $f(3/8)$, etc.) and if the independent variable X is known, then it is possible to perform a linear interpolation to determine $f(X)$. For instance, if X lies between $1/8$ and $1/4$ then it is possible to interpolate between $f(1/8)$ and $f(1/4)$ to obtain a very close approximation of $f(X)$.

1-63. The linear interpolator has its own arithmetic unit with a parallel binary adder and the appropriate registers and logic circuitry to do interpolations.

1-64. Scaling. All numbers handled by the Mark I must be scaled so that the magnitude is not greater than one. This also applies to the function interpolator. Therefore, both the independent variable, X , and the ordinate value, $f(X)$, must be scaled so that their magnitudes are not greater than one. All numbers handled by the interpolator are assumed to be positive, so variables and functions must be scaled accordingly.

1-65. Flow Of Information. The four bands on the magnetic drum which are used for function interpolation serve the purpose of storing the ordinates of the breakpoints of all the function curves. The drum also contains the core memory location of the independent variable, and the core memory location in which the calculated value of the function will be stored. Each different function is represented by its own block of information listed on one of the bands, all of the blocks being listed in order around the bands. Figure 1-10 shows the flow of information for function generation.

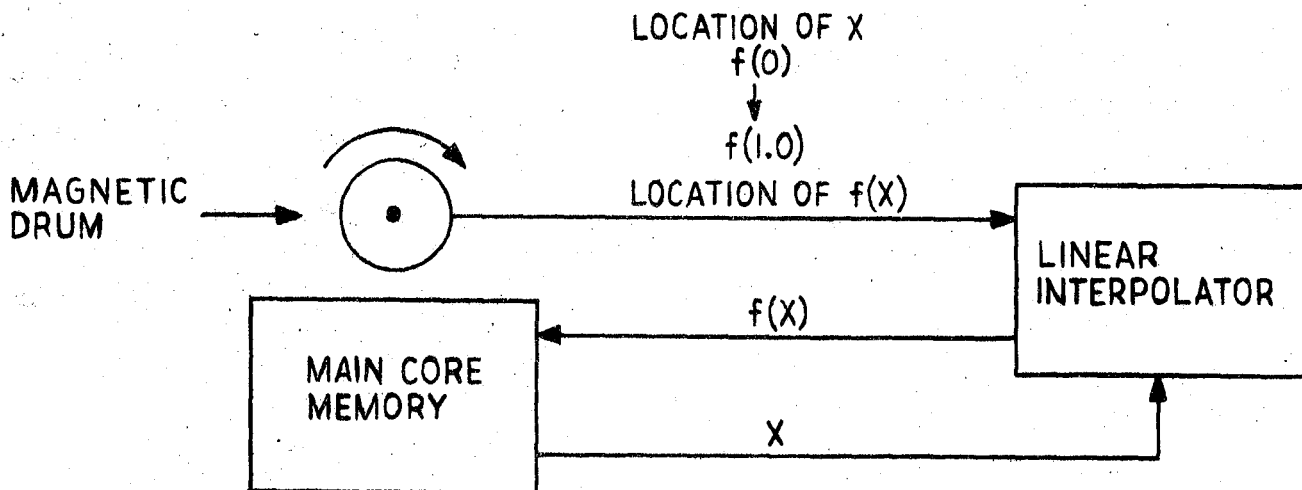


Figure 1-10. Flow of Information (Interpolator)

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1-66. It is unnecessary to store the X values of the breakpoints because, since these breakpoints are fixed at 0, 1/8, 1/4, etc., it is only necessary to build the logic of the interpolator in such a way that it can look at the value of X and recognize between which two breakpoints it lies. Consider the binary representation of the numbers, 0, 1/8, 1/4, etc.

```

0 = 000'0000000
1/8 = 001'0000000
1/4 = 010'0000000
3/8 = 011'0000000
1/2 = 100'0000000
5/8 = 101'0000000
3/4 = 110'0000000
7/8 = 111'0000000
1 = 111'1111111
    
```

1-67. An examination of only the first three digits of X will determine between which two breakpoints X lies. If $X < 1/8$ then its first three digits will be 000; hence $0 \leq X < 1/8$. If $1/8 \leq X < 1/4$, then the first three digits will be 001. Figure 1-11 shows how the first three digits of X will determine between which two breakpoints it lies.

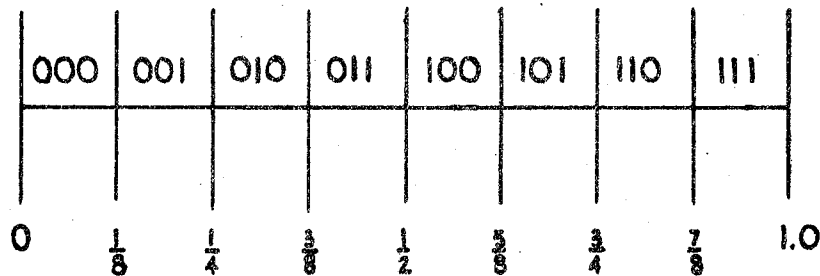


Figure 1-11. Decoding Scheme Determining "Location" of X

1-68. In a block of words on the drum concerning a given function (assume a function of a single variable), the first word that is listed is a control word which serves the purpose of identifying a new function and describing whether it is a function of one, two, or three variables. The second word listed is the memory location of the independent variable. Following this will be the ordinates of the nine breakpoints in order beginning with $f(0)$. The memory location of X, the independent variable, is listed before the ordinate information. Memory access by the main program has priority over access requirements by the interpolator; therefore, the interpolator may have access to memory only during "holes" in the main program. In order to ensure that the current value of the independent variable is obtained from its memory location, its address must be repeated five times. (One of the rules governing the general purpose program is that memory cannot be accessed more than four times in a row or more than 60 percent of the program.)

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1-69. Once access to the core memory has been gained, the current value of the independent variable is read into a register in the interpolator. The first three digits of X (the independent variable) are examined to bracket X between two breakpoints. This process is completed before the data field is read off; therefore, before the first ordinate is read, the interpolator already knows which two breakpoints bracket X . As the ordinates are read off the drum, only the two ordinates concerned, $f(X_n)$ and $f(X_{n+1})$, are held for interpolation. The other ordinate words are ignored by the interpolator. The result of the interpolation is $f(X)$. $f(X)$ is held in the linear interpolator until a word is read off the drum directing that $f(X)$ be stored and giving the location in the core memory in which to store it. The location of $f(X)$ must also be repeated five times to ensure memory access.

1-70. Timing. In the event that X was located between $7/8$ and 1.0 , the interpolator would have to wait until the eighth and ninth ordinates were read off the drum before it could begin its calculations. This means that some time must be allowed after the last ordinate is listed before the memory location of $f(X)$ is listed. This time is to allow the interpolator to finish its calculations before directing it to store the results.

1-71. In the case of a single variable function, (X) , two blank words (12 usec. approximately), allows sufficient time for the interpolator to finish its calculations. In the case of a function of two variables (X, Y) , four blank words are necessary, and, for the three variable function (X, Y, Z) , six blank words are necessary.

1-72. The final arrangement for the data and instructions for some single variable function (X) , is shown in figure 1-12.

1-73. Two Variable Function. A function of two variables as handled by the Mark I will be in the form of a "family" of nine single-variable functions. (See figure 1-13.)

1-74. To describe a two variable function requires 81 ordinates. The address of Y is listed after listing the address of X , and must also be repeated five times to ensure memory access. The 81 data points are listed in zone five beginning with the $f(X, Y = 0)$ curve and ending with the $f(X, Y = 1)$ curve.

1-75. There would be a total of 729 data words for a three variable function: nine data words for X , times nine data words for Y , times nine data words for Z . The address location of the independent variable Z is listed after the Y location and must also be listed five times to ensure memory access.

1-76. Since there are four bands on the drum for the linear interpolator and 4096 words around a single band, there are a total of 16,384 words of storage capacity on the drum to be used for function generation alone. Twenty-two words are required to describe a function of a single variable, so if only single variable

MARK I

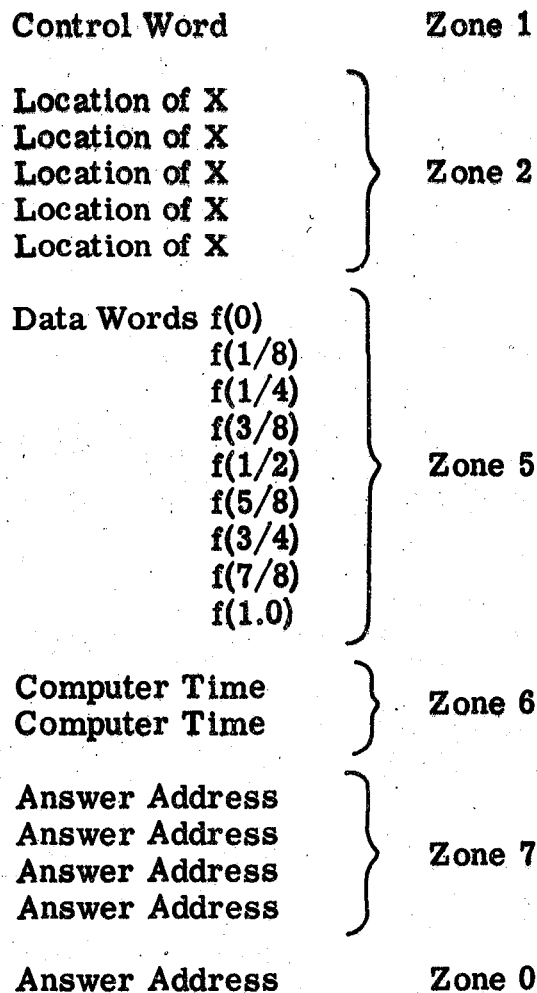


Figure 1-12. Interpolator, Single Variable Function Arrangement

functions were stored on the drum, there would be sufficient capacity to generate over 740 different functions. Since two and three variable functions are also stored, the capacity is affected accordingly.

1-77. It is possible, by using certain indexing bits in the control word, to use the same function data or curve with four different independent variables, the results to be stored in four different locations. This reduces the necessity for having to repeat the data for the same curve several times on the drum, thereby saving storage capacity on the drum. The main "drawback" in using this method is that indexed functions are only recalculated $1/4$ as many times as non-indexed functions which are recalculated at a rate of ten times per second.

1-78. All of the words on the four bands of drum storage for the Linear Function Interpolator (LFI) are 11 bits long. Of these 11 bits, one, the MSB, is reserved as a control bit and the remaining ten are for data. Numerical data (ordinates of the

MARK I

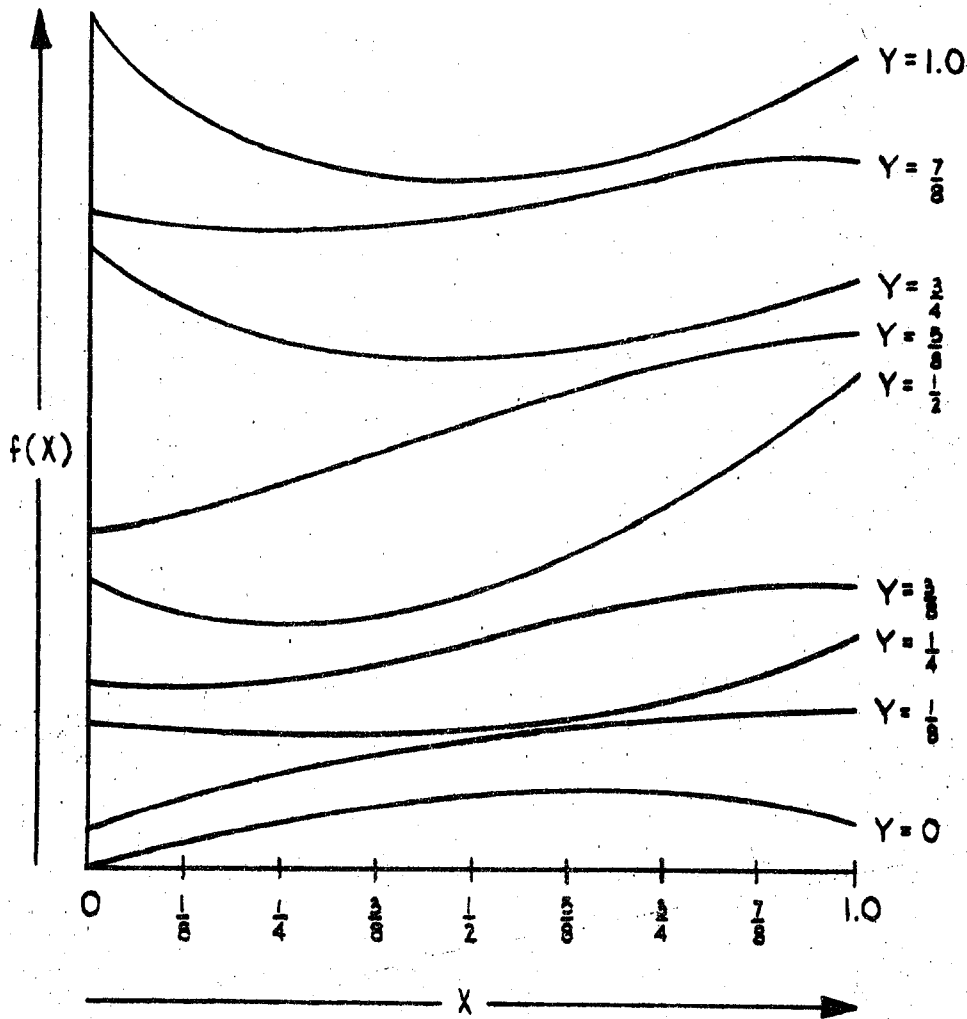


Figure 1-13. Two Variable Function

breakpoints) are only listed with ten binary digit resolution. Arithmetic in the interpolator is carried to 14 places and rounded off.

1-79. RADIO AIDS DATA PRESELECTOR.

1-80. General. It is the function of the Radio Aids Data Preselector to examine a total of 350 different radio transmitters and select the best possible station, if any, that each of the simulated aircraft receivers should be receiving. The Radio Aids Data Preselector operates in parallel with the general program of the Mark I, and it is completely automatic, without need for programmer attention.

1-81. The automatic radio system treats each transmitter as a separate entity. Under this concept, an ILS facility would consist of a localizer transmitter, two 75-megacycle marker transmitters, and two low frequency compass marker transmitters, a total of five separate units.

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1-82. Each simulated transmitter is counted separately with the following exceptions:

a. The glideslope facility is provided as a component of the localizer system and does not require a separate transmitter in the total facilities count.

b. A DME (Distance Measuring Equipment) system, if co-located at a VHF Omni-Range Station, is associated (from a computational standpoint) with the related azimuth facility and does not count in the total.

1-83. The 350 available transmitters are divided into five groups according to the type of facility; the maximum number of facilities in each group may not be exceeded, although it is not necessary that all facility channels be employed if a lesser number is desired. The five groups are:

a. Low-frequency transmitters: This group includes low-frequency beacons, low-frequency compass locator facilities and A/N range stations. 127 such facilities can be represented, of which 32 may be A/N range stations.

b. VHF/UHF facilities: These include VOR transmitters, TACAN transmitters, Navy UHF direction finder transmitters and ILS transmitters. 127 independent VHF/UHF facilities can be represented.

c. Outer Markers: The system can represent 32 Outer Markers.

d. Middle Markers: The system can represent 32 Middle Markers.

e. Fan and Z Markers: The system is capable of representing 32 Fan or Z markers which can be intermixed in any desired proportion.

1-84. All information for the 350 transmission facilities is contained in 4096 successive 20-bit parallel words which occur sequentially at 6.105 microsecond intervals around the surface of the drum. Except for the 20-bit length, these words are similar in timing to the instructions and interpolator data contained on the remainder of the Mark I program drum.

1-85. Since all 350 possible facilities must be scanned every drum revolution (40 times per second), preselection is limited to station frequency, latitude coordinate, and longitude coordinate. Preselection in this manner permits the use of simple electronic circuitry and ensures that time-wise, the facility will be inspected.

1-86. Frequency Inspection. For each transmitter represented, an upper and a lower frequency limit is assigned. The facility preselector system will find a particular facility acceptable for a particular receiver from a frequency standpoint, if and only if the frequency of the receiver falls between the upper and lower frequency limits assigned to that facility.

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1-87. Although all marker transmitters operate on 75 megacycles, artificial frequencies are assigned in the Mark I. The range of these frequencies are 0 to 1.0, 0 to 0.499, and 0.5 to 1.0. The second two frequency ranges are used to prevent overlaps where more than one marker facility is simulated at any one station.

1-88. Low frequency transmitter facilities are assigned frequency limits by subtracting and adding to the assigned operating frequency a number somewhat larger than half the receiver bandwidth. The resultant two numbers are used as the lower and upper frequency limits.

1-89. VHF/UHF receivers employ digital tuning with discrete frequency assignments. The limits (lower and upper) assigned to the transmitter are numerically close together to ensure that only those transmitters which exactly match the receiver's frequency will pass the frequency test for a given receiver.

1-90. Geographic Position Inspection. The method employed for geographic inspection is assigning two pairs of coordinates to each of the 350 possible facilities. These coordinate pairs represent the upper, lower, left and right boundaries of a rectangle which contains a given facility. These rectangles are arbitrarily assigned so that the left and right boundaries (limits) are in the East-West direction, (longitude axis) and the upper and lower boundaries are in the North-South direction (latitude axis). (See figure 1-14.)

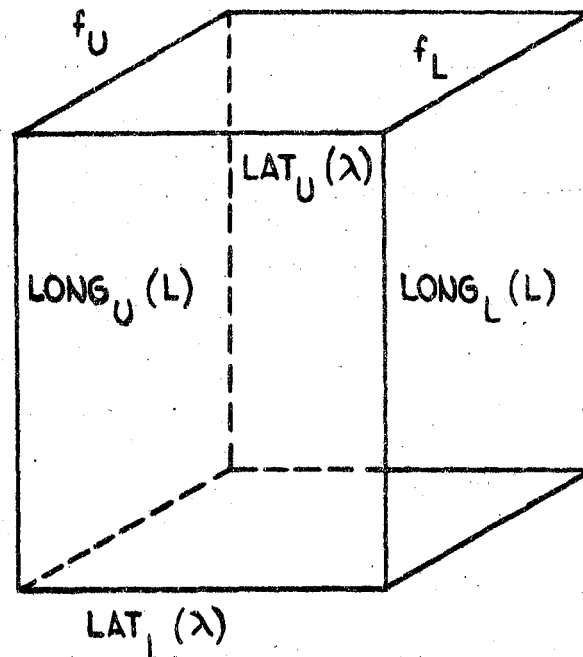


Figure 1-14. Frequency and Geographical Coordinates, Single Transmitter

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1-91. Each rectangle is assigned to be as large as possible, although care must be taken to ensure that there are no overlaps of rectangles assigned to different facilities either operating on the same frequency (in the case of markers and VHF/UHF facilities) or operating on adjacent frequencies so that two or more facilities could be within the bandpass of the receiver (in the case of LF facilities).

1-92. The assignment of rectangles to each of the facilities is made by the facility grouping in the computer. For example, there are three groups of markers, Outer, Middle and Fan/Z markers. Even though all three groups operate on the same frequency, only one marker transmitter from each of the three groups can be selected at any one time. Therefore, it is only necessary to assign the rectangles in such a way that for a given group, no overlapping rectangles are assigned. Overlapping rectangles are permitted between facilities of different groups, and because of the programmed calculations involving range and radiation pattern, no interference will result, unless two or more markers of different types that in reality do interfere, are represented and can be received simultaneously.

1-93. Preselection. Preselection of one of the facilities within a group is accomplished by determining whether or not the aircraft is within a pair of left and right Longitude coordinates, a pair of upper and lower Latitude coordinates and whether or not the receiver is tuned to a frequency within a pair of upper and lower frequency limits. Each transmitter is effectively placed within a rectangular box having North/South and East/West boundaries (i.e., the box cannot be placed diagonally on a map). The third dimension of the box is frequency, the three dimensional concept is for convenience is visualizing the physical domain within which the individual transmitters are eligible for reception.

1-94. It is possible to operate in a space free of any of the individual boxes in which case no station may be received. This situation is immediately altered if the receiver tuning is changed since this constitutes an effective movement in the vertical or frequency coordinate in the imaginary three dimensional space, which may result in the preselection of a station whose "box" has been entered.

1-95. When a station of a group meets simultaneously all three preselected criteria, the stored data which completely describes that station is transferred to a specific group of core memory locations associated with the receiver capable of receiving that station. The transferred data is used by the programmer to calculate signal strength, range by orientation, beam pattern, call letters, and so forth, according to the type of facility.

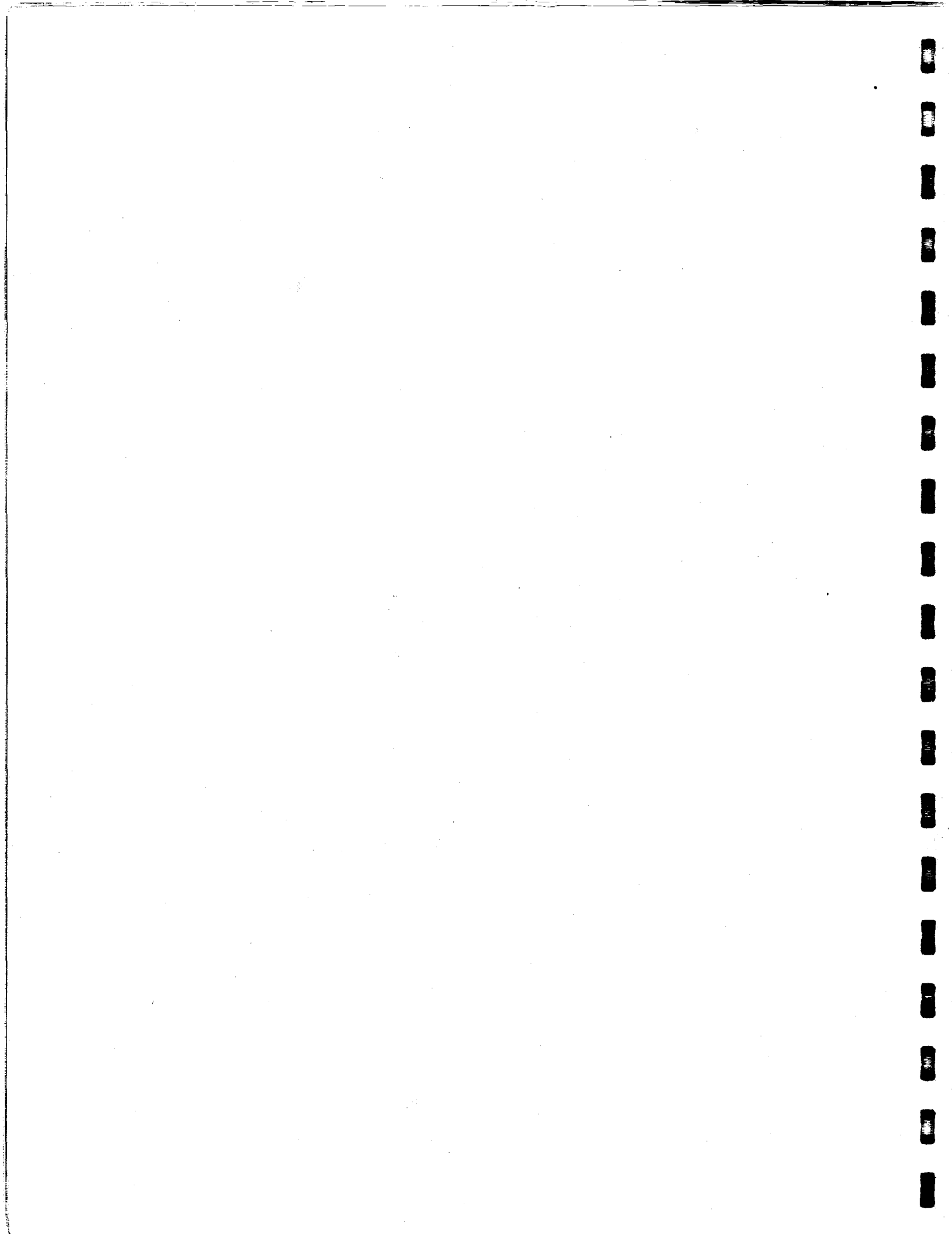
1-96. KEYING FUNCTION GENERATOR.

1-97. General. The Keying Function Generator (KFG) is used to simulate the call letters and characteristic codes of various types of navigational transmitters. The call letters of seven different transmitters can be stored in 8 core memory words. Each word is 16 bits long and four words are utilized for each transmitter, thus providing up to 64 bits per transmitter.

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1-98. Priority. The four binary words forming the call letters of each station selected by the Data Preselector are transferred from the drum to core memory. One bit at a time is retrieved from core memory, with a block of seven bits read out during the first seven machine cycles (approximately 42 usec always reserved for KFG priority) of every fourth drum revolution. During this period, one bit is taken from each of the seven stations in storage. The seven bits removed from core memory are shifted into a storage register where they remain for four drum revolutions (0.1 sec). A new set of seven bits is then shifted into the register. These are the next least significant bits (start with the MSB) of each of the seven core memory words being read. This process continues until all four core memory words are read for the seven stations in storage. Since there are 64 bits per station, a total of 6.4 sec is used to obtain all the call letter information stored.

1-99. Since every bit of call letter information represents 0.1 sec of the call letter, a dot is equal to a 1 (0.1 sec), a dash is equal to three 1's (0.3 sec), the space between dots and dashes within a letter is a 0 (0.1 sec), the space between letters within a call letter group is three 0's (0.3 sec), and the space between call groups (if they are repeated in one 64 bit segment) is at least five 0's (0.5 sec).



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SECTION II

LIST OF INSTRUCTIONS

2-1. **GENERAL.** This section contains the 26 machine instructions which the programmer may use in directing the Mark I in a step-by-step solution of an equation. These machine instructions are all that is written on the 11 general-program bands of the drum, and these instructions are read and performed in the order in which they are written. One instruction is read every machine cycle (6.1 microseconds). All instructions describe an operation which the Mark I is to perform, and they give the location of the data word or constant involved in the operation.

2-2. All instructions fall into three general categories: transfer, arithmetic, and control, and each instruction has an identifying code number which is recognized by the machine.

2-3. An instruction word is made up of two sections: a two octal-digit section which gives the operation (identifying code), and a four octal-digit section which specifies a core memory address. Figure 2-1 is an example of an instruction word to add the contents of memory location 1500 to the contents of the accumulator.

01	1500
----	------

 NOTE: (01 and 1500 are octal numbers)

Figure 2-1. Instruction Word

2-4. When the six octal-digit word (figure 2-1) is punched on the Tape Preparation Unit, it will be automatically converted into a 16-binary-bit word. The first five bits will be the binary code for the operation, and the following 11 bits will be the binary code for the core memory location. (The eleven general-program bands on the drum are all 16 bit wide.) The octal-digit word (figure 2-1) would be coded as shown in figure 2-2.

0	1	1	5	0	0
00	001	01	101	000	000

Figure 2-2. Binary Coded Octal-Digit Instruction Word

2-5. Each digit of the instruction is coded separately. This is the binary-coded octal format. Each octal digit of the instruction is separately converted to binary, and the binary equivalents are written in the same order as the octal numbers.

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The first octal digit of the operation section code and address section code never exceeds three and thus requires only two binary digits to simulate it. All of the other octal digits can take on values from 0 to 7 and each requires three binary digits.

2-6. INSTRUCTIONS.

2-7. The following paragraphs contain the complete list of Mark I instructions complete with the instruction code, explanation of the operation, the class in which the instruction falls (control, transfer, or arithmetic), and sample programming procedures for each instruction.

2-8. Load Accumulator.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Transfer	LD	20	<u>MMMM</u>	Transfer the contents of the accumulator to the salvage register. Clear the accumulator. Transfer the contents of core memory address MMMM to the accumulator.

NOTE

The contents of the salvage register may not be loaded in the accumulator. Address 0000 is not allowed.

EXAMPLE: X is in the accumulator and Y is in core memory location 1234 Load Y

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>	<u>Salv.</u>
LD	20	1234	X Y	X

2-9. Store Accumulator.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Transfer	ST	23	<u>MMMM</u>	Transfer the contents of the accumulator to core memory address MMMM. The contents of the accumulator will

MARK I

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
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remain in the accumulator
until the next load instruction.

NOTE

Address 0000 is not allowed.

EXAMPLE: Y is in the accumulator. Transfer the contents of the accumulator to core memory address 1000.

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>
ST	23	1000	Y Y

NOTE

Y is stored in core memory location 1000. Y will also remain in the accumulator until the next LOAD instruction when it will automatically transfer to SALV.

2-10. No-Operation.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Control	NPA	12	0000	Do not transfer information.
	NPB	25	3777	

NOTE

Indicates an unused instruction word location on the drum. "Time-killer" gives the Mark I time to perform such instructions as multiply, divide, and square root. Priority control is free to accept any auxiliary process. The two NO-OP instructions will be used alternately by the programmer. This instruction also functions as a parity check on the drum read heads. An example of a NO-OP instruction is shown in paragraph 2-13.

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2-11. Add.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	ADD	01	<u>XXXX</u>	Transfer the contents of address XXXX to the arithmetic unit and ADD to the contents of the accumulator. The automatic overflow process operates if required.

EXAMPLE: It is desired to form the equation $Z = X + Y$. Assume Y is stored in memory location 1235, X in memory location 1234, and Z in memory location 1236.

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>
LD	20	1234	X
ADD	01	1235	X + Y
ST	23	1236	X + Y

NOTE

X + Y is stored in core memory location 1236 (Z). X + Y will also remain in the accumulator until the next LOAD instruction when it will automatically transfer to SALV.

2-12. Subtract.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	SUB	02	<u>XXXX</u>	Transfer the contents of location XXXX to the arithmetic unit and subtract from the contents of the accumulator. Overflow process operates if required.

EXAMPLE: It is desired to form the equation $Z = X - Y$. Assume X is stored in memory location 1234, Y in memory location 1235, and Z in memory location 1236.

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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>
LD	20	1234	X
SUB	02	1235	X - Y
ST	23	1236	X - Y

NOTE

X - Y is stored in memory location 1236 (Z). X - Y will also remain in the accumulator until the next LOAD instruction when it will automatically transfer to SALV.

2-13. Multiply.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	MLT	03	<u>XXXX</u>	Transfer the contents of location XXXX to the arithmetic unit as multiplicand and multiply with contents of the accumulator as multiplier. The 48-bit product remains in the accumulator and Multiply (MQ) Register. (The 24 most significant bits (MSB's) are in the accumulator.)

NOTE

A multiplication requires an amount of time equal to five machine cycles (30.5 microseconds). Multiplication instructions must be followed by four NO-OP instructions. Boolean instructions may be substituted for the NO-OP instructions since they do not involve the use of the main arithmetic unit.

EXAMPLE: Form the equation $W = Z (X + Y)$. Assume X is in memory location 1234, Y in memory location 1235, Z in memory location 1236, and W in memory location 1237.

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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>
LD	20	1234	X
ADD	01	1235	X + Y
MLT	03	1236	X + Y
NPA	12	0000	X + Y
NPB	25	3777	X + Y
NPA	12	0000	X + Y
NPB	25	3777	Z (X + Y) = W
ST	23	1237	Z (X + Y) = W

2-14. Negative Multiplication.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	NMT	04	<u>XXXX</u>	Same as multiply except number transferred has sign inverted.

EXAMPLE: Form the equation $W = Z - XY$. Assume the same memory location for X, Y, Z and W as paragraph 2-13.

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>
LD	20	1234	X
NMT	04	1235	X
NPA	12	0000	X
NPB	25	3777	X
NPA	12	0000	X
NPB	25	3777	-XY
ADD	01	1236	Z - XY = W
ST	23	1237	Z - XY = W

2-15. Square.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	SQ	05	<u>0000</u>	Same as multiply except transfer contents of accumulator for use as multiplier and multiplicand.

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NOTE

0000 is the only allowed address.

EXAMPLE: Form the equation $Z = X^2 - Y$. Assume X, Y, and Z are in the same memory locations as in paragraph 2-13.

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>
LD	20	1234	X
SQ	05	0000	X
NPA	12	0000	X
NPB	25	3777	X
NPA	12	0000	X
NPB	25	3777	X ²
SUB	02	1235	X ² - Y = Z
ST	23	1236	X ² - Y = Z

2-16. Divide.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	DIV	06	<u>XXXX</u>	Transfer the contents of address XXXX to the main arithmetic unit as divisor and divide into the contents of the accumulator as dividend. Discard remainder of dividend from accumulator and transfer quotient to accumulator. Overflow process operates if required.

NOTE

A divided instruction must be followed by four NO-OP instructions. (Boolean instructions may be substituted for NO-OPS.)

EXAMPLE: Form the equation $W = \frac{XY - Y^2}{Z} + Z$. Assume W, X, Y, and Z are in the same memory location as in paragraph 2-13.

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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Arithmetic Accumulator</u>
LD	20	1234	X
SUB	02	1235	X - Y
MLT	03	1235	X - Y
NPA	12	0000	X - Y
NPB	25	3777	X - Y
NPA	12	0000	X - Y
NPB	25	3777	Y (X - Y)
DIV	06	1236	Y (X - Y)
NPA	12	0000	Y (X - Y)
NPB	25	3777	Y (X - Y)
NPA	12	0000	Y (X - Y)
NPB	25	3777	Y (X - Y)
			$\frac{Y (X - Y)}{Z}$
ADD	01	1236	$\frac{Y (X - Y)}{Z} + Z =$
			$\frac{XY - Y^2}{Z} + Z = W$
ST	23	1237	$\frac{XY - Y^2}{Z} + Z = W$

2-17. Square Root Step.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	SRS	07	MMMM	<p>Take the square root of the contents of the accumulator, by performing one iteration of the Newton-Raphson approximation where $X = \sqrt{Y}$;</p> $X_n = 1/2 \left(\frac{Y}{X_{n-1}} + X_{n-1} \right)$ <p>The previous result of this operation, X_{n-1}, is found in memory location <u>MMMM</u>. The result of this step, X_n, is to be stored in memory location <u>MMMM</u>.</p>

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NOTE

The square root of 0 is not allowed. A square root instruction must be followed by four NO-OP instructions (Boolean instructions may be substituted.)

EXAMPLE: Form $Z = X + Y + \sqrt{XY}$. Assume that X is stored in memory location 1233, Y is in 1234 and Z in 1235.

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Arithmetic Accumulator</u>	<u>Salv.</u>
LD	20	1233	X	
ADD	01	1234	X + Y	
LD	20	1233	X	X + Y
MLT	03	1234	X	X + Y
NPA	12	0000	X	X + Y
NPB	25	3777	X	X + Y
NPA	12	0000	X	X + Y
NPB	25	3777	XY	X + Y
SRS	07	1000	XY	X + Y
NPA	12	0000	XY	X + Y
NPB	25	3777	XY	X + Y
NPA	12	0000	XY	X + Y
NPB	25	3777	\sqrt{XY}	X + Y
ST	23	1000	\sqrt{XY}	X + Y
ADD	01	0000	$X + Y + \sqrt{XY}$	X + Y
ST	23	1235	Z	

2-18. Scale.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	SCL	10	1---	The address portion of this instruction contains a control code as follows: If the most significant bit (MSB) is 0, left shift. If the MSB is 1, right shift. The remaining portion of the address contains the number of places to be shifted, 001 through 101 (Binary). The MSB of the accumulator will remain unchanged to retain the sign bit.
	SCL	10	0---	

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<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
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The remainder of the accumulator contents will be shifted by the required number of bits, with insertion of zeros starting at the second most significant bit for scale right, and with the insertion of zeros starting at the least significant MQ bit for scale left. For scale left, the MSB of the accumulator (after the sign bit) will be examined before each 1-bit shift. If a "one" exists in this bit, OVERFLOW will occur replacing the scaling process, and ending execution of the instruction.

NOTE

Scaling a number left one place is equivalent to multiplying that number by two. Scaling right one place is equivalent to dividing by two. The Mark I can shift five places in one basic machine cycle (6.1 microseconds).

EXAMPLE: Form $Z = \frac{3X + 8Y}{2}$. Assume X is in memory location 1234, Y in 1235, and Z in 1236.

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Arithmetic Accumulator</u>	<u>Salv.</u>
LD	20	1234	X	
SCL	10	1001	$\frac{X}{2}$	
ADD	01	1234	$\frac{3X}{2}$	
LD	20	1235	Y	$3X$
SCL	10	0003	$8Y$	$\frac{3X}{2}$
ADD	01	0000	$\frac{3}{2}X + 8Y$	$\frac{3X}{2}$
ST	23	1236	Z	$\frac{3X}{2}$

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2-19. Shift.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	SFT	11	1---	Same as the "SCALE" instruction (paragraph 2-18) except that the entire contents of the accumulator, including the sign bit, will be shifted. Zeros are inserted at the LSB for left shifts, and at the MSB for right shifts. The control code is the same as for the scale instruction.
	SFT	11	0---	

2-20. Invert Sign.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	INS	13	<u>0000</u>	Reverse the sign (the most significant bit) of the accumulator.

NOTE

0000 is the only allowed address.

EXAMPLE: Form $Z = X - Y$. Assume that Y is already in the accumulator, X is in 1234 and Z is 1235.

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Arithmetic Accumulator</u>
SUB	02	1234	Y
INS	13	0000	Y - X
ST	23	1235	$-(Y - X) = X - Y$
			Z

2-21. Absolute Value.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	ABS	14	<u>0000</u>	Make the sign (MSB) of the accumulator positive (0).

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NOTE

0000 is the only allowed address.

EXAMPLE: Form $Z = /X - Y/$. Assume $X.2^{-8}$ is stored in memory location 1234 and $Y.2^{-6}$ is stored in 1235. It is desired to form and store $Z.2^{-7}$ in location 1236.

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Scale</u>	<u>Arithmetic Accumulator</u>
LD	20	1235	2-6	Y
SCL	10	1002	2-8	Y
SUB	02	1234	2-8	Y - X
ABS	14	0000	2-8	$/Y - X/$
SCL	10	0001	2-7	$/Y - X/$
ST	23	1235	2-7	Z

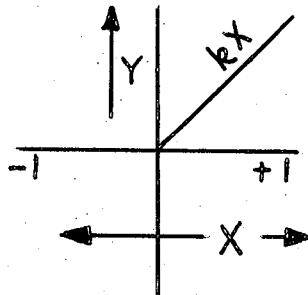
2-22. Zero Slice.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	ZSL	15	<u>0000</u>	If the sign of the number in the accumulator is negative, make the contents of the accumulator zero (including the sign bit). If the sign of the number is positive, do nothing.

NOTE

0000 is the only allowed address.

EXAMPLE: It is desired to form $Y = F(X)$ where $/X/ \leq 1$ and Y is described by the following curve.



$$Y = kX \text{ for } X > 0$$

$$Y = 0 \text{ for } X \leq 0$$

Assume X located in memory location 1234, k in 1235, and Y in 1236.

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<u>Mnemonic Code</u>	<u>O. P. Code</u>	<u>Mem. Add.</u>	<u>Arithmetic Accumulator</u>
LD	20	1234	X
MLT	03	1235	X
NPA	12	0000	X
NPB	25	3777	X
NPA	12	0000	X
NPB	25	3777	kX
ZSL	15	0000	
ST	23	1236	Y

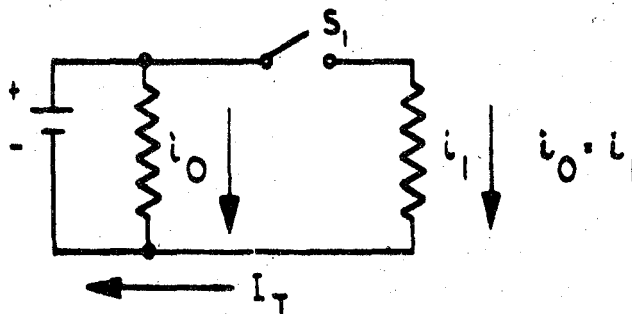
2-23. Conditional Skip.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O. P. Code</u>	<u>Address</u>	<u>Process</u>
Control	SKP	26	The octal equivalent of the number of steps to be skipped.	Skip the next N instructions only if the Boolean accumulator is 1. (Maximum number of skips in one instruction is 127.) The Mark I can skip to another skip instruction.

NOTE

This is the only form of branching in the Mark I.

EXAMPLE: I_T is the total load current on a power buss and the problem is to add i_1 , and additional load, to i_0 the minimum load, if switch S_1 is closed. If S_1 is closed $S_1 = 1$. If S_1 is open $S_1 = 0$. Assume S_1 is in the Boolean accumulator, i_0 is in core memory location 1234, and i_1 is in 1235. Calculate I_T and store in 1236.



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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Arithmetic Accumulator</u>	<u>Boolean Accumulator</u>
LD	20	1234	i_0	S_1
BIN	32	0000		S_1
SKP	26	0001		S_1
ADD	01	1235	$i_0 + i_1$	S_1
ST	23	1236	$I_T = i_0 + i_1$ or i_0	S_1

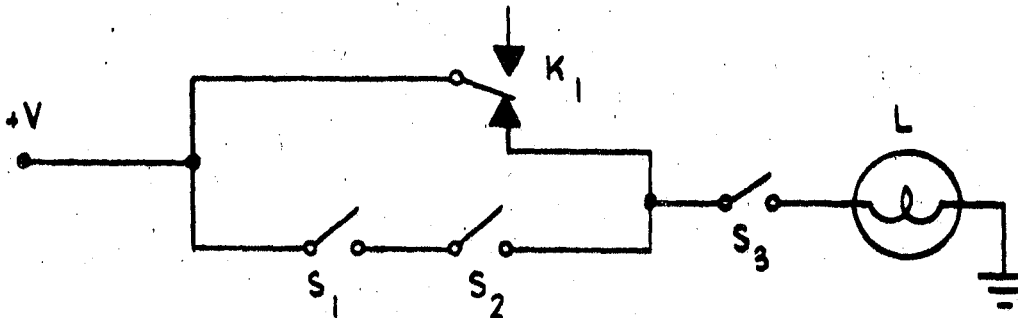
2-24. Invert Boolean Accumulator.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	BIN	32	<u>0000</u>	Complement the contents of the Boolean accumulator (i.e., a 1 is changed to a 0, and a 0 is changed to a 1).

NOTE

0000 is the only allowed address.

EXAMPLE:



$$L = S_3 (\bar{K}_1 + S_1 S_2)$$

$S_1, S_2, S_3, K_1,$ and L are in storage locations 0100 through 0104.

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Mnemonic Code	O.P. Code	Mem. Add.	Boolean Accumulator	Salvage			
				0000	0001	0002	0003
BLD	33	0103	K_1				
BIN	32	0000	\bar{K}_1				
BLD	33	0100	S_1	\bar{K}_1			
AND	31	0101	$S_1 S_2$				
OR	30	0000	$\bar{K}_1 + S_1 S_2$	\bar{K}_1			
AND	31	0102	$S_3 (K_1 + S_1 S_2)$				
BST	34	0104	L				

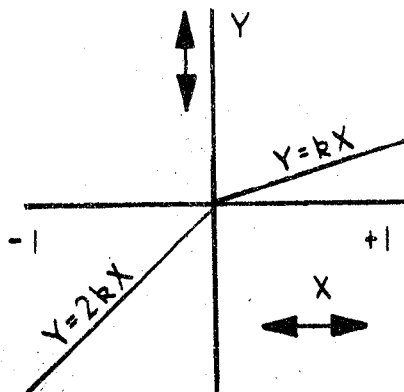
2-25. Flag Negative.

Class	Mnemonic Code	O.P. Code	Address	Process
Arithmetic	FLN	16	<u>0000</u>	Set the Boolean accumulator the same as the sign bit in the arithmetic accumulator. The previous contents of the Boolean accumulator are transferred to the salvage register B 0000.

NOTE

0000 is the only allowed address.

EXAMPLE: Generate $Y = kX$ where $0 \leq X \leq 1$, and $Y = 2kX$ where $-1 \leq X < 0$.



Assume X is in location 1234, and k is in 1235. Calculate and store Y in 1236.

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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Arithmetic Accumulator</u>
LD	20	1234	X
MLT	03	1235	X
NPA	12	0000	X
NPB	25	3777	X
NPA	12	0000	X
NPB	25	3777	kX
FLN	16	0000	kX
BIN	32	0000	kX
SKP	26	0001	kX
SCL	10	0001	2kX
ST	23	1236	Y

2-26. Index Load.

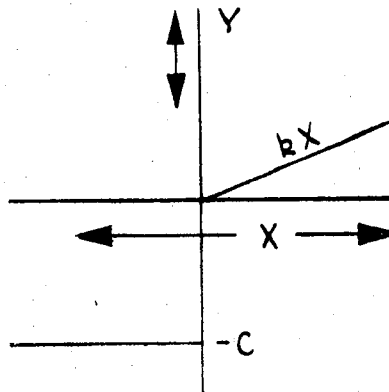
<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Transfer	ILD	21	<u>MMMM</u>	Same as LOAD instruction with the addition that the LSB of the eleven address bits is made to correspond to the contents of the Boolean accumulator.

NOTE

Address 0000 is not allowed. By use of this instruction, data from either of two locations may be loaded into the accumulator, depending on some external condition (as reflected in the state of the Boolean accumulator). The only pairs of adjacent core memory locations allowed consist of even numbered locations and the next higher number (e.g., 3776 and 3777; 0900 and 0901; etc.).

EXAMPLE: Generate $Y = f(X)$, where $f(X) = kX$ for $0 \leq X \leq 1$ and $f(X) = -C$ for $-1 \leq X < 0$. Assume X is in core memory location 1234, $-C/k$ is in 1235, k is in 1236 and Y in location 1237.

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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>
LD	20	1234	X
FLN	16	0000	X
ILD	21	1234	
MLT	03	1236	
NPA	12	0000	
NPB	25	3777	
NPA	12	0000	
NPB	25	3777	f(X)
ST	23	1237	f(X)

2-27. Index Store.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Transfer	IST	24	<u>MMMM</u>	Same as "STORE" instruction plus the same address modification of "ILD".

NOTE

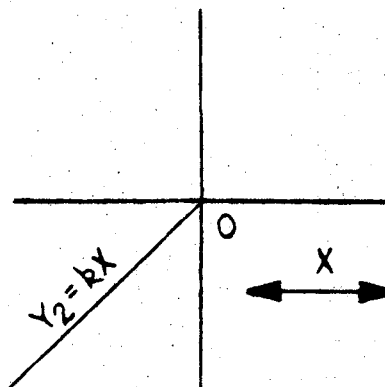
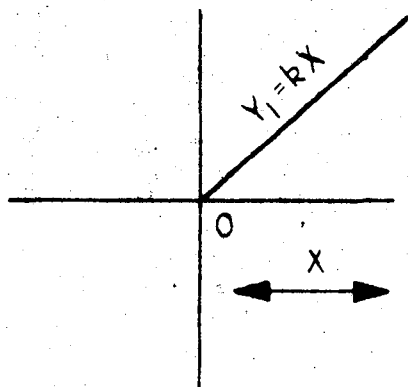
Address 0000 is not allowed.

EXAMPLE: $Y_1 = kX$ for $X \geq 0$ and $Y_1 = 0$ for $X < 0$

$Y_2 = kX$ for $X < 0$ and $Y_2 = 0$ for $X \geq 0$

Assume X is in location 1230, k in 1231, Y_1 in 1232 and Y_2 in 1233.

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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Accumulator</u>
LD	20	1230	X
FLN	16	0000	X
MLT	03	1231	
NPA	12	0000	
NPB	25	3777	
NPA	12	0000	
NPB	25	3777	kX
IST	24	1232	

2-28. No Address Load (Load Constant).

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Transfer	LDK	22		The address portion of this instruction word contains an 11-bit constant instead of an address. This constant is always assumed to be positive and is loaded into the accumulator. The remaining 12 LSB's of the accumulator are set to zero.

EXAMPLE: Calculate $Y = kX + C$:
 $X_{.2-5}$ is stored in 1234,
 $Y_{.2-10}$ is desired.
 $k_{.2-5} = .86875$
 $C_{.2-3} = .8500$

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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Scale</u>	<u>Accumulator</u>	<u>Salvage</u>
LDK	22	.8687	2-5	k	
MLT	03	1234			
NPA	12	0000			
NPB	25	3777			
NPA	12	0000			
NPB	25	3777	2-10	kX	
LDK	22	.8500	2-3	C	kX.2-10
SCL	10	1005	2-8	C	kX.2-10
SCL	10	1002	2-10	C	
ADD	01	0000	2-10	kX + C	
ST	23	1235	2-10	Y	

2-29. Conditional Stop.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Control	STP	27	<u>0000</u>	Stop the program. Hold clock counter at the last instruction address. Operates when the "conditional stop" switch on the Mark I is activated.

NOTE

0000 is the only allowed address. This instruction is programmed only in diagnostic routines. It may also be given during any program by use of a manual control on the Mark I. The program may be restarted at the following instruction by means of the conditional stop switch on the Mark I.

2-30. Load Boolean Accumulator.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Transfer	BLD	33	<u>BBBB</u>	Transfer the contents of the Boolean accumulator to Boolean salvage location <u>0000</u> . Clear the Boolean accumulator and transfer the contents of Boolean memory location <u>BBBB</u> to the Boolean accumulator.

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NOTES

1. Boolean addresses, 0000, 0001, 0002, and 0003 are allowed. (These are the addresses of the four Boolean salvage registers.)
2. The address portion of any Boolean instruction word, as written on the drum, is actually a control code which describes the Boolean memory location. This code tells which of the 128 main core memory words (that have been set aside for Boolean storage) is involved, and which of the 16-bits of the word concerned actually is the Boolean word desired. The four LSB's of the 11-bit control code (address portion of the instruction word) are transferred to the Boolean arithmetic unit to provide bit selection on the core memory output register. The first seven bits are transferred to the seven LSB places of the core memory address register and four zeros are inserted into the four most significant places of the register. This process constructs a core memory address from 0000 to 0127 as determined by the MSB's of the control code. The selected word is transferred to the core memory output register where the particular bit concerned is selected by the four LSB's of the control code previously transferred to the Boolean arithmetic accumulator.

2-31. Store Boolean Accumulator.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Transfer	B ST	34	<u>BBBB</u>	Store the contents of the Boolean accumulator in Boolean core memory location <u>BBBB</u> .

NOTE

Boolean addresses 0000-0003 are not allowed.

EXAMPLE: X, a quantity which varies from 0 to +1 is stored in 1234. Set a flag to determine whether X is greater or less than 0.5, and store the flag in Boolean core memory location 0100 for later use.

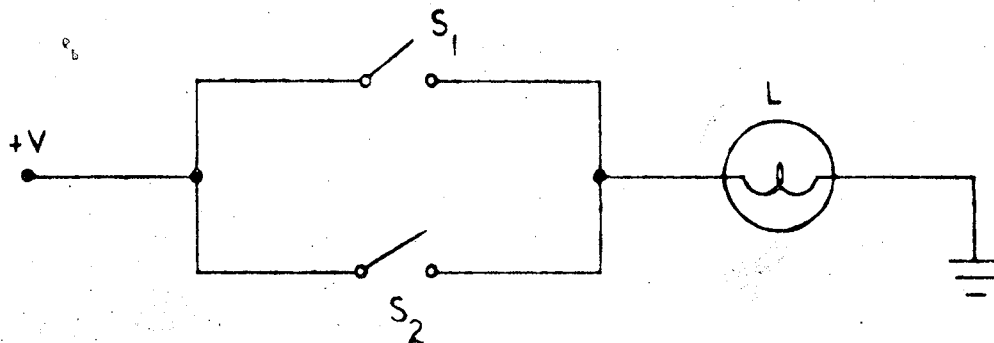
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<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Arithmetic Accumulator</u>	<u>Salvage</u>	<u>Boolean Accumulator</u>
LDK	22	4000	.5000		
LD	20	1234	X	.5000	
SUB	02	0000	X-.5000		
FLN	16	0000	X-.5000		X-.5000 flag
B ST	34	0100	X-.5000		X-.5000 flag

2-32. Boolean Sum.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	OR	30	<u>XXXX</u>	Transfer the addressed bit to the Boolean arithmetic unit and ADD (OR) with the contents of the Boolean accumulator. The sum (OR function) remains in the Boolean accumulator.

EXAMPLE:



The light, L, is on (1) if S₁ or S₂ are closed (1). ∴ L = S₁ + S₂
 Calculate L and store. S₁ is in Boolean location 1234, S₂ is in 1235 and L in 1236.

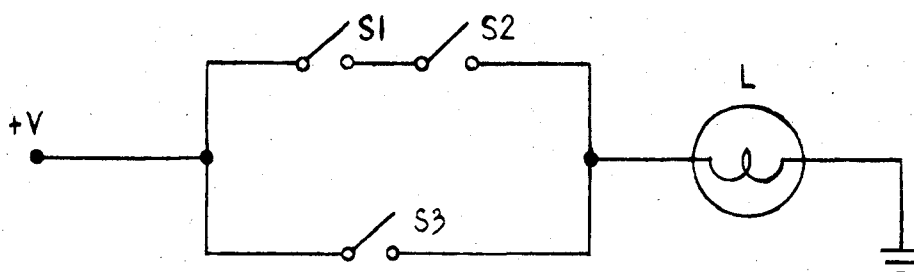
<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Boolean Accumulator</u>
BLD	33	1234	S ₁
OR	30	1235	S ₁ + S ₂
B ST	34	1236	L

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2-33. Boolean Product.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
Arithmetic	AND	31	<u>XXXX</u>	Transfer the addressed bit to the Boolean arithmetic unit and multiply (AND) with contents of Boolean accumulator. Products remain in the accumulator.

EXAMPLE:



$L = S_1 S_2 + S_3$ (The light is on (1) when we have either S_1 and S_2 or S_3 .)
 $S_1, S_2, S_3,$ and L are in Boolean locations 0100-0103

<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Mem. Add.</u>	<u>Boolean Accumulator</u>
BLD	33	0100	S_1
AND	31	0101	$S_1 S_2$
OR	30	0102	$S_1 S_2 + S_3$
BST	34	0103	L

2-34. Tape Stop Code.

<u>Class</u>	<u>Mnemonic Code</u>	<u>O.P. Code</u>	<u>Address</u>	<u>Process</u>
External	TRS	37	NONE	A stop code for the photo electric tape reader. Each second character on the tape will be interrogated for this code.

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SECTION III

PREPARATION OF PROGRAMS

3-1. GENERAL PROGRAM

3-2. Upon solution, a General Program problem is placed on a program sheet (Coding and Constant Sheet), punched on paper tape, and written onto the General Program section of the magnetic drum.

3-3. Coding and Constant Sheets. The coding and constant sheets are used by programmers for general purpose programs. These program sheets are broken up into 13 individual columns as follows:

- Column 1 - **INSTRUCTION NUMBER** - Used to count the number of instructions in a particular program. Decimal numbers are used in this column.
- Column 2 - **MNEMONIC CODE** - Abbreviation for the instruction being used (i.e., Multiply instruction would be listed in the Mnemonic Code Column as MLT).
- Column 3 - **O.P. CODE** - Instruction number (MLT Instruction is 03). Octal numbers only are used in this column.
- Column 4 - **MEM. ADD.** - Memory address of the instruction to be used. Octal numbers only are used in this column.
- Column 5 - **SCALE** - Scaling of the number in the Arithmetic accumulators. Scaling is to powers of two only.
- Column 6 - **ARITHMETIC ACCUMULATOR** - The number actually being operated on. This number is in binary format.
- Column 7 - **SALV.** - Salvage register column. Stores the contents of the accumulator after a load instruction.
- Column 8 - **BOOLEAN ACCUMULATOR** - Serves the same purpose as the arithmetic accumulator. Used for Boolean instructions only.
- Columns 9-12 - **SALV. 1 - SALV. 4** - Boolean salvage registers. Serves the same purpose as column 7. Bits may shift from one register to another.
- Column 13 - **REMARKS** - Used for brief explanation of instruction where necessary.

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3-4. The completed program on the Coding and Constants Sheets is punched on paper tape by an electrical keyboard. The keyboard, which resembles a conventional desk calculator, eliminates the need for punched card inputs to the tape preparation unit.

3-5. **Data Format.** All instructions will be written into the keyboard using six octal digits: Most Significant Code digit first, second code digit, then address, Most Significant Digit first.

3-6. No-Address Load Instructions (LDK), will require a keyboard entry of Octal "22" to activate a fractional decimal-to-octal translator. The four digit fractional decimal number will then follow, being entered through the keyboard.

3-7. Boolean Instructions will have the address portion tabulated 0000 to 3777 (Octal), which represents 128 16-bit words. All remaining instructions will be written as two-digit code and four-digit address or control word.

3-8. An example of a General Program Computer Word and binary equivalent is shown in figure 3-1 where d_n represents each octal digit, "0" stands for binary bits not recognized, and "X" represents valid binary bits.

d_1	d_2	d_3	d_4	d_5	d_6
OXX	XXX	OXX	XXX	XXX	XXX

Figure 3-1. General Program Computer Word

3-9. Each General Program Computer Word occupies two lines of punched paper tape, each line capable of holding eight binary digits. A punched hole in the tape signifies a one, and a blank, zero. Tape format for a General Program Computer Word is illustrated in figure 3-2, where "C" is the O.P. Code and "A" is the address.

C	C	C	C	C	.	A	A	A
A	A	A	A	A	.	A	A	A

Figure 3-2. Tape Format, General Program Computer Word

3-10. A sample General Program forming the equation $I = E/R$ is illustrated in figure 3 3. Part (A) is the formation of the equation on a "Coding and Constant" sheet, and Part (B) is the same program on paper tape.

DATE APRIL 23, 1963
 PROBLEM CURRENT (I) COMPUTATION
 PROGRAMMER JOHN DOE

CODING AND CONSTANT SHEET
 MARK I COMPUTER

PAGE 1 OF 1

F-2214-A

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE	MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
01	LD	20	1206		E							Load E into the Arithmetic Accumulator
02	DIV	06	2410		E							Divide the Contents of the Accumulator By R
03	NPA	12	0000		E							Instructions 03-06 Used to Give Computer Time To Complete Divide Instruction
04	NPB	25	3777		E							
05	NPA	12	0000		E							
06	NPB	25	3777		E/R							
07	ST	23	0777		I = E/R							Store the Contents of the Accumulator in the Memory Location of I.

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Figure 3-3. General Program Part A - (Coding and Constant Sheet)

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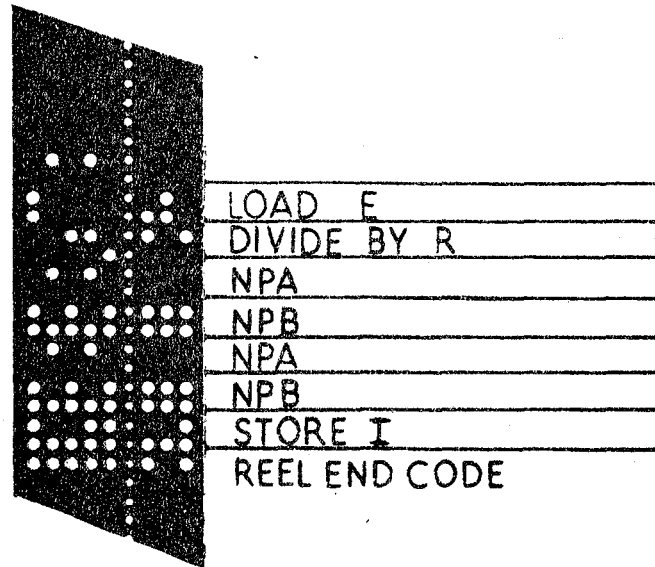


Figure 3-3. General Program Part B - (Punched Paper Tape)

3-11. INTERPOLATOR PROGRAM.

3-12. Solutions of flight equations are placed on "Linear Function Interpolator Data Input Sheets", punched sequentially on paper tape, and put into the interpolator bands of the magnetic drum.

3-13. Linear Function Interpolator Data Sheet. The Linear Function Interpolator Data Sheet is divided into two sections. The first section contains information concerning the number of variables, whether the variables are indexed scaling of variables, etc. The second section contains the location of the breakpoints. The first section is further broken-down into cards 1, 2, and 3. This is done for convenience where punched cards and a card reader is used in conjunction with the tape Preparation Unit.

3-14. A standardized procedure is required to fill out the LFI input sheets to maintain full usage and uniformity in all interpolator programs. The standard form of each item on the LFI input sheet is presented as follows:

CARD 1

Function Numbers - the function number space has twelve blocks assigned. The first three blocks will be used to show the numerical function number. The second three blocks are used for the first variable input number, the third set of three blocks for the second variable

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input number, and the last three blocks for the third variable input number. Function numbers are arbitrarily assigned by the programmer. These numbers may be written either decimally or octally on the input sheet. An example of a three variable function number follows:

f40 M⁽¹²⁾, $\alpha e^{(11)}$, $\alpha se^{(11)}$ would be written as
040002 009022 decimally or
050002 011026 octally where the input number for M⁽¹²⁾ is 2, $\alpha e^{(11)}$ is 9, and $\alpha se^{(11)}$ is 22. The function number used is 40.

The programmer should be consistent when writing the function number. If the decimal numbering system is used for the function number in the rest of the interpolation program, it should be used in any new programs. The same holds true for octal numbers.

Sort Number - This number is any convenient combination of alphabets and numerics which describes the order of this card. Two alphabets and three numerics will be used. (This is only used with punched cards and card reader.)

CARD 2

X Address (X ADD) - The address will contain the core address (in octal) of the independent variable X. If the term is to be indexed (the same set of curves and with different inputs), the X ADD will be the core address (in octal) of the first item to be indexed and must have a zero or a four as the last numeric in the octal number. The next three serial octal core locations must be the remaining indexed inputs. Core location 145 will appear as 0145.

Repeat X (RPX) - The number of times the X address will appear in the output data. If the X address is to appear five times, this will be written on the sheet as 05. As the present, five will always be used.

Index X (IXX) - If X is to be indexed, X will appear. If X is not to be indexed, the space will be left blank.

Y Address (Y ADD) - Similar to X address except this is for the second variable in a two or three variable function. For a single variable this will be left blank.

Repeat Y (RPY) - The number of times the Y address is to appear in the output data. Five is the only number used at this time, and it would appear on the input sheet as 05. These blocks are only used for a function of two or three variables.

MARK I

Index Y (IXY) - If Y is to be indexed, Y will appear. This will be filled out only if this is a function of two or three variables.

Z Address (Z ADD) - Similar to X ADD except for the third variable of a three variable function. For single or double variable functions this will be left blank.

Repeat Z (RPZ) - The number of times the Z address is to appear in the output data. Five is the only number used at this time and would appear on the input sheet as 05. This will be filled out only for a three variable function.

Index Z (IXZ) - If Z is to be indexed, Z will appear to be filled out only for a function of three variables.

Sort Number - Number used to signify the order of this card in the input data.

CARD 3

Answer Address (A ADD) - The answer address will contain the core address (in octal) where the answer (dependent variable) will be located. For functions which are being indexed, the answer address will be that of the first answer and the core location in octal must have a zero or a four in its last numeric. The next three core locations will be the indexed answers.

Repeat answer (RPA) - The number of times the answer is to appear in the output data. Five is the value of the number to be used and will appear on the input sheet as 05.

Computer time (CT) - The number of words consisting of all zeros that is to appear in the output data. 02, 04, or 06 will be used for a function of one, two, or three variables, respectively.

Decimal Point (DP) - The number of places the decimal point in the input data is to be shifted. The decimal point in the input data is always at the extreme left. 50 written in these blocks implies no shift, 51 implies a decimal point shift to the right of one place, 52 means a shift to the right of two places, 49 means a shift to the left of one place, 48 shift left two places, etc.

Scale (SC) - The proper power of two. -05 implies that the adjusted decimal number is to be divided by 32, +07 means the adjusted decimal number is to be divided by 0.0078125. As an example, if the largest decimal number for this function is 15.87, the scale factor is -04; or if the largest decimal number was 0.007753, the scale factor would be +07..

MARK I

Sort Number - Signifies the order of this card in the resultant card deck.

The lower half of the input sheet contains 81 blocks for the independent variables. Since a single variable has nine data words ($f_0, f_{1/8}, f_{1/4}, f_{3/8}, \dots, f_{1.0}$), a single page may contain all the data words for a two variable function ($9 \times 9 = 81$). A three variable function would have 729 data words ($9 \times 9 \times 9$) and require nine input sheets to show the whole program.

3-15. Information contained in this section is in decimal form. Prior to being punched on paper tape, it must be divided by the appropriate scale number and converted into octal numbers.

3-16. Data on the Linear Function Interpolator Data Input Sheets is punched sequentially on paper tape using an electric keyboard which is part of the Tape Preparation Unit.

3-17. Interpolator Words. Interpolator words written into the keyboard are divided up into instruction words and data words.

a. Interpolator instructions are written into the keyboard as follows:

(1) When a flag bit is written in the most significant bit position (bit 11), a separate manual key (F) shall be operated prior to writing the instruction.

(2) For a control instruction word, four octal digits shall be written: Zero; variable value 1-3; zero; variable value 0-7. Largest number possible would be 0307.

(3) For an address instruction word, four octal digits shall be written: most significant digit first, with values: 0001-1777. The binary equivalent of interpolator instruction words is shown in figure 3-4, where F is the flag bit, d_n are octal digits, 0 is a bit not recognized and X is a valid binary bit.

	d_1	d_2	d_3	d_4
F	00X	XXX	XXX	XXX
	1	7	7	7

Figure 3-4. Interpolator Instruction Word

b. Interpolator data words shall be written as follows:

(1) The flag bit shall be written in the identical manner as the interpolator instruction flag bit and shall appear with the first data word only.

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(2) The data words shall be written with four decimal digits, in fractional decimal form, the most significant digit first, with values: .0000 - .9999. These data words are internally translated to a ten-bit fractional binary equivalent, without roundoff. The binary/octal equivalent is illustrated in figure 3-5, where F is the flag bit, dn are octal digits, 0 is a bit not recognized and X is a valid bit.

	d1	d2	d3	d4
F	XXX	XXX	XXX	X00
	7	7	7	4

Figure 3-5. Interpolator Data Words

3-18. Interpolator Tape. An interpolator program is divided into several zones on paper tape. The least number of zones allowed is six for a single variable function, seven for two variable functions, and eight for three variables. These zones are as follows:

Zone 1 - Control Word - One word, the first bit of which is always one (flag bit) and the second bit always zero. The tape format for a control word is shown in figure 3-6.

D	D	D	D	F	.	0	0	X
X	0	0	0	X	.	X	X	0

Figure 3-6. Control Word Tape Format

D represents the dummy code which is always 0111 and is located at the beginning of every interpolator word. F is the flag bit which is always 1 in the control word, 0 is bits not recognized and X is valid bits. The binary/octal format of the control word is shown in figure 3-7, where octal word A is the flag bit, octal digit C is not used, and octal digits B and D are coded words. Octal digit B tells whether the function is of one, two or three variables, D tells which of the variables are indexed.

A	B	C	D
F0	XXX	000	XXX

Figure 3-7. Control Word Binary/Octal Format

Octal digit B is coded as shown in table 3-1.

Table 3-1. Control Word, Octal Digit B Code

<u>Number of Variables</u>	<u>Binary Equivalent</u>
1	001
2	010
3	011

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Octal digit D is coded as shown in table 3-2.

Table 3-2. Control Word, Octal Digit D Code

<u>Indexed Variables</u>	<u>Binary Equivalent</u>
None	000
X	001
Y	010
X, Y	011
Z	100
X, Z	101
Y, Z	110
X, Y, Z	111

Zone 2 - Consists of five identical words. It is the core memory location of the independent variable X. The first word in zone 2 always has a flag bit and all five words have the dummy code. The binary equivalent of zone 2 words is shown in figure 3-4.

Zone 3 - Identical to zone 2 except that it contains the address of the independent variable Y.

Zone 4 - Identical to zone 2 or zone 3 except that it contains the address of the independent variable Z.

Zone 5 - The data field consisting of the sequentially stored data words which describe the function at fixed breakpoints. The first word in this zone always contains a flag bit, and all words have a dummy code. The binary equivalent for the words contained in this zone is shown in figure 3-5.

Zone 6 - Blank words used to allow the computer time to finish the interpolation. The first word in the zone always contains a flag bit (F) and all words contain a dummy code (D). Tape format for a computer time word is illustrated in figure 3-8.

(D)	(F)	
⏟		
0	X	X X X . 000
0	0	0 0 0 . 000

Figure 3-8. Computer Time Word, Tape Format

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Zone 7 - Contains the core memory address where the result of the interpolation $f(X, Y, Z)$ is to be stored. The address is repeated four times. The first word always contains a flag bit and all four words have a dummy code. The binary equivalent of the answer word is illustrated in figure 3-4.

Zone 0 - The same as zone 7 except it is a single word always containing a flag bit and dummy code. Zone 0 is used to reset the counter, which tells the computer that the interpolator program has been completed.

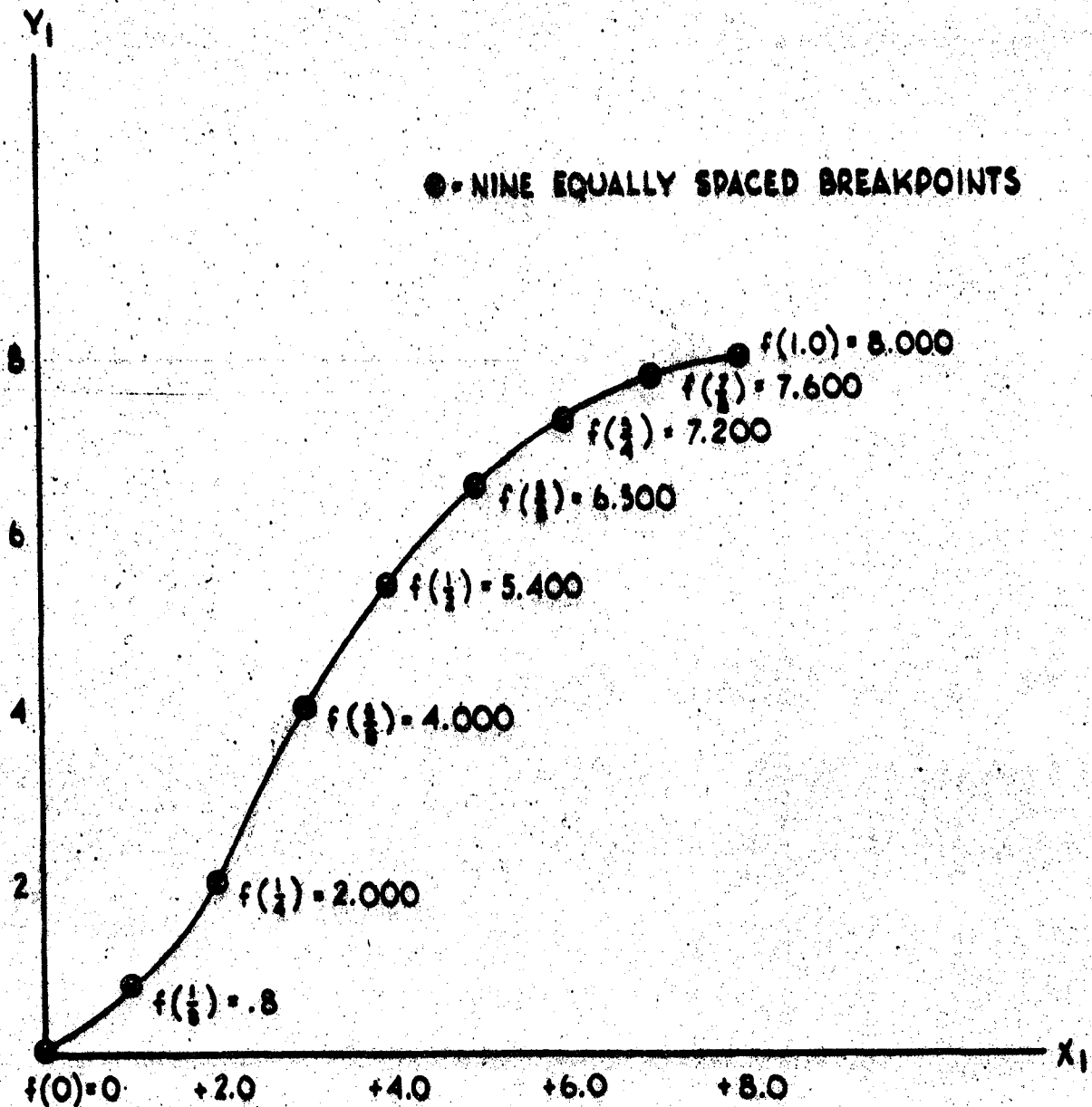


Figure 3-9. Interpolator Program Part A - Function Graph

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DATE 6-26-63	LINEAR FUNCTION INTERPOLATOR DATA INPUT SHEET	PAGE NO. 1
REV.--		REP. NO.

CARD ①	FUNCTION NUMBER 009002		SORT NO. AA001
---------------	-------------------------------	--	-----------------------

CARD ②	X ADD 1123	RPX 05	IXX <input type="checkbox"/>	Y ADD <input type="checkbox"/>	RPY <input type="checkbox"/>	SORT NO. <input type="checkbox"/>
	IXY <input type="checkbox"/>	Z ADD <input type="checkbox"/>	RPZ <input type="checkbox"/>	IXZ <input type="checkbox"/>		

CARD ③	A ADD 1576	RPA 05	CT 02	DP 51	SC -03	SORT NO. <input type="checkbox"/>
---------------	-------------------	---------------	--------------	--------------	---------------	-----------------------------------

CODE									
1	0	0000							
2	1.0	0800							
3	2.0	2000							
4	3.0	4000							
5	4.0	5400							
6	5.0	6500							
7	6.0	7200							
8	7.0	7600							
9	8.0	8000							

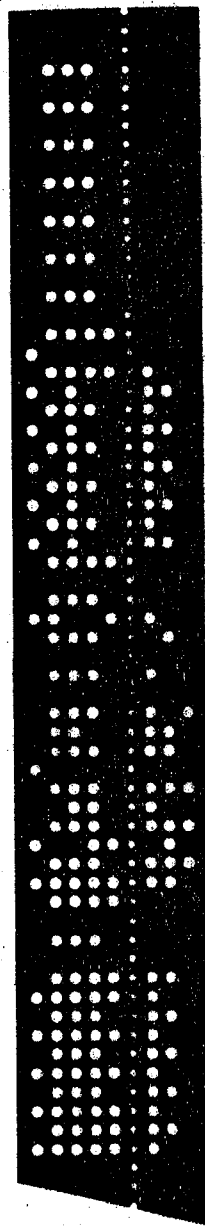
CARD NO.

REFERENCE:

NO.	CHANGE	NAME	DATE

Figure 3-9. Interpolator (Part B - Data Input Sheet)

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TAPE LEADER

7 DUMMY CODES

CONTROL WORD - ZONE 1

X ADDRESS - .1123
ZONE 2

DATA WORDS	←	$f(0) = .0000$
	←	$f(\frac{1}{8}) = .0630$
ZONE 5	←	$f(\frac{1}{4}) = .2000$
	←	$f(\frac{3}{8}) = .4000$
	←	$f(\frac{1}{2}) = .5314$
	←	$f(\frac{5}{8}) = .6400$
	←	$f(\frac{3}{4}) = .7150$
	←	$f(\frac{7}{8}) = .7774$
	←	$f(1.0) = .7774$

COMPUTER TIME - ZONE 6

ANSWER ADDRESS - 1576
ZONE 7

ANSWER ADDRESS - ZONE 0

Figure 3-9. Interpolator Program Part C - Punched Paper Tape

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3-19. A sample interpolator program involving a one variable functions is as follows: Figure 3-9 Part (A) illustrates a graph of a certain function; Part (B), the data which would be contained on the Linear Function Interpolator Data Input Sheet; Part (C) the corresponding program punched on paper tape.

3-20. RADIO AIDS PROGRAM.

3-21. Information pertaining to Radio Aids preselection is placed on a Radio Facility Data Sheet punched on paper tape and loaded onto the Radio Aids band of magnetic drum.

3-22. Radio Facility Data Sheet. The Radio Facility Data Sheet is divided into three sections, Card #1, Card #2 and Card #3. The breakdown of the sheet into card numbers is for convenience where punched cards and a card reader are used in conjunction with the tape preparation unit.

3-23. A standard procedure is required to fill out the Radio Facility Data Sheets to maintain full usage and uniformity in all Radio Aids programs. The procedure for completing the Radio Facility Data Sheet follows:

Card #1

ALL-TYPE-Six characters - fill in starting at extreme left. Any unused spaces will appear on the right. This will be filled in for all types of Radio Aids.

Example: ILS would appear as ILS

ALL-CALL LETTERS - Seven characters - fill in starting at extreme left. Any unused spaces will appear on the right. This will be filled in for all type Radio Aids. Two or three alphabetic will usually be written, but for FM, BONE, Z, and LFM, numerics will be written. A three will represent a dash and a one will represent a dot.

Example: a. ACY would appear as A C Y.
b. ... would appear as 13.13.

ALL-LATITUDE (Point of Touchdown) - Seven digits - one digit for sign, two digits for degrees, and four digits for fractional parts of a degree. N4.2256 degrees would appear as +04 2256. This will be filled in for all types of Radio Aids.

ALL-LONGITUDE (Point of Touchdown) - Eight digits - one digit for sign, three digits for degrees, and four digits for fractional parts of a degree. E74.8279 degrees would appear as +074 8279. This will be filled in for all types of Radio Aids.

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ALL-ELEVATION (Feet) - five digits, 518 feet would appear as 00518. This will be filled in for all types of Radio Aids.

LF, LFRR-POWER - four digits. 512/2048 would appear as 0512. 2048's considered max power equivalent to 480 NM range. Thus 512 = 120 NM or 1/4 MAX RGE. This is filled in for types 6 and 7. (See Appendix A.) The type is the most significant digit of the sort number.

ALL-FREQUENCY - (MC or KC) - four digits filled in for all types.

- a. 400 KC would appear as 0400, for types 6 and 7, but for types 4 and 5 the decimal point will be after the third significant digit. 117.5 would appear as 1175.
- b. A special code will be used for types 1, 2, and 3.
 - (1) Zero to full scale is 0700.
 - (2) One-half to full scale is 2700.
 - (3) Zero to one-half scale is 0300.

VHF, LFRR-COSINE MAG. VAR. (Cosine magnetic variation) - four decimal digits. Filled in for types 5 and 7.

ILS-RL-RTG +1000 (runway length minus distance from threshold to touch-down plus 1000 feet). This represents the distance between TD and Localizer in feet - 5 digits, 9971 would appear as 09971. Filled in for type 4 only.

ALL-COSINE LATITUDE - Cosine of the latitude in the input data; four digits with decimal point at extreme left. Filled in for all types.

ALL-SORT NUMBER - any convenient combination of alphabetic or numerics that describe the order of this card (where used). This number does not enter in the computation. Filled in for all types.

Example: 6 NY BGM 1. In this sample 6 represents the type facility, NY the state, BGM the call letters, and 1 the card number.

Card #2

MARKERS - SINE AXIS - sign and four decimal digits. Axis of facility is measured positive clockwise from north (negative measured counter-clockwise from north). If the angle is between 0 and +90°, sign of the sine is positive. If the angle is between 0 and -90°, the sign of the sine is

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negative. Decimal point of the sine is always assumed to be at the extreme left, +.0156 would appear on the form as +0156. Filled in for types 1, 2 and 3.

- b. COSINE AXIS - Sign and four decimal digits. Axis is measured positive clockwise from north. Sign of the cosine is always positive. The decimal point of the cosine is always assumed at the extreme left. +.0156 would appear as +0156. Filled in for types 1, 2 and 3.

VHF - a. MAG. VAR. (Magnetic Variation) - write in directly.

- b. SINE MAG. VAR. - five digits, one digit for sign, four digits for the decimal value of the sine of the magnetic variation. An east magnetic variation would have a plus sign, and a west magnetic variation would have a minus sign.

ILS - Cross out facilities not associated with the ILS installation.

- a. RNWY BRG (MAG) - Magnetic runway bearing in degrees with 360° magnetic north. Write in directly.
- b. MAG VAR - Magnetic variation. Write in directly.
- c. RNWY BRG (TRUE) - True runway bearing. Write in directly. (TRUE = MAG + M.V.) + for East, - for West.
- d. SINE BRG - Sine of the true runway bearing. One digit for the sign of the sine and four digits for the numerical value of the sine.
- e. COSINE BRG - Same as d. except cosine.
- f. G/S - Glide Slope Angle (degrees) - three digits. The decimal point is assumed to be after the first digit. 4.11 degrees would appear on the input sheet as 411. Filled in for type 4. Maximum angle 4.99 degrees, minimum 2.00 degrees.

LFRR - a. MAG. VAR. - Magnetic variation - same as previously explained.

- b. SINE AXIS - Five bits, one bit for sign and four bits for magnitude.

- c. COSINE AXIS - Five bits, one bit for sine and four bits for magnitude.

- d. LEG NO. - MAG. BRG and DIA

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- (1) LEG NO. - The four A-N course legs. The leg numbers are counted clockwise starting in the northerly quadrant.
- (2) MAG. BRG - Magnetic Bearing, write in directly.
- (3) DIA - Diameter of the circular radiation patterns. Consist of four decimal digits with the decimal point at the extreme left.

ALL - a. MISC - Miscellaneous - six bits to be used whenever necessary (i.e., simulating certain foreign facilities). If none used, leave blank.

b. SORT NO. - Same as Card #1.

Card #3

SIMULATOR NO. - any convenient seven character array that describes the simulator being worked on. This number does not enter into the computation.

BASE ADDRESS, J NUMBER - base address will be a four digit number and J will be a two digit number. The base address is the octal drum address of the start of the preselect data for this facility, and the J number is an octal number ranging from 00 to 37. A base address of 540 and a J number of 7 will appear on the sheet as 0540 07. Filled in for all types.

SORT NO. - Same as Card #1.

3-24. Processing Type Code 1 and 2 Inputs (1 = MM, 2 = OM). Each card of output for the radio aids will contain up to a maximum of seven character words. Each output card, in addition to the required numerical octal information, will contain the following:

- a. Call letters - max. seven alphabets or numerics.
- b. Type - max. six alphabets.
- c. Card number - two numerics.
- d. Octal address - four numerics.
- e. Simulator - max seven alphabets or numerics.

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This output data will be punched out from what appears in the input data. The remaining two words on the card will be occupied by octal information.

3-25. Preselect Data - The preselect data will be placed on punched cards as follows. There is one word punched on each card, therefore Card 1 = Word 1, etc.

Card 1. The first two octal words of the preselect data for outer marker or middle marker inputs will consist of the data listed below. Items a, b, c, d and e will be punched on the card. The remaining two words will be all zeros.

At least one space will separate the two octal words. Call letters, type, and simulator number will not vary from output card to output card for each station, but card number and addresses will. For this card, the card number will be 1 and the address (ADDRESS) will equal the base address in the input data.

Card 2. The second card to be punched will consist of the same data that was punched on the first card, except the address will be incremented by one (octal), and the card number will be 2. The two octal words will be 000077 330000 and 200077 330000 or 000037 330000, depending upon the values in the frequency input field. (See table 3-3.)

Table 3-3. Input Frequency versus Octal Output

<u>Input Card Frequency</u>	<u>Octal Output</u>
0700	000077 330000
2700	200077 330000
0300	000037 330000

Card 3. The third card to be punched will be similar to Card 2 except the address will be incremented by one and the card number will be 3. The two octal data words will consist of latitude lower and latitude upper, which will be formed as follows:

- a. The latitude lower and upper will be formed respectively by subtracting the size to lower latitude from the latitude, and by adding the size to upper latitude to the latitude. Table 3-4 gives the size to upper and lower latitude, longitude, and frequency.

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Table 3-4. Size to Upper and Lower Limits

<u>Type</u>	<u>Latitude (Degrees)</u>	<u>Longitude (Degrees)</u>	<u>Frequency (KC)</u>
OM, MM, Z, LFM	±0.1000	±0.1000	Not applicable
BONE, FM	±0.6667	±0.6667	Not applicable
ILS, ILSDME	±1.0	±1.0	Not applicable
MVRTAC, TACAN, UHF-DF, LVR HVR, MVR, HVRTAC	$\frac{\text{Power}}{258}$	$\frac{\text{Power}}{256}$	Not applicable
LOM, LMM, RBN, BC, LFRR	$\frac{\text{Power}}{256}$	$\frac{\text{Power}}{256}$	06

- b. The two octal words will be formed in the following manner. The lower latitude will be divided by 256 to produce a seven digit decimal number from 0000 to .9999999. This number will be multiplied successively by two, to produce a ten bit binary number which are the ten most significant bits of the resultant 20 bit number. After division by 256, the upper latitude will form the ten least significant bits. The resultant 20 bit binary word will be converted to two octal words as follows:

Octal Word 1

- a. 1st character - beginning of word definer
- b. 1st two significant bits - form octal digit 0 to 3
- c. next three bits - form octal digit 0 to 7
- d. next two bits - form octal digit 0 to 3
- e. next three bits - form octal digit 0 to 7
- f. next three bits - form octal digit 0 to 7
- g. next three bits - form octal digit 0 to 7

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Octal Word 2

- h. next two bits - form octal digit 0 to 3
- i. next two bits - form octal digit 0 to 3

Four zeros will make up the last four digits of the second octal word. This condition is true for the second octal word of all data.

Card 4. The same process that was used on Card 3 can be used to form Card 4 except the sizes will be divided by cos latitude before they are subtracted or added to longitude. The lower and upper longitude will be formed with a 20 bit number and converted to octal in the same manner employed with Card 3. Again, the base address will be incremented by one and the card number will be 4.

3-26. Data Words. There are four data words for the outer or middle markers.

- a. Data Word A - latitude - 19 bits, with a leading sign bit (0 = plus, 1 = minus)
- b. Data Word B - longitude - 19 bits, with a leading sign bit (0 = plus, 1 = minus)
- c. Data Word C - sine (10 bits) cosine (10 bits)
- d. Data Word D - ten leading zeros and elevation +1000 feet (10 bits)

3-27. Each word will be defined by two octal words, as was the preselect data. The call letters, type, card number, base address and simulator will also be punched on the card.

Card 5. The call letters, type and simulator will be punched the same way as in Cards 1, 2, 3, and 4. Two hundred will be added octally to the base address +J to form the octal address for this card, and the card number will be five. The two octal words representing latitude will be formed in the following manner: The latitude, which was stored when the input data was read in, will be divided by 256 and converted to a 21 bit pure binary number by successive multiplications by two. The first two most significant bits will be ignored, the most significant bit will be made a zero, and the 20 resultant bits will be converted to octal in the same manner as Card 3.

Card 6. The same as Card 5 except that longitude will be converted to two octal words after division by 256. The most significant bit will be made a

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one instead of a zero as in Card 5. The octal address will be formed by octally adding 40 to the octal address of Card 5, and the card number will be six.

Card 7. The card number is seven. The address is octal 40 plus the octal address of Card 6. The sine and cosine of the axis which is contained in the input data will be converted to binary and then to octal in the following manner: the sign of the sine will form the most significant bit. The remaining nine bits of the sine will be formed by multiplying by two, nine times. The cosine will be treated in the same manner to form the ten least significant bits of the 20 bit word. The 20 bits will be converted to two octal words forming data word C.

Card 8. The card number is eight, and the octal address will be octal 40 plus the octal address of Card 7. The 20 bit elevation word will be formed of the six miscellaneous bits and four zeros, dividing the elevation +1000 feet by 16,384, and multiplying by two ten times to produce the remaining ten bits. The 20 bits will be converted to two octal words forming data word D.

3-28. Processing Type Code 3 Inputs (Fan Z Marker). This program will be used to process FM, Z, BONE or LFM. The input data is the same as that used with type Codes 1 and 2.

3-29. Preselect Data. Formation of the preselect data will be exactly the same technique used for type Codes 1 and 2.

3-30. Data Words. Data words A, B, and C will be formed in the same manner as type Codes 1 and 2. In the case of data word D, instead of the first ten bits of the 20 bit word containing six miscellaneous bits and four zeros, the first four bits will be formed according to the type of facility as shown in table 3-5.

Table 3-5. First Four Bits of Data Word D (Type Code 3)

<u>Type</u>	<u>Binary Bits</u>
LFM	1000
BONE	0100
FM	0010
Z	0001

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3-31. The remaining six bits of the ten most significant bits of data word D will be "padded" with zeros. The ten least significant bits will contain elevation and will be formed in exactly the same manner as the ten bits representing elevation in Type Codes 1 and 2.

3-32. Call Letter Generation. Call letters must be generated in this program in addition to the preselect and data words. There are four 20 bit words of call letters, although only the 16 most significant bits of each word will be used. The remaining four bits will be miscellaneous bits and/or zeros.

3-33. When a Z marker facility is to be simulated, 16 ones would be used, making the first octal word for Cards, 9, 10, 11 and 12 equal to 373777.

Card 9. This card will contain the four most significant MISC bits. They will form binary bits 17, 18, 19 and 20. These are converted to be the first two octal bits of Card 9's second octal word. The remaining four octal bits will be zeros.

Card 10. This card will contain the two least significant MISC bits which will form binary bits 17 and 18. These bits are converted to the first octal bits of Card 10's second octal word. The remaining five octal bits are zeros.

Card 11 and Card 12 will have their second octal word equal to 000000.

3-34. If any of the other types of fan markers (FM, BONE or LFM), are to be simulated, the call letter words must be generated from the numerical information contained in the input data word representing the call letters. (A three will produce three ones followed by a zero. A one will produce one 1 followed by a zero.) The program will continue to follow this process and count the number of bits it has formed starting with the most significant digit. A one will be subtracted from the counter after the last numeric is processed.

3-35. When all the bits are formed, the computer will divide the count into 64 to determine the quotient and the remainder.

- a. If the quotient is less than or equal to the remainder, the remainder will be divided by the quotient, and the integer obtained will be the number of zeros placed between the call letters and after the last call letter. The call letters will be placed in the 64 bits the number of times specified by the quotient.
- b. If the quotient is greater than the remainder, the quotient will be reduced by one, and the count will be added to the remainder.

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- c. If the reduced quotient multiplied by five is less than or equal to the accumulated remainder, the remainder will be divided by the quotient. The integral result will be the number of zeros inserted between the call letters in the 16 bit words. Any uneven number of zeros left over will appear at the end of the last call letter.
- d. If the reduced quotient multiplied by five is greater than the remainder, repeat steps b and c.

3-36. The 64 bits will form 16 bits of four binary words. The four least significant bits (17, 18, 19 and 20) of the first word will be the four most significant MISC bits. The 17th and 18th bits of the second word will be the two least significant MISC bits. All remaining bits needed to form four 20 bit words will be zeros.

3-37. Processing Type Code 4 Inputs (ILS).

3-38. Preselect Data. The preselect data will consist of two octal words consisting of zeros on the first output card. The second output card will consist of frequency in the first ten bits. The first nine will be as shown in table 3-6. These same nine bits will be the 11 through 19 bits inclusive of the frequency word. Bits 10 and 20 are illustrated in table 3-7.

Table 3-6. Type Code 4 Frequency Bits 1 thru 9

<u>Frequency</u>	<u>Bits 1 thru 5</u>	<u>Frequency</u>	<u>Bits 6 thru 9</u>
108	10100	.0	1000
109	10101	.1	0100
110	11010	.2	1010
111	11011	.3	0101
112	11100	.4	0010
113	11101	.5	1001
114	01110	.6	1100
115	01111	.7	0110
116	00110	.8	0011
117	00111	.9	0001

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Table 3-6. Type Code 4 Frequency Bits 1 thru 9 (Cont)

<u>Frequency</u>	<u>Bits 1 thru 5</u>	<u>Frequency</u>	<u>Bits 6 thru 9</u>
133	10111		
134	01010		
135	01011		

Table 3-7. Type Code 4 Frequency Bits 10 and 20

<u>Type</u>	<u>Bit 10</u>	<u>Bit 20</u>
ILS	0	0
ILS DME	0	1

Cards 3 and 4 will consist of latitude and longitude lower and upper.

3-39. Data Words. Cards 5 and 6 will consist of latitude and longitude (20 bits each), formed in the same manner as previously described.

Card 7 will consist of true runway bearing sin and cos; one bit for sign and nine bits for the magnitude of both sine and cosine for a total of 20 bits. A zero in the sign position denotes positive sign and a one denotes negative sign.

Card 8 will consist of one and zero in the two most significant bits for ILS and two ones for ILS DME. The next six significant bits will be the MISC. bits from the input data. The 12 least significant bits (for a total of 20 bits) will be elevation. The elevation +1000 in the input data will be divided by 13,384 and converted to 12 bit binary.

3-40. Call Letters. Cards 9, 10, 11 and 12 will consist of the call letters. The call letters will be formed once from the alphabetic call letters in the input data and not repeated, as in the case with markers. The call letter bits will be formed starting with the first word and any unused bits will be "padded" with zeros. Spaces between letters will be represented by three zeros as shown in table 3-8. There will be a maximum of three call letters in the input data.

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Table 3-8. Call Letter Generation

<u>Call Letter</u>	<u>Binary Equivalent</u>	<u>Number of Bits</u>
A	10111000	8
B	111010101000	12
C	11101011101000	14
D	1110101000	10
E	1000	4
F	101011101000	12
G	111011101000	12
H	1010101000	10
I	101000	6
J	1011101110111000	16
K	111010111000	12
L	101110101000	12
M	1110111000	10
N	11101000	8
O	11101110111000	14
P	10111011101000	14
Q	1110111010111000	16
R	1011101000	10
S	10101000	8
T	111000	6
U	1010111000	10
V	101010111000	12

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Table 3-8. Call Letter Generation (Cont)

<u>Call Letter</u>	<u>Binary Equivalent</u>	<u>Number of Bits</u>
W	101110111000	12
X	11101010111000	14
Y	1110101110111000	16
Z	11101110101000	14

3-41. The four least significant bits of Cards 9, 10, 11 and 12 will consist of the binary representation of glide path angle, and runway length minus distance from threshold to touchdown. Two will be subtracted from the glide path angle in the input data and the result will be divided by three and converted to binary. The four most significant bits of glide path angle will be placed in the four least significant bits (17, 18, 19 and 20) of Card 9. The four least significant bits of glide path angle will be placed in the four least significant bits of Card 10.

3-42. The eight binary bits of runway length minus threshold to touchdown +1000 feet after division by 16,384 will be placed in the four least significant bits of the data word on Cards 11 and 12. The four most significant bits will be described by the second octal word of Card 11 and the four least significant bits will be described by the second octal word of Card 12.

3-43. Processing Type Code 6 Inputs (LF).

3-44. Preselect Data. The preselect data will consist of two octal words consisting of zeros on the first output card. The second card will consist of the lower frequency in the first ten most significant bits and upper frequency in the ten least significant bits. Frequency will be formed by subtracting the size (table 3-4) to lower frequency from the frequency in the input data, and adding the size to upper frequency, to the frequency in the input data. The two formed numbers will be divided by 2048 and converted to ten bit binary. Cards 3 and 4 latitude and longitude will be formed as previously described.

3-45. Data Words. Cards 5 and 6 will be 20 bit latitude and longitude respectively. Card 7 will be the frequency converted to binary after division by 2048. The 13 most significant bits will contain frequency (with a leading bit of zero), and the seven least significant bits will be padded with zeros. Card 8 will contain a leading bit of zero. The next nine significant bits will contain power (divided by 2048) and converted to nine bit binary. The last ten bits (Card 8) will contain elevation +1000, formed as previously described.

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3-46. Call Letters. The alphabetic call letters contained in the input data will be used to generate the 64 bits of call letters. The call letters will be generated according to table 3-8. Call letters will be generated as many times as possible for one letter calls, twice for two letter calls, with at least five zeros spacing between each word, and after the last call letter. Where three call letters are used, generate the call only once.

3-47. The process to be used is explained in paragraph 3-34 to 3-39. The four least significant bits in each of the third and fourth call letter words will be padded with zeros. The first and second call letter words will have the MISC. bits.

3-48. Processing Type Code 7 Inputs (LFRR).

3-49. Preselect Data. The preselect data words are formed in exactly the same manner as used in Type Code 6 (LF).

3-50. Data Words A, B, C, and D.

Data Word A - Card 5 - 20 bit latitude

Data Word B - Card 6 - 20 bit longitude

Data Word C - Card 7 - The most significant 13 bits (with a leading bit of zero), contain the frequency. The seven least significant bits are "padded" with zeros.

Data Word D - Card 8 - Most significant bit = 1, next nine bits = power divided by 2048, ten least significant bits = elevation + 1000 divided by 16,384.

3-51. Call Letters. Same as Type Code 4 process, paragraph 3-42 except the first 16 bits of the first call letter word will be zero. Remainder of bits will contain the call letters formulated once, with zero "padding" for the remaining bits.

3-52. Data Words E, F, G, and H. These data words are used only in the simulation of LFRR facilities. The storage locations of these words can be found by utilizing table 3-11.

3-53. Data Word E punched on card 13 will consist of the diameters of the first two circles (LEG NO. 1 and 2), in the input data (ten bits each). Data word F punched on card 14 consists of the diameters of the last two circles (LEG NO. 3 and 4), in the input data (ten bits each).

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3-54. Data words G and H, cards 15 and 16, will consist respectively of the sine and cosine of the axis, and the sine and cosine of the magnetic variation. The sine will be made up of one bit for sign and nine bits for magnitude. The cosine will always be positive and consist of a zero and nine magnitude bits. These conditions hold true for both axis and magnetic variation.

3-55. Processing Type Code 5 Inputs (UHF/VHF).

3-56. Preselect Data. The first preselect word will contain 20 bits of zeros. The second preselect word is frequency which is formed from table 3-6 except that the 10th and 20th bits are as shown in table 3-9.

Table 3-9. Type Code 5 Frequency Bits 10 and 20

<u>Type Facility</u>	<u>Tenth Bit</u>	<u>Twentieth Bit</u>
-VR	0	0
-VR - TC	0	1
-VRDME	0	1
-TC	1	1

3-57. The third and fourth preselect words will be two 20 bit words consisting of latitude and longitude lower and upper respectively.

3-58. Data Words.

Data Word A - Card 5 - latitude (20 bits)

Data Word B - Card 6 - longitude (20 bits)

Data Word C - Card 7 - Sine and cosine of magnetic variation. One sign bit (either 1 or 0) and nine magnitude bits each.

Data Word D - Card 8 - Type and elevation. The type is formed according to table 3-10.

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Table 3-10. Data Word D Type Code 5

Type	<u>ILS</u>	<u>DME</u>	<u>VOR</u>	<u>UHF-DF</u>	<u>TAC BRG</u>	
LVR	0	0	01	0	0	0
MVR	0	0	10	0	0	0
HVR	0	0	11	0	0	0
LVR DME	0	1	01	0	0	0
MVR DME	0	1	10	0	0	0
HVR DME	0	1	11	0	0	0
LVR LTC	0	1	01	0	0	1
LVR MTC	0	1	01	0	1	0
LVR HTC	0	1	01	0	1	1
MVR LTC	0	1	10	0	0	1
MVR MTC	0	1	10	0	1	0
MVR HTC	0	1	10	0	1	1
HVR LTC	0	1	11	0	0	1
HVR MTC	0	1	11	0	1	0
HVR HTC	0	1	11	0	1	1
LTC	0	1	00	0	0	1
MTC	0	1	00	0	1	0
HTC	0	1	00	0	1	1
UHF-DF	0	0	00	1	0	0

3-59. Upon completion of the Radio Facility Data Sheet, data preselector information regarding each radio station is manually precoded into eight or sixteen 20-bit binary data words. Each word is written on the keyboard as eight octal digits. An example of a data preselector word and binary equivalent is illustrated in figure 3-10, where dn is the octal data bits, 0 are bits not recognized and X are valid binary bits.

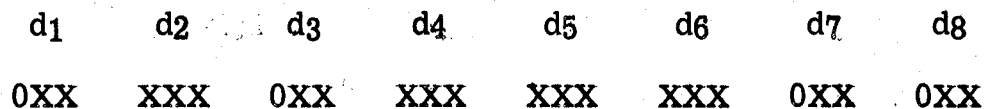


Figure 3-10. Data Preselector Word

3-60. Each data preselector word occupies three lines of punched paper tape and is preceded by a dummy code. Figure 3-11 illustrates the tape format for a data preselector word.

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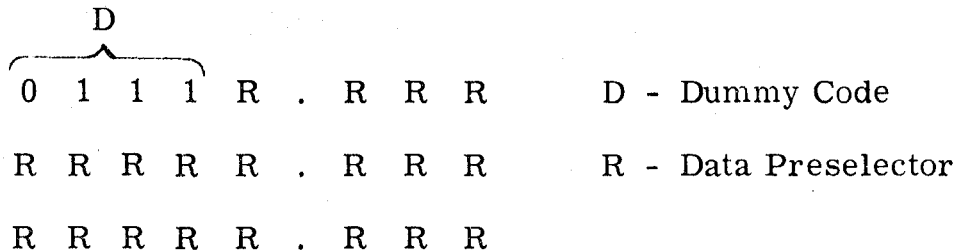


Figure 3-11. Tape Format, Data Preselector Word

3-61. A sample "Radio Facilities Data" sheet for a type 5 is illustrated in figure 3-12 Part (A). Figure 3-12 Part (B) is the information contained in figure 3-12 Part (A) as it would appear on paper tape.

3-62. Figure 3-13 shows the band location in octal of the various radio facilities simulated in the Mark I. (Marker call letters are used for reference only.) The symbol J in figure 3-13 and table 3-11 represents the serial number of the individual station within a group. The J numbers range from 0 to 37, thus the information for the twelfth station is obtained by assigning the numerical value 11 to the algebraic symbol J.

3-63. Table 3-11 is used in conjunction with figure 3-13 to find the location of any part of the facilities being simulated. For example: the sine and cosine axis for the middle marker station located at Kansas City, Mo. required a change. Referring to paragraph 3-26 it is found that the sign and cosine axis is assigned to data word "C" for Middle and Outer Markers. The formula for locating data word "C" is Base Address +J +100. The data word base address for middle markers is 0200 (figure 3-13) and the J number for Kansas City is 07. The sine and cosine axis can therefore be found at drum location 0307 octal or 0199 decimal.

3-64. Figure 3-14 illustrates the "layout" of the information on the data pre-selector band. All numerics in this figure are in octal form.

Table 3-11. Data Preselector Word Storage Locations

<u>Word</u>	<u>Card Number</u>	<u>Octal Address*</u>
1 (Preselector Word 1)	1	Base Address +4J
2 (Preselector Word 2)	2	Base Address +4J +1
3 (Preselector Word 3)	3	Base Address +4J +2
4 (Preselector Word 4)	4	Base Address +4J +3
5 (Data Word A)	5	Base Address +J

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Table 3-11. Data Preselector Word Storage Locations (Cont)

<u>Word</u>	<u>Card Number</u>	<u>Octal Address*</u>
6 (Data Word B)	6	Base Address +J +40
7 (Data Word C)	7	Base Address +J +100
8 (Data Word D)	8	Base Address +J +140
9 (First Call Letter Group)	9	Base Address +J +200
10 (Second Call Letter Group)	10	Base Address +J +240
11 (Third Call Letter Group)	11	Base Address +J +300
12 (Fourth Call Letter Group)	12	Base Address +J +340
13 (Data Word D)	13	Base Address +J +400
14 (Data Word F)	14	Base Address +J +440
15 (Data Word G)	15	Base Address +J +500
16 (Data Word H)	16	Base Address +J +540

*All arithmetic performed under this heading is octal arithmetic.

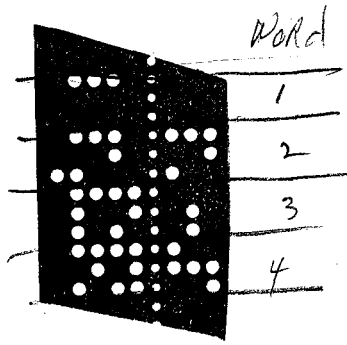
ID 5 - CF - GFS
TYPE STATE ID

TYPE		CARD #1	TYPE	CARD #2	CARD #3
ALL	TYPE	<u>M</u> <u>V</u> <u>R</u>	MARKERS	MINOR AXIS ANGLE SINE AXIS COSINE AXIS	ALL TYPES SIMULATOR NO.
ALL	CALL LETTERS	<u>G</u> <u>F</u> <u>S</u>	VHF	MAG. VAR. <u>+ 15.5</u> SINE MAG. VAR. <u>+ 2673</u>	
ALL	LATITUDE	<u>+</u> <u>35</u> <u>13</u> <u>11</u> <u>.35</u> <u>07</u> <u>52.1</u>	ILS	RNWX BRG (MAG) MAG VAR RNWX BRG (TRUE) SINE BRG COSINE BRG G/S	BASE ADDRESS
ALL	LONGITUDE	<u>-</u> <u>115</u> <u>17</u> <u>54</u> <u>115</u> <u>10</u> <u>32.2</u>	(OM) (MM) (LOM) (LMM)		
ALL	ELEVATION	<u>0</u> <u>3</u> <u>0</u> <u>0</u> <u>0</u> FT.	LFRR	MAG. VAR. SINE AXIS COSINE AXIS LEG NO. MAG. BRG SINE MAG. VAR.	SORT NO.
LF LFRR	POWER				<u>5</u> <u>CF</u> <u>GFS</u> <u>3</u>
ALL	FREQUENCY	<u>1</u> <u>1</u> <u>4</u> <u>4</u>			
VHF LFRR	COSINE MAG. VAR.	<u>9</u> <u>6</u> <u>3</u> <u>6</u>			
ILS	RL-RTG + 1000				
ALL	COSINE LATITUDE	<u>8</u> <u>1</u> <u>9</u> <u>2</u>	ALL	MISC.	
ALL	SORT NO.	<u>5</u> <u>CF</u> <u>GFS</u> <u>1</u>		SORT NO.	<u>5</u> <u>CF</u> <u>GFS</u> <u>2</u>

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Figure 3-12. Data Preselector Program Part A - Radio Facility Data Sheet

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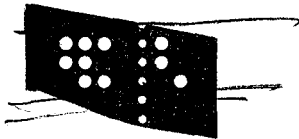
PRESELECT WORDS

WORD 1 - ZERO

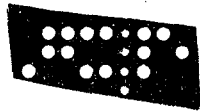
WORD 2 - FREQUENCY

WORD 3 - LATITUDE (U AND L)

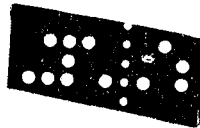
WORD 4 - LONGITUDE (U AND L)



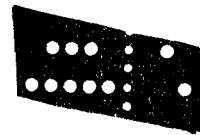
A - LATITUDE



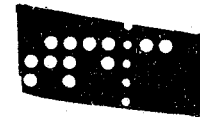
B - LONGITUDE



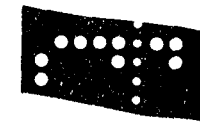
C - SIN AND COSINE (MAG. VAR.)



D - TYPE AND ELEV.



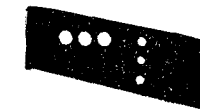
CALL LETTERS - 1



- 2



- 3



- 4

Figure 3-12. Data Preselector Program Part B - Punched Paper Tape

Preselector
Words Base
Address

J 4J
0 0
1 4
2 10
3 14
4 20
5 24
6 30
7 34
10 40
11 44
12 50
13 54
14 60
15 64
16 70
17 74
20 100
21 104
22 110
23 114
24 120
25 124
26 130
27 134
30 140
31 144
32 150
33 154
34 160
35 164
36 170
37 174

0000		0400		1000		1600		2400		3200		4000		4600		5400		6200		7000	
Type	Call Letters	Type	Call Letters	Type	Call Letters	Type	Call Letters	Type	Call Letters	Type	Call Letters	Type	Call Letters	Type	Call Letters	Type	Call Letters	Type	Call Letters	Type	Call Letters
				F	11.3			H	TBC	HV	PGS	MV	RBV					-H-	LAX		
				B	31	I	LAX	H	ONT	MV	LGB	LV	STW	LO	LA	LM	AX	-H-	DOW		
				B	13.1	I	SFO	L	SMO	LV	VTU	MV	SAX	LO	SF	LM	FO	MH	FRX		
						I	MFA	L	LHS	MV	FIM	MV	SBJ	LO	MF	LM	FA	MH	HWD		
						I	MIA	H	PMD	MV	GMN	HV	FMN	LO	MI	LM	IA	MH	SFG		
						I	ORD	L	SXC	HV	SBA	HV	IDL	LO	OR	LM	RD	-H-	MIA		
						I	IAC	M	PYE	HV	SAC	MV	RVH	LO	IA	LM	AC	MH	TMT		
						I	MKC	L	SFO	HV	SCK	MV	HUO	LO	MK	LM	KC	-H-	PRR		
						I	MCI	L	SJC	LV	SAU	MV	DAY	LO	MC	LM	CI	MH	NBU		
						I	STJ	M	GFS	HV	OAK	MV	CLE	LO	ST	LM	TJ	MH	PLV		
						I	EWR	L	DCA	HV	HEC	MV	TVE	LO	EW	LM	WR	MH	FRY		
						I	LGA	L	FLL	MV	DAG	MV	ABE	LO	LG	LM	GA	MH	LIY		
						I	IDL	M	BSY	HV	ALS	HV	PIT	MH	ID	LM	DL	MW	C		
						I	IWY	M	API	MV	PUB	HV	ERI	LO	IW	LM	WY	MH	SRI		
						I	DLX	L	DPA	HV	MIA	MV	PSB			LM	LX				
						I	DIA	M	BDF	MV	JOT	MV	LDN	LO	DI	LM	IA				
								H	HLC	HV	OBK	LV	CSN								
								M	ICT	MV	CGT	MV	HRN								
								L	FDK	LV	RFD	MV	MRB								
								L	EMI	MV	EON	LD	LAX								
								L	RIS	MV	MLI	MV*	APC								
								H	BLD	HV	DSM	LD	OSI								
								L	BLM	MV	TOP	LD	ORD								
								M	TRN	HV	GCK	LD	COL								
								L	LGA	MV	SLN										
								L	DPK	HV	BAL										
								M	ARD	HV	PMM										
								M	FRR	LV	STJ										
								H	OAF	HV	MKC										
								M	BSP	HV	STL										
										MV	PWE										
										MV	CYN										
	MM		OM		FAN/Z		VHF 1		VHF 2		VHF 3		VHF 4		LF 1		LF 2		LF 3		LF 4
	0200		0600		1200		2000		2600		3400		4200		5000		5600		6400		7200
MARKERS						VHF/UHF						LOW FREQUENCY									

Data Words
Base Address

NOTES:

TYPE CODE: B = BONE
F = FM
-H- = H
H = HVR
HV = HVORTAC
I = ILS

L = LVR
LD = LVORDME
LM = LMM
LO = LOM
LV = LVORTAC
M = MVR

MH = MH
MM = MM
MV = MVORTAC
MW = MHW
OM = OM

*USED AS MVORDME

MARK I

Figure 3-13. Radio Facilities Band Locations (Octal)

MARK I

DRUM WORDS	FIELD 1	FIELD 2	FIELD 3	FIELD 4				FIELD 5				
	MIDDLE MARKER 0000-0377	OUTER MARKER 0400-0777	FAN/Z MARKER 1000-1577	VHF GROUP 1 1600-2377	VHF GROUP 2 2400-3177	VHF GROUP 3 3200-3777	VHF GROUP 4 4000-4577	LF GROUP 1 4600-5377	LF GROUP 2 5400-6177	LF GROUP 3 6200-6777	LF/AN GROUP 4 7000-7777	
PRESELECTION CONTROL DATA (NOT TRANSFERABLE)	BLANK	0 -	400 -	1000 -	1600 -	2400 -	3200 -	4000 -	4600 -	5400 -	6200 -	7000 -
	(L IU)	1 STA 0	401 STA 0	1001 STA 0	1601 STA 0	2401 STA 0	3201 STA 0	4001 STA 0	4601 STA 0	5401 STA 0	6201 STA 0	7001 STA 0
	(X I Xu)	2 STA 0	402 STA 0									
	(Y I Yu)	3 STA 0	403 STA 0									
	BLANK	4 -	404 -	1004 -								7004 -
	(L IU)	5 STA 1	405 STA 1									
	(X I Xu)	6 STA 1	406 STA 1									
	(Y I Yu)	7 STA 1	407 STA 1									
	BLANK	10 -	410 -	1010 -								7010 -
	(L IU)	11 STA 2	411 STA 2									
	(X I Xu)	12 STA 2	412 STA 2									
	(Y I Yu)	13 STA 2	413 STA 2									
STATION PATTERN IDENTICAL FOR ALL FIELDS												
INFORMATION FOR TRANSFER TO CORE MEMORY	DATA A	200 STA 0 201 STA 1 202 STA 2	600 STA 0 601 STA 1 602 STA 2	1200 STA 0	2000 BLANK 2001 STA 1	2600 STA 0	3400 STA 0	4200 STA 0	5000 STA 0	5600 STA 0	6400 STA 0	7200 STA 0
	DATA A	237 STA 37	637 STA 37	1237 STA 37	2037 STA 37	2637 STA 37	3437 STA 37	4237 STA 37	5037 STA 37	5637 STA 37	6437 STA 37	7237 STA 37
	DATA B	240 STA 0 241 STA 1	640 STA 0 641 STA 1	1240 STA 0	2040 STA 0	2640 STA 0	3440 STA 0	4240 STA 0	5040 STA 0	5640 STA 0	6440 STA 0	7240 STA 0
	DATA B	277 STA 37	677 STA 37	1277 STA 37	2077 STA 37	2677 STA 37	3477 STA 37	4277 STA 37	5077 STA 37	5677 STA 37	6477 STA 37	7277 STA 37
	DATA C	300 STA 0	700 STA 0	1300 STA 0	2100 STA 0	2700 STA 0	3500 STA 0	4300 STA 0	5100 STA 0	5700 STA 0	6500 STA 0	7300 STA 0
	DATA C	337 STA 37	737 STA 37	1337 STA 37	2137 STA 37	2737 STA 37	3537 STA 37	4337 STA 37	5137 STA 37	5737 STA 37	6537 STA 37	7337 STA 37
	DATA D	340 STA 0	740 STA 0	1340 STA 0	2140 STA 0	2740 STA 0	3540 STA 0	4340 STA 0	5140 STA 0	5740 STA 0	6540 STA 0	7340 STA 0
	DATA D	377 STA 37	777 STA 37	1377 STA 37	2177 STA 37	2777 STA 37	3577 STA 37	4377 STA 37	5177 STA 37	5777 STA 37	6577 STA 37	7377 STA 37
	FIRST CALL LETTER GROUP			1400 STA 0	2200 STA 0	3000 STA 0	3600 STA 0	4400 STA 0	5200 STA 0	6000 BLANK	6800 STA 0	7400 STA 0
				1437 STA 37	2237 STA 37	3037 STA 37	3637 STA 37	4437 STA 37	5237 STA 37	6037 STA 37	6837 STA 37	7437 STA 37
	SECOND CALL LETTER GROUP			1440 STA 0	2240 STA 0	3040 STA 0	3640 STA 0	4440 STA 0	5240 STA 0	6040 STA 0	6840 STA 0	7440 STA 0
				1477 STA 37	2277 STA 37	3077 STA 37	3677 STA 37	4477 STA 37	5277 STA 37	6077 STA 37	6877 STA 37	7477 STA 37
	THIRD CALL LETTER GROUP			1500 STA 0	2300 STA 0	3100 STA 0	3700 STA 0	4500 STA 0	5300 STA 0	6100 STA 0	6900 STA 0	7500 STA 0
				1537 STA 37	2337 STA 37	3137 STA 37	3737 STA 37	4537 STA 37	5337 STA 37	6137 STA 37	6937 STA 37	7537 STA 37
	FOURTH CALL LETTER GROUP			1540 STA 0	2340 STA 0	3140 STA 0	3740 STA 0	4540 STA 0	5340 STA 0	6140 STA 0	6940 STA 0	7540 STA 0
				1577 STA 37	2377 STA 37	3177 STA 37	3777 STA 37	4577 STA 37	5377 STA 37	6177 STA 37	6977 STA 37	7577 STA 37
	DATA E											7600 STA 0
												7637 STA 37
												7640 STA 0
	DATA F											7677 STA 37
												7700 STA 0
	DATA G											7737 STA 37
												7740 STA 0
	DATA H											7777 STA 37

NOTES:

1. All marker stations operate on 75 MCS. - Preselection by X/Y only.
2. X/Y position required for preselection during interval 2-7177. Core memory access 7200 0000.
3. VHF receiver frequency required for preselection during interval 1601-4175. Core memory access 0001 1600.
4. LF receiver frequency required for preselection during interval 4577-7170. Core memory access 4200 4500.
5. Preselection patterns:

Drum Rev #1	#2	#3	#4
Middle Mk.	Middle Mk.	Middle Mk.	Middle Mk.
Outer Mk.	Outer Mk.	Outer Mk.	Outer Mk.
Fan/Z Mk.	Fan/Z Mk.	Fan/Z Mk.	Fan/Z Mk.
VHF Rcvr. #1	VHF Rcvr. #2	VHF Rcvr. #3	VHF Rcvr. #4
LF Rcvr. #1	LF Rcvr. #2	LF Rcvr. #1	LF Rcvr. #2
6. Two stations are deleted due to blanking requirements during drum loading. These blank words have all bits equal to zero and are non-recoverable words. The stations deleted are:
 - a. Field 4, VHF Group 1, Station #1
 - b. Field 5, LF Group 2, Station #1
7. Number of stations available for preselection:
 - 32 Middle Marker
 - 32 Outer Marker
 - 32 Fan/Z Marker
 - 127 VHF
 - 98 LF
 - 32 LF/AN
 - 350 Total

Figure 3-14. Data Preselector Band

MARK I

3-65. MULTIPLEXER PROGRAM.

3-66. The 100 input lines of the A/D converter are programmed sequentially on the four slow bands (approximately 25 inputs to a band). This input information (analog voltages) is transferred sequentially from the Multiplexer to the Multi-verter, (where they are converted to digital), and further transferred to a main core memory location and on to another core location depending upon the relay positions in the Redcor Multiplexer. (See figure 3-15.)

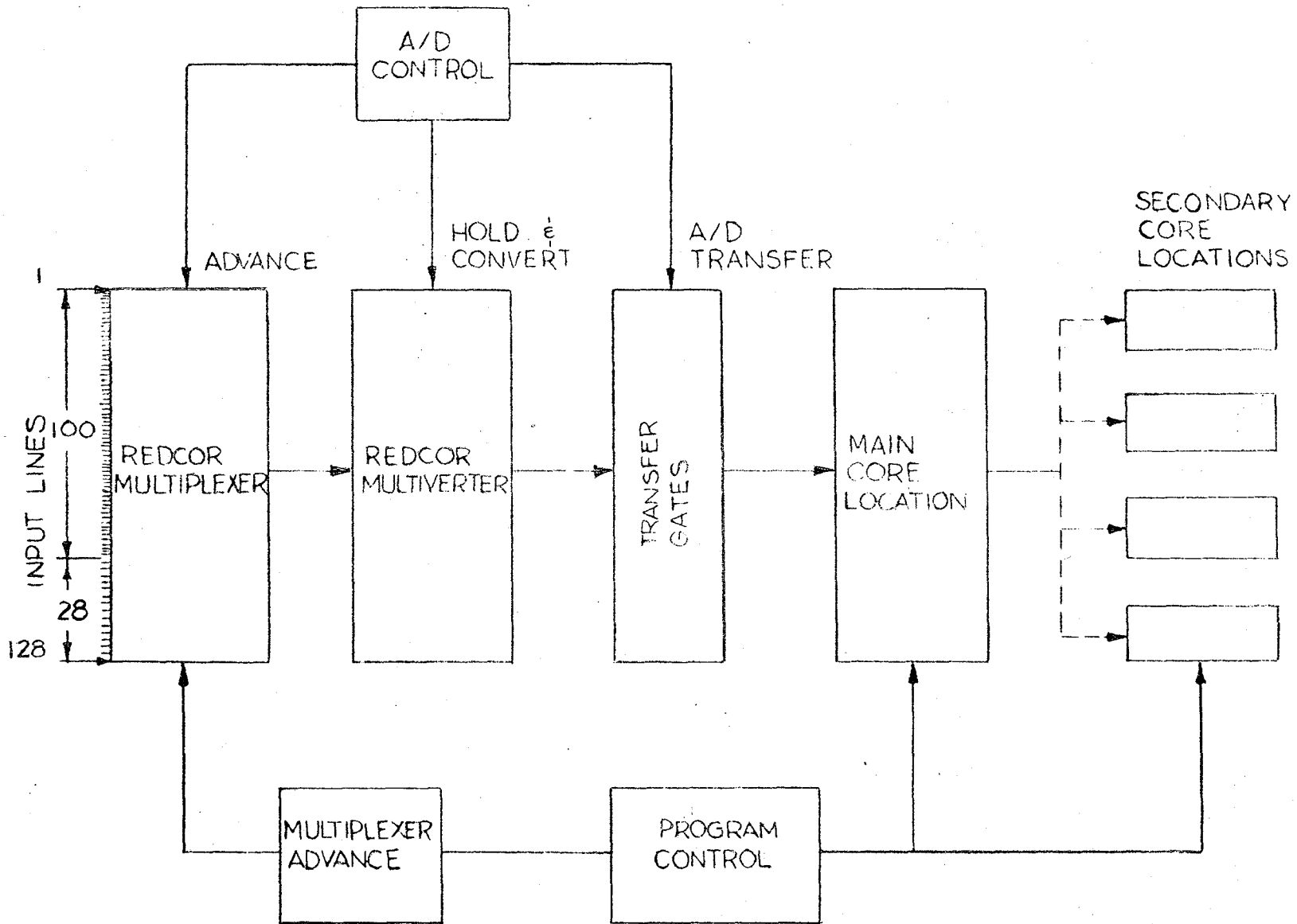
3-67. A Boolean program used in conjunction with the last multiplexed program on slow band four is used to simulate resetting the switch positions to 0. Figure 3-16 is a sample multiplexer program for slow band 4.

3-68. The three other multiplexer programs (slow bands 1, 2, and 3) are ended with a small Boolean program consisting of BLD, BIN, and BST into the same core location as the BLD instruction. This is done to change switch position (A to \bar{A} , B to \bar{B} etc.).

3-69. BOOLEAN EQUATIONS.

3-70. General: There are five basic steps which should be taken into consideration by the programmer prior to programming a Boolean equation. These steps will help the programmer to visualize the system more clearly and eliminate possible extra program steps. The five basic steps are as follows:

- a. Develop a complete "picture" of the system.
 - (1) Block diagram or signal flow type.
 - (2) Show all indicators, lights, etc.
 - (3) Show all actuators, circuit breakers, etc.
 - (4) Determine the extent of simulation.
- b. Redraw the system "picture" including the results of step 4 of a.
- c. Determine any breakdown of the system.
 - (1) Any indicator, such as a light, must be a Boolean output. Any breakdown should be in these terms.
 - (2) Any term that is used many times should be stored in memory.



MARK I

Figure 3-15. Block Diagram, Multiplexer Flow of Information

DATE 5/9/63

CODING AND CONSTANT SHEET

PROBLEM MULTIPLEXER PROGRAM - SLOW BAND 8 QUADRANT 1

MARK I COMPUTER

PROGRAMMER JOHN DOE

F-2214-A

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE		MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
		9 10	12 13 14 15										
0 1	LD	2 0	0 2 7 0										Steps 1 Thru 32 Used To Load Contents Of Main Core Memory Location And Store Those Contents Into A Certain Other Core Location Dependent Upon The Relay Position In The Packard-Bell Multiplexer.
0 2	ST	2 3	2 7 0 0										
0 3	LD	2 0	0 2 7 1										
0 4	ST	2 3	2 7 0 4										
0 5	LD	2 0	0 2 7 2										
0 6	ST	2 3	2 7 1 0										
0 7	LD	2 0	0 2 7 3										
0 8	ST	2 3	2 7 1 4										
0 9	LD	2 0	0 2 7 4										
1 0	ST	2 3	2 7 2 0										
1 1	LD	2 0	0 2 7 5										
1 2	ST	2 3	2 7 2 4										
1 3	LD	2 0	0 2 7 6										
1 4	ST	2 3	2 7 3 0										
1 5	LD	2 0	0 2 7 7										
1 6	ST	2 3	2 7 3 4										
1 7	LD	2 0	0 3 0 0										
1 8	ST	2 3	2 7 4 0										
1 9	LD	2 0	0 3 0 1										
2 0	ST	2 3	2 7 4 4										
2 1	LD	2 0	0 3 0 2										
2 2	ST	2 3	2 7 5 0										
2 3	LD	2 0	0 3 0 3										
2 4	ST	2 3	2 7 5 4										
2 5	LD	2 0	0 3 0 4										
2 6	ST	2 3	2 7 6 0										
2 7	LD	2 0	0 3 0 5										
2 8	ST	2 3	2 7 6 4										
2 9	LD	2 0	0 3 0 6										
3 0	ST	2 3	2 7 7 0										

MARK I

Figure 3-16. Multiplexer Program (Sheet 1 of 2)

DATE 5/9/63

PROBLEM MULTIPLEXER PROGRAM - SLOW BAND 8 QUADRANT 1

PROGRAMMER JOHN DOE

CODING AND CONSTANT SHEET

MARK I COMPUTER

PAGE 2 OF 2

F-2214-A

INSTRUCTION NUMBER							MNEMONIC CODE	O.P. CODE		MEM. ADD.			SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS		
1	2	3	4	5	6	7		9	10	12	13	14										15	
					3	1	LD	2	0	0	3	0	7										
					3	2	ST	2	3	2	7	7	4										
					3	3	BLD	3	3	2	4	0	5		A or B								
					3	4	BIN	3	2	0	0	0	0		\bar{A} or \bar{B}								
					3	5	BLD	3	3	2	4	0	5		A or B								
					3	6	AND	3	1	0	0	0	0		(A or B) (\bar{A} or \bar{B})					Ensure 0			
					3	7	BST	3	4	2	4	0	5		0						Store Zero In Location A or B		
					3	8	BST	3	4	2	4	0	6		0							Store Zero In Location A or B	

MARK I

Figure 3-16. Multiplexer Program (Sheet 2 of 2)

MARK I

d. Write the Boolean expressions for each section of the system breakdown.

- (1) Use combinations that are common to several sections of the system and can be reclaimed from the temporary Boolean register.

e. Write the programming instructions.

3-71. In order that the "pictures" of the system transfer the maximum information, a standard method of representation should be used. A variation of the signal flow graph is most easily understood.

3-72. A function is defined by the lines directed into the circle with that label. These lines come from other labeled functions or circles labeled with Boolean functions such as "AND" or "OR". (See figure 3-17.)

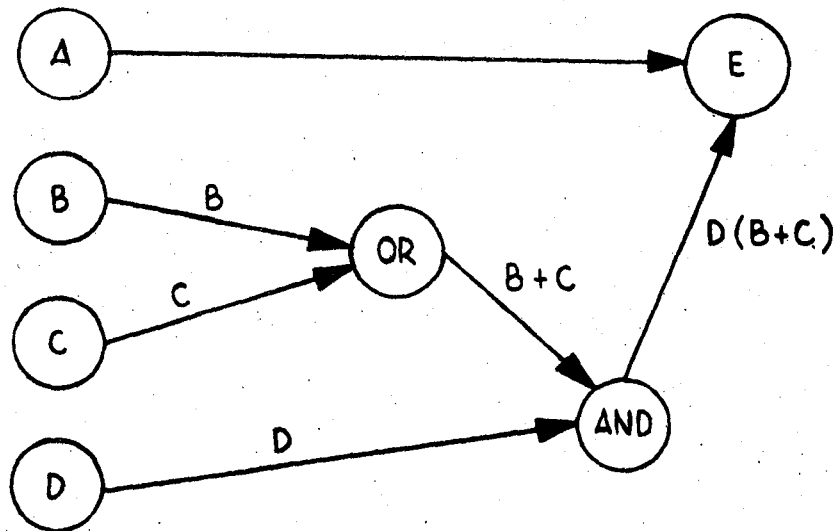


Figure 3-17. Flow Chart

3-73. The function E is defined by the two lines directed into it. One of these is the function A, the other is the indicated function of B, C, and D. The equation for E would be $E = A + D(B + C)$ in Boolean designation.

3-74. The circles can be labeled with the names of switches, lights, circuit breakers, relays, and other elements of the aircraft's system. Using this method the systems as shown in the aircraft manufacturer's manuals can be transcribed to a function diagram. Flow charts are simplified until only the inputs, outputs, and variables which are to be stored remain as labeled circles.

3-75. The Boolean expressions for the function represented by a labeled circle can be written directly from the flow chart. The function of any labeled circle is the sum of the directed lines entering the circle. Any directed line leaving an "OR" circle is the sum of the directed lines entering the circle. Any directed

MARK I

line leaving an "AND" circle is the product of the directed lines entering the circle. Utilization of these ideas result in the Boolean function for all outputs and elements to be stored.

3-76. An illustration of this method is shown in figures 3-18 and 3-19. Figures 3-18 is a typical aircraft power circuit. All details except those necessary to determine when the three buses are energized have been omitted. Figure 3-19 represents the transition from figure 3-18 to determine the equations for energization of the three buses. The circles A and B on figures 3-19 represent Gen I operating and Gen I circuit breaker "made". To the right of Gen I C.B. on figure 3-18 there is a junction corresponding to the "AND" circle (figure 3-19) which the arrows from A and B enter. This junction is defined by AB and each arrow leaving the circle is so designated. In the circuit, power from this junction goes through GEN I RY to a second junction. This junction is represented on figure 3-19 by the "AND" circle which the arrows A, B, and C enter. C is the circle for GEN I RY. Power from this junction feeds LOAD BUS #1, but this bus can also be fed through the GEN I BUS TIE. Therefore, the arrow ABC must enter an "OR" circle which then goes to E (LOAD BUS #1). The first junction also supplies power to the ESS PWR BUS through the GEN I ESS PWR relay. This is shown by the arrow AB going to the upper right hand "AND" circle in conjunction with the D arrow. This "AND" circle goes to G through an "OR" circle indicating two power sources for the ESS PWR BUS "G". The rest of the circuit of figure 3-18 is described on figure 3-19 in a similar manner.

3-77. The Boolean equations for G, E, and K can be determined from the arrows entering the "OR" circles which define G, E, and K.

$$G = ABD + LMN$$

$$E = ABC + FHJLM$$

$$K = JLM + FHABC$$

3-78. When the Boolean equations have been developed, a program can be written. This program is in terms of storage, input, and output locations in the Mark I. On a system design sheet such as figure 3-19, a tabulation of the letter designations used on that sheet, their corresponding aircraft functions and Mark I storage locations should be included. This tabulation provides the correlation between the Mark I locations and the simulated aircraft variables. This tabulation would appear as follows:

MARK I

GEN I OPER	-A-	B2347
GEN I C.B.	-B-	B1433
GEN I RY	-C-	B2131
GEN I ESS PWR RY	-D-	B2134
LOAD BUS 1	-E-	B3214
GEN I BUS TIE RY	-F-	B2133
ESS PWR BUS	-G-	B3217
GEN II BUS TIE RY	-H-	B2132
GEN II RY	-J-	B2135
LOAD BUS 2	-K-	B3215
GEN II C.B.	-L-	B1435
GEN II OPER	-M-	B2354
GEN II ESS PWR RY	-N-	B2136

3-79. A preliminary program sheet can be filled out to ensure the programmer that all phases of the problem are included in the program. This step further eliminates the possibility of errors, or insufficient information to solve a problem being programmed into Mark I. A program sheet of this type developed for figure 3-19 follows:

	<u>ACCUM.</u>	<u>SALVAGE REGISTER</u>			
BLD - A	A				
AND - B	AB				
BLD - D	D	AB			
AND - 0000	ABD	AB			
BLD - L	L	ABD	AB		
AND - M	LM	ABD	AB		
BLD - N	N	LM	ABD	AB	
AND - 0000	LMN	LM	ABD	AB	
OR - 0001	ABD + LMN = G	LM	ABD	AB	
BST	G	LM	ABD	AB	
BLD - C	C	G	LM	ABD	AB
AND - 0003	ABC	G	LM	ABD	AB
BLD - J	J	ABC	G	LM	ABD
AND - 0002	JLM	ABC	G	LM	ABD
BLD - H	H	JLM	ABC	G	LM
AND - F	HF	JLM	ABC	G	LM
AND - 0000	HFJLM	JLM	ABC	G	LM
OR - 0001	ABC + FHJLM = E	JLM	ABC	G	LM

MARK I

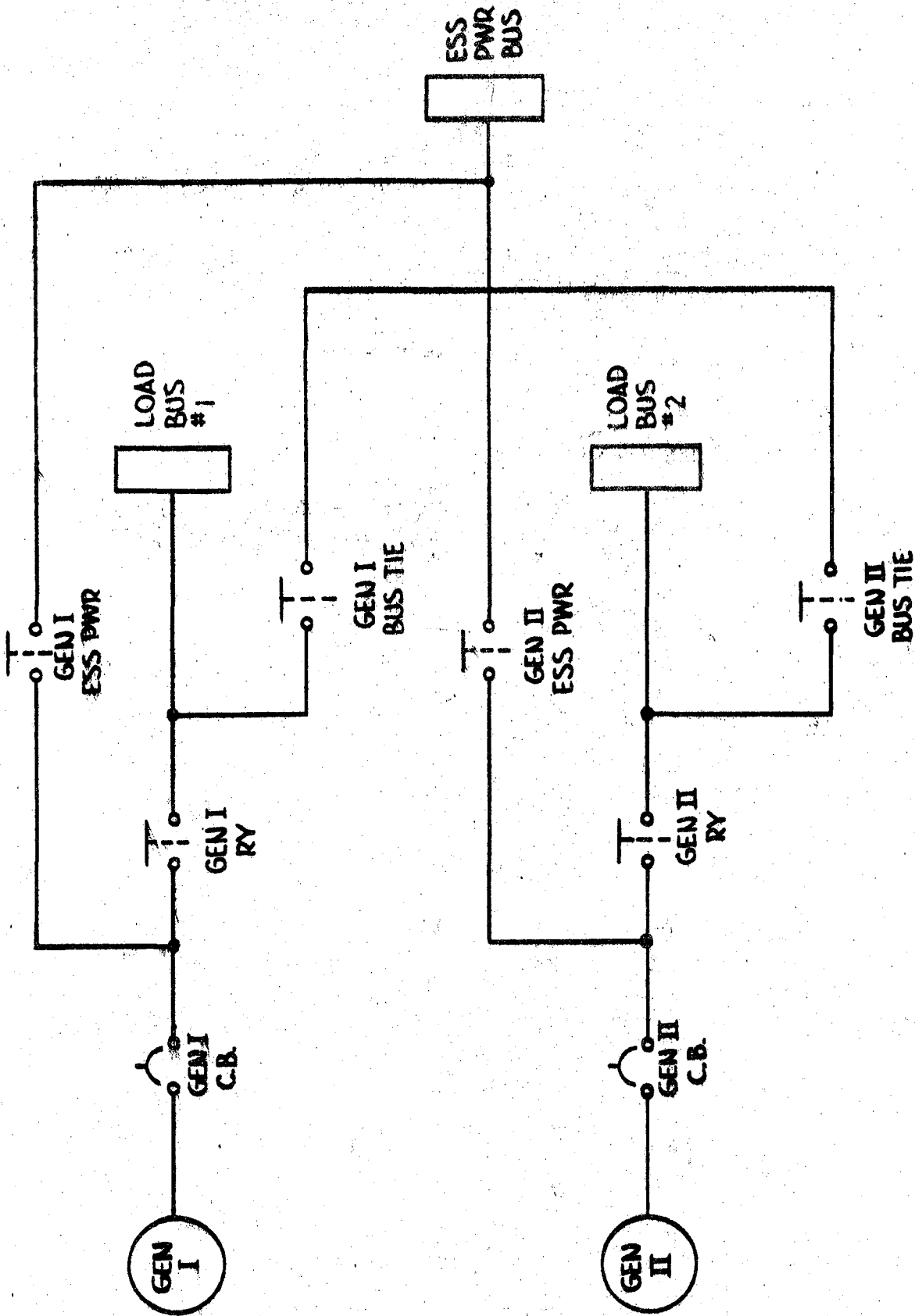


Figure 3-18. Aircraft Power Circuit

MARK I

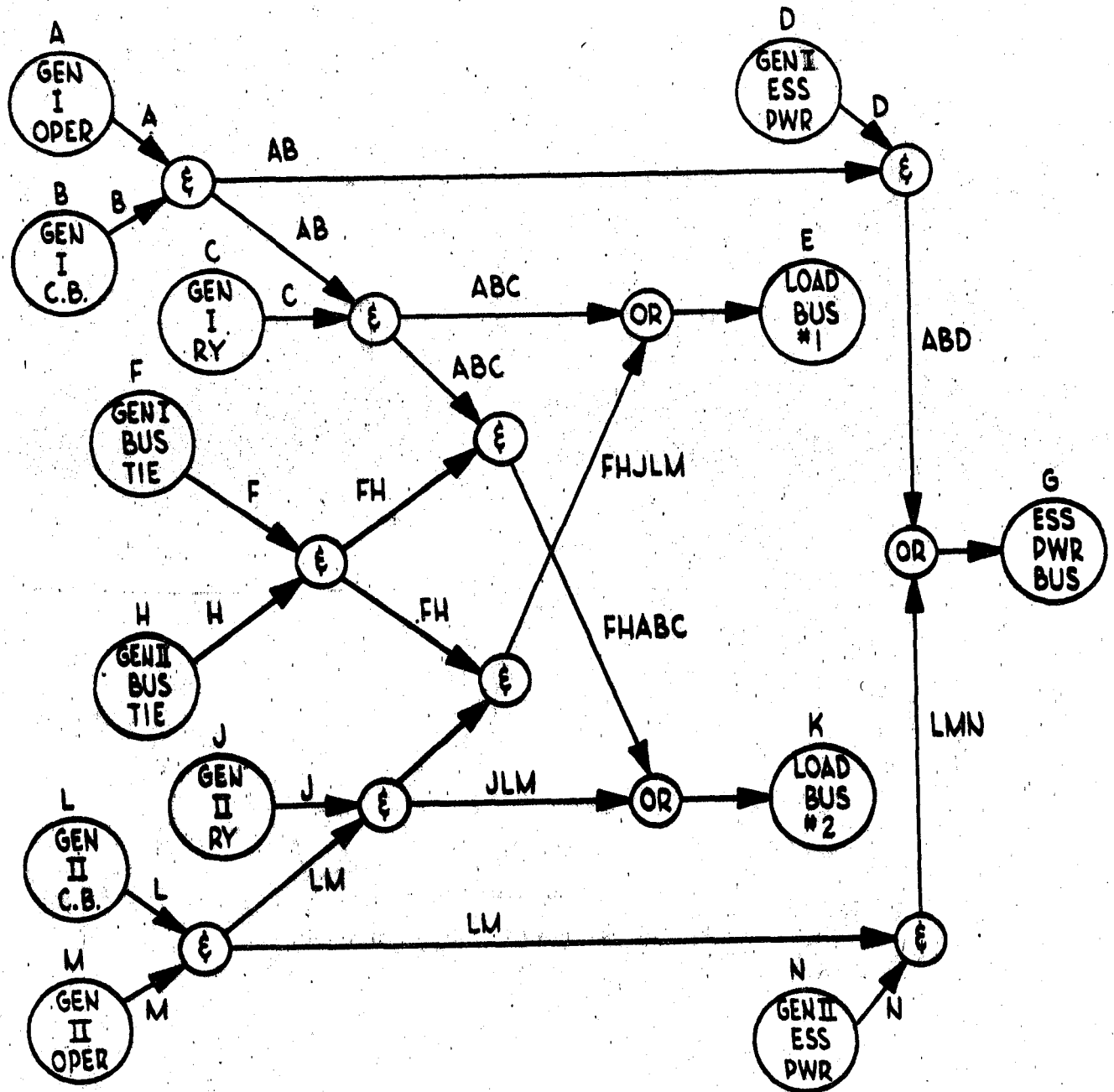


Figure 3-19. Aircraft Power Circuit Flow Chart

DATE 5/7/63
 PROBLEM BUS ENERGIZATION
 PROGRAMMER H. SMITH

CODING AND CONSTANT SHEET
 MARK I COMPUTER

F-2214-A

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE	MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
0 1	BLD	3 3	2 3 4 7				A					System Diagram (Figure 3-12)
0 2	AND	3 1	1 4 3 3				AB	↓				Calculate G
0 3	BLD	3 3	2 1 3 4				D	↓				
0 4	AND	3 1	0 0 0 0				ABD	↓				
0 5	BLD	3 3	1 4 3 5				L	↓				
0 6	AND	3 1	2 3 5 4				LM	↓				
0 7	BLD	3 3	2 1 3 6				N	↓				
0 8	AND	3 1	0 0 0 0				LMN	↓				
0 9	OR	3 0	0 0 0 1				ABD + LMN = G					↓
1 0	BST	3 4	3 2 1 7				G	↓	↓	↓		
1 1	BLD	3 3	2 1 3 1				C	↓	↓	↓		Calculate E
1 2	AND	3 1	0 0 0 3				ABC	↓	↓	↓		lost
1 3	BLD	3 3	2 1 3 5				J	↓	↓	↓		lost
1 4	AND	3 1	0 0 0 2				JLM	↓	↓	↓		lost
1 5	BLD	3 3	2 1 3 2				H	↓	↓	↓		lost
1 6	AND	3 1	2 1 3 3				FH					
1 7	AND	3 1	0 0 0 0				FHJLM					
1 8	OR	3 0	0 0 0 1				ABC + FHJLM = F					↓
1 9	BST	3 4	3 2 1 4				F	↓	↓	↓		lost
2 0	BLD	3 3	2 1 3 2				H	↓	↓	↓		lost
2 1	AND	3 1	2 1 3 3				FH					Calculate K
2 2	AND	3 1	0 0 0 2				ABCFH					
2 3	OR	3 0	0 0 0 1				ABCFH + JLM = K					
2 4	BST	3 4	3 2 1 5				K					

MARK I

Figure 3-20. Bus Energization

MARK I

	<u>ACCUM.</u>	<u>BOOLEAN SALVAGE</u>			
BST - E	E	JLM	ABC	G	LM
BLD - H	H	E	JLM	ABC	G
AND - F	FH	E	JLM	ABC	G
AND - 0002	FHABC	E	JLM	ABC	G
OR - 0001	JLM + FHABC = K	E	JLM	ABC	G
BST - K	K	E	JLM	ABC	G

3-80. Figure 3-20 is a sample of this program as it would appear on the standard form. The letter designations on the flow chart (figure 3-19) are used on this sheet with a cross reference to the flow chart under "REMARKS". The program is arranged using combinations in the Boolean salvage to reduce the number of instructions.

3-81. CORE MEMORY.

3-82. Core Memory Load Data. Information to be placed in core memory will be written, Most Significant digit first, as nine Octal digits, for the loading of 24-bit binary words. Words will be written in core memory address order. An example of a core memory word and binary equivalent is shown in figure 3-21.

Where dn = Octal data bits and sign
 X = Valid binary bits, "0" is not recognized
 Sign *X = "0" for positive number, "1" for negative number

d ₁ (sign)	d ₂	d ₃	d ₄	d ₅	d ₆	d ₇	d ₈	d ₉
00X	XXX	XXX	XXX	XXX	XXX	XXX	XXX	XX0

Figure 3-21. Core Memory Word

3-83. Core Memory Tape Format. The form of the Core Memory tape data words is shown in figure 3-22 where M = memory data and D = dummy code.

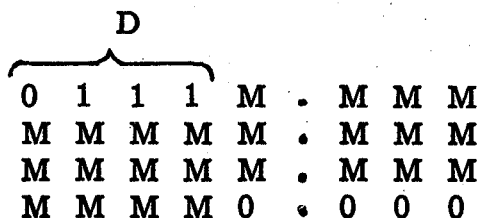
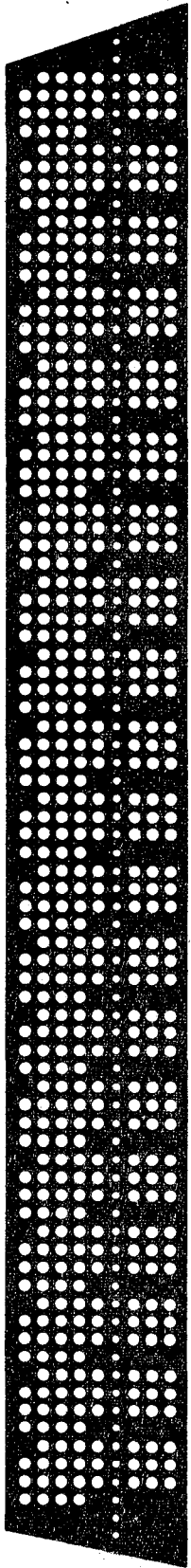


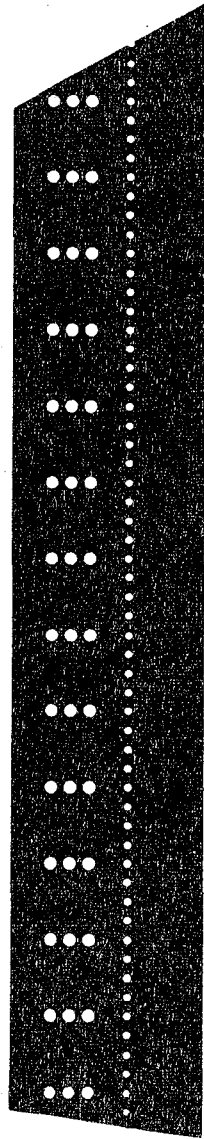
Figure 3-22. Core Memory Word Tape Format

3-84. Figure 3-23 illustrates three different core memory tapes used in testing the core. "A" tape is used for loading all ones, "B" all zeros, and "C" a combination of zeros and ones.

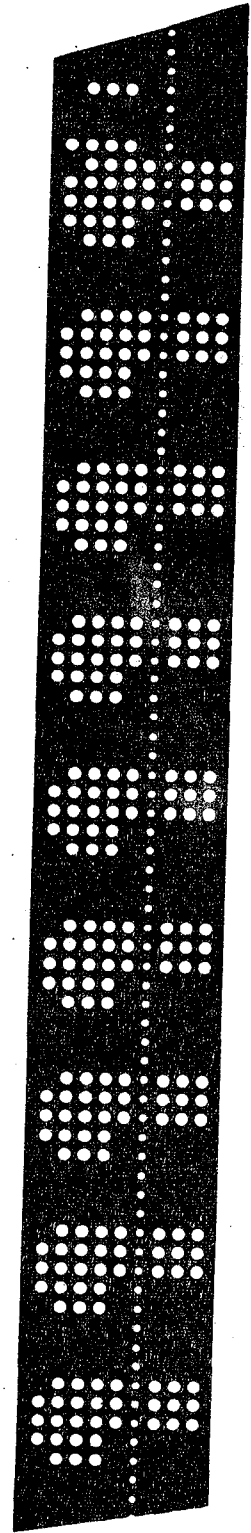
MARK I



TAPE A



TAPE B



TAPE C

Figure 3-23. Core Memory Tapes

MARK I

SECTION IV

PROGRAMMING AIDS

4-1. BOOLEAN ALGEBRA.

4-2. General. Boolean algebra is particularly suited for describing situations where variables can assume only two values. These two values have many designations: on-off, yes-no, plus-minus, one-zero, etc. Variables are designated by letters, and the two possible conditions are shown by the absence or presence of a bar over the letter. To illustrate, A and \bar{A} designate the two possible conditions of the variable A. They are read as "A" and "not A". The bar usually signifies the minor or negative condition. The barred function is known as the complement to its corresponding unbarred function.

4-3. To describe systems of more than one variable, several conventions must be accepted. Figure 4-1 illustrates the "AND" and "OR" circuits common to Boolean algebra.

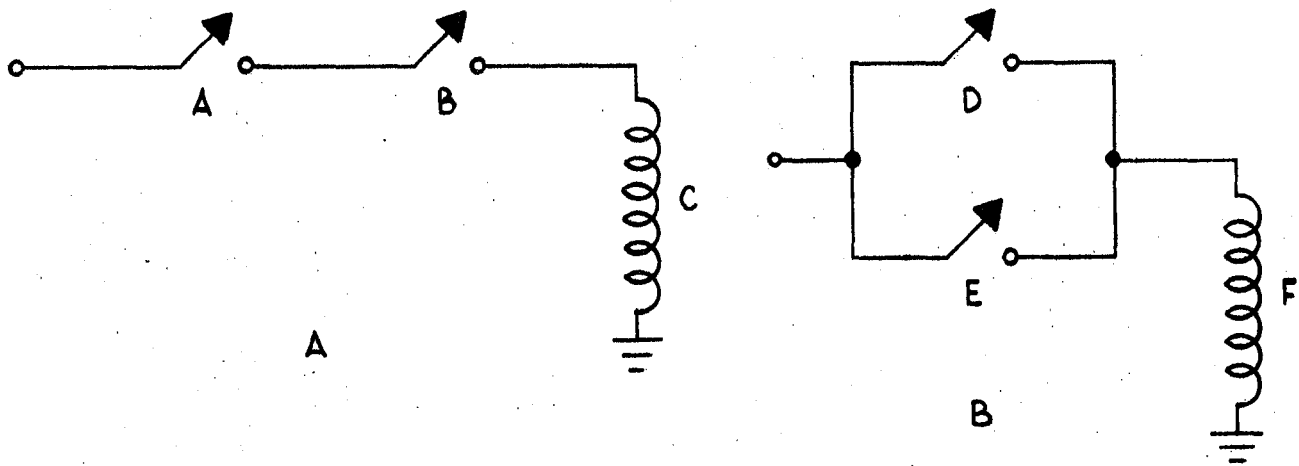


Figure 4-1. "AND" and "OR" Circuits

4-4. In figure 4-1 (A) relay C is energized when switches A and B are both energized. Thus, C equals A and B. The conventional symbol for the "AND" is a multiplication sign or implication ($C = A \cdot B$ or $C = AB$). In (B), the relay F is energized if switch D or E is closed. The symbol for "OR" is the addition sign ($F = D + E$).

4-5. Venn Diagram. A more general illustration of the meaning of "AND" and "OR" is shown by the Venn diagram figure 4-2.

MARK I

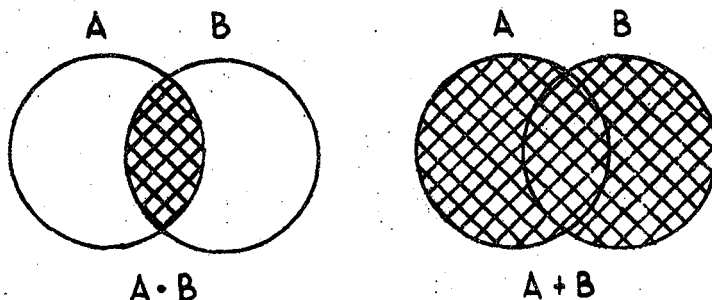


Figure 4-2. Venn Diagram

4-6. Referring to the Venn diagram, figure 4-2, the area inclosed by any circle represents the condition ascribed to the designation for that circle. The cross-hatched area common to both A and B shows the meaning of $A \cdot B$. The cross-hatched area covering both A and B, shows the meaning of $A + B$.

4-7. Figure 4-2 also shows the meaning of the complement when applied to more than one variable. Using the circles describing $A \cdot B$, $\overline{A \cdot B}$ would be all the area not cross-hatched including the area outside the circles. This is the area which is either outside A or outside B. This would be written $\overline{A} + \overline{B}$. This is one of many useful identities. Considering the area describing $A + B$, $\overline{A + B}$ would be all the area not cross-hatched. It is the area outside of A which is also outside of B. This can be expressed as $\overline{A} \cdot \overline{B}$ giving us the identity $\overline{A + B} = \overline{A} \cdot \overline{B}$.

4-8. Identities. The following are a list of identities useful in manipulating Boolean algebra.

- | | |
|---------------------------|--|
| 1. $A + 1 = 1$ | 10. $\overline{\overline{A}} = A$ |
| 2. $A \cdot 1 = A$ | 11. $\overline{\overline{A + B}} = \overline{A} \cdot \overline{B}$ |
| 3. $A + 0 = A$ | 12. $\overline{\overline{A \cdot B}} = \overline{A} + \overline{B}$ |
| 4. $A \cdot 0 = 0$ | 13. $A + \overline{A \cdot B} = A + B$ |
| 5. $A + A = A$ | 14. $A(\overline{A} + B) = AB$ |
| 6. $A \cdot A = A$ | 15. $\overline{(A + B)(\overline{A} + C)} = AC + \overline{A}B$ |
| 7. $A + AB = A$ | 16. $\overline{(\overline{A}C + B\overline{C})} = \overline{A}C + \overline{B}C$ |
| 8. $A(A + B) = A$ | 17. $\overline{(A + C)(B + \overline{C})} = \overline{(A + C)}(\overline{B} + \overline{C})$ |
| 9. $A + \overline{A} = 1$ | |

4-9. The one is used to mean the truth or continuance of a function. It can be compared to a short circuit in a system of switches. Zero is the opposite and can be compared to an open circuit. Number one and number four identities are illustrated in figure 4-3. Identities two and three also concur with figure 4-3.

4-10. Figure 4-3 (A) proves the first identity $B = A + 1 = 1$. The relay B is always energized whether switch A is open or closed. The fourth identity $B = A \cdot 0 = 0$, (B) shows that B will never be energized. Identities seven and eight are shown in figure 4-4.

MARK I

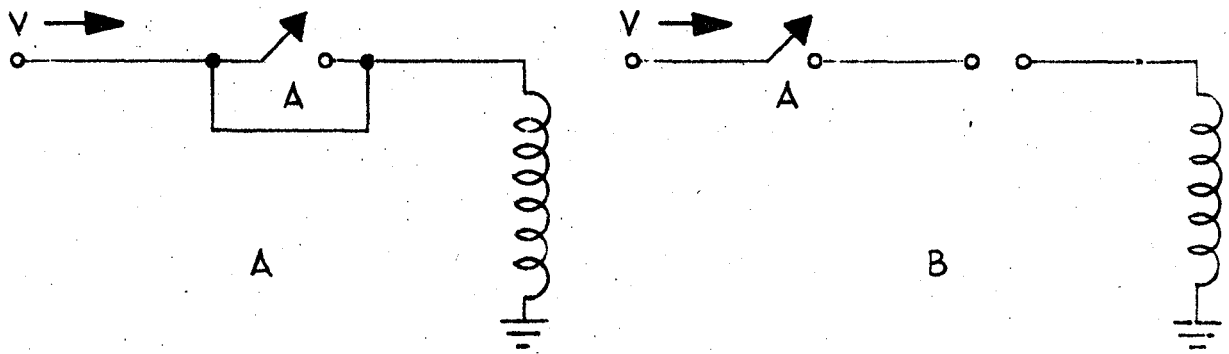


Figure 4-3. Identities 1 through 4

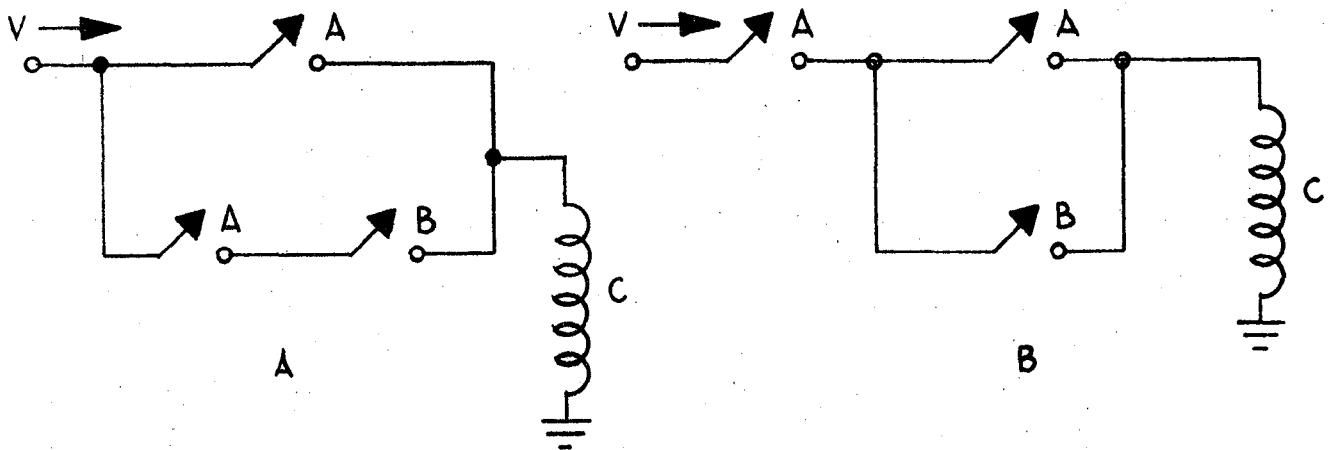


Figure 4-4. Identities Seven and Eight

4-11. Figure 4-4 (A) illustrates the seventh identity, $C = A + AB = A$. The parallel circuit with switches A and B is unnecessary because the operation of the relay C is the same without it. This can be shown mathematically as follows: $C = A + AB = A + A(1 + B) = A + A(1) = A$. The eight identity $C = A(A + B)$ illustrated in (B) shows that the parallel combination of A and B does not change the operation of relay C. This can also be shown by mathematical proof. $C + A(A + B) = A[A(1 + B)] = A[A(1)] = (A) = A$.

4-12. Identity 13, $A + \bar{A}B = A + B$ is derived from the equation $A + AB + \bar{A}B = A + \bar{A}B = A + B$. This equation is illustrated in figure 4-5.

4-13. Switches A and B in the middle path of the circuit (figure 4-5 (A)) do not change the operation of relay C. If either switch A or B is closed there will be a transmission. The mathematical proof follows:

$$A + \bar{A}B = A + AB + \bar{A}B = A + B(A + \bar{A}) = A + B(1) = A + B.$$

MARK I

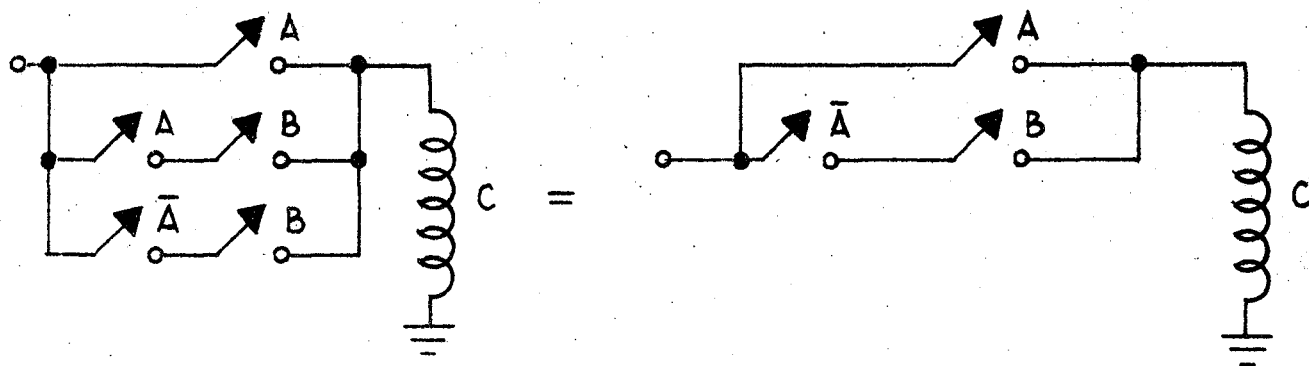


Figure 4-5. Identity 13

4-14. CONDITIONAL SKIPPING.

4-15. **General.** The "conditional skip" instruction allows the programmer to branch to two different groups of instructions by "skipping over" one of the two groups (i.e., if a certain condition is true, then _____; if not, then _____). The two groups in a branch are listed one after the other in the program. Depending on the results of a test, the Mark I either reads the first group of instructions and skips the second, or it skips the first group and reads the second.

4-16. The state of the Boolean accumulator is the test which determines the branch read. The Mark I will skip only when there is a one in the Boolean accumulator. The programmer is not restricted within the framework of allowed instructions, to devise a test which will result in the Boolean accumulator being set one way or the other so as to reflect the state of the condition being examined.

4-17. Since the two groups of instructions which follow a conditional skip are listed consecutively, then, in the event the first group is not skipped, but is read and performed, the second group must be skipped. In order for the Mark I to skip the second group of instructions, the first group must have a conditional skip as its last instruction. Assuming that the first group of instructions is being read and performed, then the contents of the Boolean accumulator must be zero. It is then necessary to include an "INVERT BOOLEAN" accumulator instruction (this instruction will set the Boolean accumulator to one), prior to the "conditional skip" at the end of the first group. The conditional skip instruction will then cause the second group to be skipped.

4-18. The maximum number of instructions that may be skipped with one "conditional skip" instruction is 127. If there is a necessity for a larger skip, the Mark I can skip from one "conditional skip" instruction to another "conditional skip" instruction.

DATE MAY 6, 1963
 PROBLEM X = A + B + C
 PROGRAMMER JOHN DOE

CODING AND CONSTANT SHEET
 MARK I COMPUTER

F-2214-A

INSTRUCTION NUMBER							O.P. CODE				MEM. ADD.				SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV.				REMARKS
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15					16	17	18	19	
			0	1			2	0		1	2	3	4		2 ⁻⁷	A						Load A into the Arithmetic Accumulator	
			0	2			1	0		1	0	0	1		2 ⁻⁸	A						Scale Right One Place to Form A.2 ⁻⁸	
			0	3			0	1		1	2	3	6		2 ⁻⁸	A + C						Add C.2 ⁻⁸ to the Contents of the Accumulator	
			0	4			2	0		1	2	3	5		2 ⁻⁴	B						Load B into the Accumulator Previous Contents Transfer to Salvage	
			0	5			1	0		1	0	0	4		2 ⁻⁸	B						Scale Right Three Places to Form B.2 ⁻⁸	
			0	6			0	1		0	0	0	0		2 ⁻⁸	A + B + C						Add Salvage to Accumulator	
			0	7			1	0		0	0	0	3		2 ⁻⁵	A + B + C = X						Scale Left Three Places to Form X.2 ⁻⁵	
			0	8			2	3		1	2	3	7		2 ⁻⁵	X						Store in X Location	

MARK I

Figure 4-6. Program Involving Scaling Operation

MARK I

4-19. SCALING AND SCALING PROBLEMS.

4-20. General. All constants and variables, as handled by the Mark I must be scaled to fall in the range from -1.0 to +1.0. The scaling factor in the Mark I is limited to integral powers of two to minimize time consuming multiplication or division operations. (Scaling or shifting operations are the equivalent of multiplying by powers of two.) The choice of scale factor is limited to the smallest integral power of two which, when divided into X_{\max} , results in a number less than or equal to 1.0 (i.e., $X_{\max}/2^n \leq 1.0$). For example, some variable that ranged decimally from -80 to +510 would require a scaling factor of at least 2^{-9} or $1/512$ to ensure against overflow.

4-21. The Mark I is capable of shifting as many as five places in one basic machine cycle. Thus, a left scale of three places is equivalent to multiplying by 2^{+3} , and right scale of three places is the same as multiplying by 2^{-3} . The scaling or shifting operation requires only one instruction word as opposed to a multiplication which requires five words.

NOTE

Care must be exercised when scaling left to make certain that overflows are not caused by scaling too many places.

4-22. When performing additions and subtractions, the scale factors of all the quantities involved must be identical. If the quantities being added have different scale factors, scaling operations must be performed to make these factors the same. Generally, all of the scales involved must be right scales, eliminating any overflow due to the scaling operation itself. Figure 4-6 illustrates an addition of three variables with different scaling factors.

4-23. Figure 4-6 forms the equation $X = A + B + C$, with X scaled at 2^{-5} as the desired quantity. A is scaled at 2^{-7} , B at 2^{-4} and C at 2^{-8} . A and B must both be scaled right; one place for A , and four places for B . The terms are then summed to form $X \cdot 2^{-8}$, and this quantity is scaled left three places to form $X \cdot 2^{-5}$.

4-24. When performing an addition and/or subtraction, the risk of overflow is still to be encountered in the actual performance of the operation itself, and serious consideration should be given to the order in which the steps of the equation are listed.

4-25. In the case where A , B , and C are variables ranging from -1.0 to +1.0, rearranging the order of steps is no longer a sufficient guarantee that overflow will not occur. In this case all of the variables must be scaled right a sufficient number of places so that no partial sum can cause an overflow.

MARK I

4-26. Multiplication. When multiplying two quantities both of which are less than or equal to one, there is no possibility of an overflow. It is possible that the product (AB) might be so small that the number of significant digits remaining in the accumulator are insufficient to describe AB with any accuracy (loss of resolution).

4-27. To overcome loss of resolution it is possible to shift the first fifteen digits of the MQ register into the accumulator using left shift instructions, after a multiplication, thus restoring the resolution of a product. Caution must be taken to ensure that the product AB is small enough to allow the shifting operation without causing overflow.

4-28. Division. When dividing in the Mark I, the problem of overflow is greatly increased. Since the quotient must always be less than or equal to one in magnitude, the dividend must be less or equal to the divisor in magnitude. That is, if $X = \frac{A}{B}$ and $-1.0 \leq X \leq +1.0$ then $|A| \leq |B|$.

4-29. If A and B are variables, careful consideration must be given to both the scale factors and the behaviors of these variables in order to decide on the final scale factor which will prevent an overflow under any conditions when performing the division.

4-30. A sample problem involving scaling techniques with multiplication and division is illustrated in figure 4-7.

4-31. It is desired to write a program for Mach number. The following equation is to be used: $M = \frac{.0152 V_p}{\sqrt{T_K}}$

$$T_K = T_{oa} + 273.16$$

where

T_{oa} = temperature of outside air in C° scaled 2^{-7}

T_K = temperature of outside air in K° scaled 2^{-9}

V_p = velocity of the A/C along the flight path in ft/sec scaled 2^{-11}

M = Mach number (result) 2^{-1}

Assume that the maximum V_p of the aircraft is 800 mph (1173 ft/sec) and the temperature of the outside air ranges from -70° to $+70^{\circ}$. The first step in programming a problem of this nature is to determine the range of numbers, scaled properly by 2.

$$\begin{aligned} .3967 \times 2^9 &\leq T_K \leq .6702 \times 2^9 \\ 0 &\leq V_p \leq .5722 \times 2^{11} \\ 0 &\leq .0152 V_p \leq .5572 \times 2^5 \\ .45 \times 2^5 &\leq \sqrt{T_K} \leq .58 \times 2^5 \end{aligned}$$

16
250

273.125

1.00010001001

DATE MAY 7, 1963
 PROBLEM COMPUTE MACH NO.
 PROGRAMMER G. GREEN

CODING AND CONSTANT SHEET
 MARK I COMPUTER

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE	MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV.				REMARKS
								1	2	3	4	
0 1	LD	2 0	1 0 0 2	2-7	TOA							
0 2	SCL	1 0	1 0 0 2	2-9	TOA							
0 3	LDK	2 2	4 2 1 1	2-9	273.16							Conversion Factor C ⁰ → K ⁰
0 4	ADD	0 1	0 0 0 0	2-9	TOA + 273.16 = T _K							
0 5	SCL	1 0	1 0 0 1	2-10	T _K							
0 6	SRS	0 7	1 0 0 0	2-10	T _K							
0 7	NPA	1 2	0 0 0 0									
0 8	NPB	2 5	3 7 7 7									
0 9	NPA	1 2	0 0 0 0									
1 0	NPB	2 5	3 7 7 7	2-5	$\sqrt{T_K}$							
1 1	ST	2 3	1 0 0 0	2-5	$\sqrt{T_K}$							T _K for Next Iteration
1 2	LDK	2 2	7 6 1 2	2-6	.0152							lost
1 3	MLT	0 3	1 0 0 4	2-6	.0152							
1 4	NPA	1 2	0 0 0 0									
1 5	NPB	2 5	3 7 7 7									
1 6	NPA	1 2	0 0 0 0									
1 7	NPB	2 5	3 7 7 7	2-5	.0152 VP							
1 8	SCL	1 0	1 0 0 1	2-6	.0152 VP							
1 9	DIV	0 6	0 0 0 0	2-6	.0152 VP							
2 0	NPA	1 2	0 0 0 0									
2 1	NPB	2 5	3 7 7 7									
2 2	NPA	1 2	0 0 0 0									
2 3	NPB	2 5	3 7 7 7	2-1	.0152 VP / $\sqrt{T_K} = M$							
2 4	ST	2 3	1 0 0 5	2-1	M							Store Mach No.

MARK I

Figure 4-7. Compute Mach Number

MARK I

The numerator $.0152 V_p \times 2^{-5}$ must be shifted right one place before it is divided by \sqrt{TK} since the largest value of the numerator is .5572 and the smallest value of the denominator is $.45 \times 2^{-5}$. Since the numerator is scaled at 2^{-6} after the shift and the denominator 2^{-5} , the resulting M will be scaled at 2^{-1} .

4-32. TIMERS.

4-33. General. A desired elapsed time can be determined in the Mark I by successively subtracting the total time elapsed, each time the storage location passes under the drum read heads, from the total time required for the unit to operate.

4-34. The drum band (fast, medium, or slow) on which the program is to be stored plays a major factor in a timing program. Storage locations on any band pass under the drum read heads at a constant interval (fast band locations every 50 milliseconds, medium band locations every 200 milliseconds, and slow band locations every 800 milliseconds). A numerical constant dependent upon the total time required for the unit to operate as well as the drum band on which the program is to be stored is required in "time delay" programs.

4-35. Figure 4-8 (Part A) is a sample time delay circuit in which the relay will energize 100 seconds after the bus bar has energized and the circuit breaker is "made". In Boolean language, the relay will energize when ABC equals 1. A sample program (when $ABC = 1$ compute $Z = \sqrt{X^2 + h^2}$) for this time delay circuit, programmed on one of the medium bands is shown in figure 4-8 (Part C). Figure 4-8 (Part B) is a flow chart for figure 4-8 (Part A).

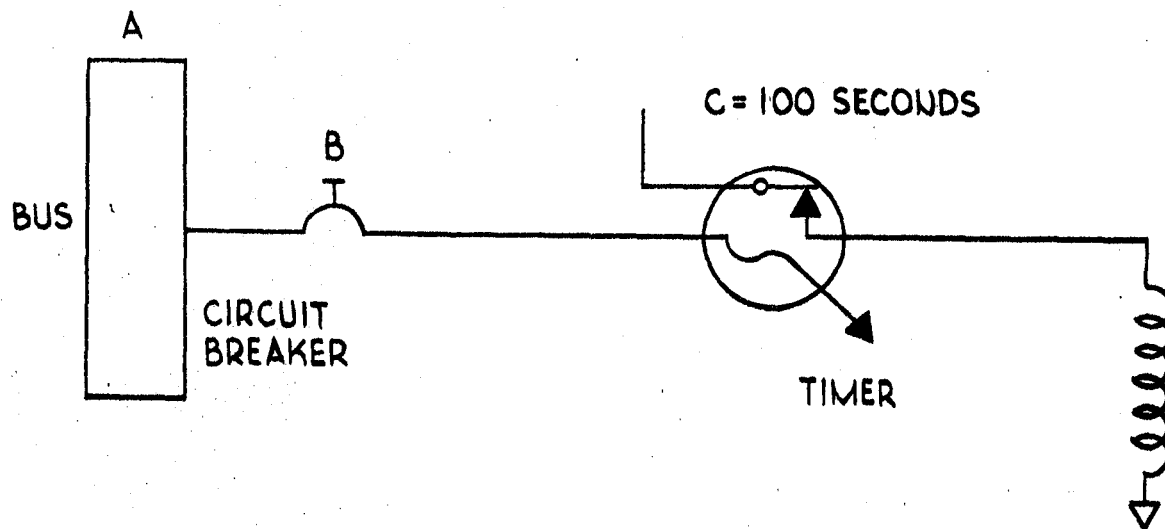


Figure 4-8. Time Delay (Part A - Circuit)

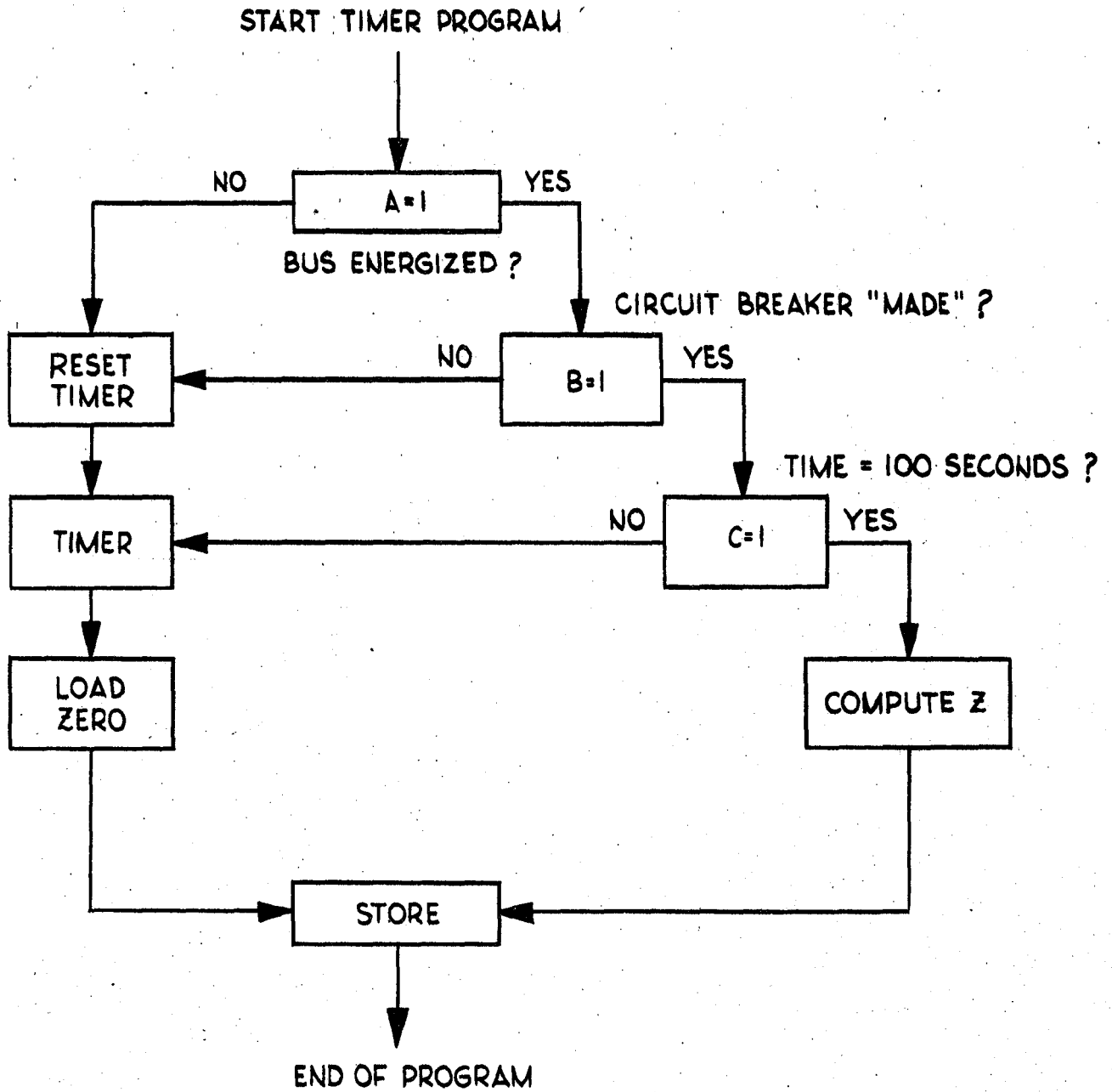


Figure 4-8. Time Delay (Part B - Flow Chart)

DATE 5/9/63

PROBLEM COMPUTE $Z = \sqrt{x^2 + h^2}$ AFTER A TIME DELAY

PROGRAMMER P. DAVIS

CODING AND CONSTANT SHEET

MARK I COMPUTER

PAGE 1 OF 2

F-2276-A

INSTRUCTION NUMBER	HEXADIC CODE	O.P. COOL	HEX. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
01	BLD	33	0127				A					
02	AND	31	0126				AB					
03	SKP	26	0002									If AB = 0 Steps 04 and 05 are used to reset the timer to 0.
04	LDK	22	0000									If AB = 1 Steps 04 and 05 are ignored.
05	ST	23	1004									
06	BN	32	0000				A + B					If steps 04 and 05 are read and performed by the machine invert and skip to store 0 for Z.
07	SKP	26	0033									
08	LDK	22	0010		500							Part of total time that elapses every time storage location passes under the drum read heads. Add to previously
09	ADD	01	1004		Cn + 500							accumulated time and store for next iteration to advance
10	ST	23	1004		Cn + 1							timer.
11	LDK	22	7776		1							
12	SUB	02	0000		1 - Cn + 1							If answer positive skip and store 0 for Z. If answer negative
13	FLN	16	0000				C					computer Z.
14	BN	30	0000				C					
15	SKP	26	0023									
16	LD	20	1000		X							
17	SQ	05	0000									
18	NPA	12	0000									
19	NPB	25	3777									
20	NPA	12	0000									
21	NPB	25	3777		x ²							
22	LD	20	1001		h							lost
23	SQ	05	0000									
24	NPA	12	0000									
25	NPB	25	3777									
26	NPA	12	0000									
27	NPB	25	3777		h ²							
28	ADD	01	0000		x ² - h ²							
29	SRS	07	1003									
30	NPA	12	0000									

MARK I

Figure 4-8. Time Delay (Part C - Program) (Sheet 1 of 2)

DATE 5/9/63
 PROBLEM COMPUTE $Z = \sqrt{x^2 + h^2}$ AFTER A TIME DELAY
 PROGRAMMER P. DAVIS

CODING AND CONSTANT SHEET
 MARK I COMPUTER

PAGE 2 OF 2

F-2216-A

INSTRUCTION NUMBER		MNEMONIC CODE	O.P. CODE		MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	BALV.	BOOLEAN ACCUMULATOR	BALV. 1	BALV. 2	BALV. 3	BALV. 4	REMARKS
1	2		3	4	5									
3	1	NPB	2	5	3 7 7 7									
3	2	NPA	1	2	0 0 0 0									
3	3	NPB	2	5	3 7 7 7		$\sqrt{x^2 + h^2}$							
3	4	BIN	3	2	0 0 0 0									
3	5	SKP	2	6	0 0 0 1									
3	6	LDK	2	2	0 0 0 0									
3	7	ST	2	3	1 0 0 3									

MARK I

Figure 4-8. Time Delay (Part C - Program) (Sheet 2 of 2)

4-36. "ILL BEHAVED" FUNCTIONS FOR THE LINEAR INTERPOLATOR.

4-37. General. Many times programmers are faced with the problem of programming function data for the digital interpolator which is not suited to being straight-lined between fixed breakpoints. (The curve has points of inflection whose ordinates do not coincide with any of the fixed breakpoints.) There are various methods of handling this problem, and the most suitable method chosen is determined by the nature of the function curve.

4-38. Warping. An efficient method for use on the Mark I is that of warping the curve into a more reasonable shape by replotting the function data vs. a new variable which is a function of the original independent variable. Instead of plotting $f(X)$ versus X , plot $f(X)$ versus $K_1 X^n + K_2$ or any other deliberately chosen function of X which will warp the function data in the desired manner. Figure 4-9 illustrates four curves. Curve 1 is the original curve of $f(X)$ vs. X . Curve 2 represents a

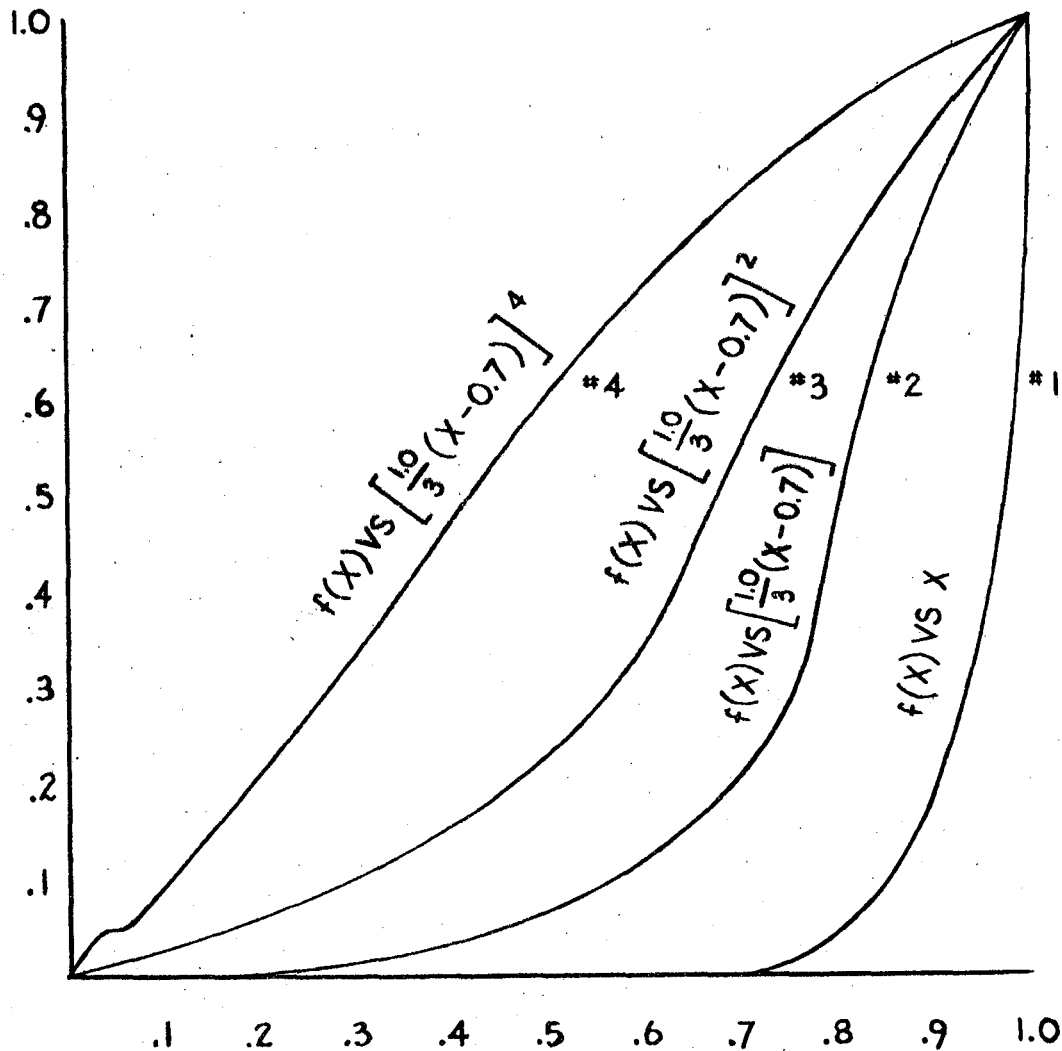


Figure 4-9. Curve Warping

MARK I

linear "stretching" of the independent variable $f(X)$ vs. $\frac{1.0}{3}(X-.7)$. In curve 3 the functional data is plotted versus $\left[\frac{1.0}{3}(X-.7)\right]^2$ and curve 4 $\left[\frac{1.0}{3}(X-.7)\right]^4$. Any degree of "warping" may be obtained by choosing the proper function of X as an independent variable. Whatever function is chosen as the independent variable must be generated in the general program and stored for use by the digital interpolator.

4-39. The "warping" method is not necessarily a "cure-all" for all of the "ill-behaved" functions which will be encountered by the programmer. It is possible that a function of the independent variable which produces the desired degree of warping is non-existent; or if it does exist, it is too difficult and time-consuming to devise. Further, it is possible that after the proper function has been derived, an excessive number of program steps are required to generate the new independent variable. Splitting a function into more than one curve is an answer to this problem in many cases.

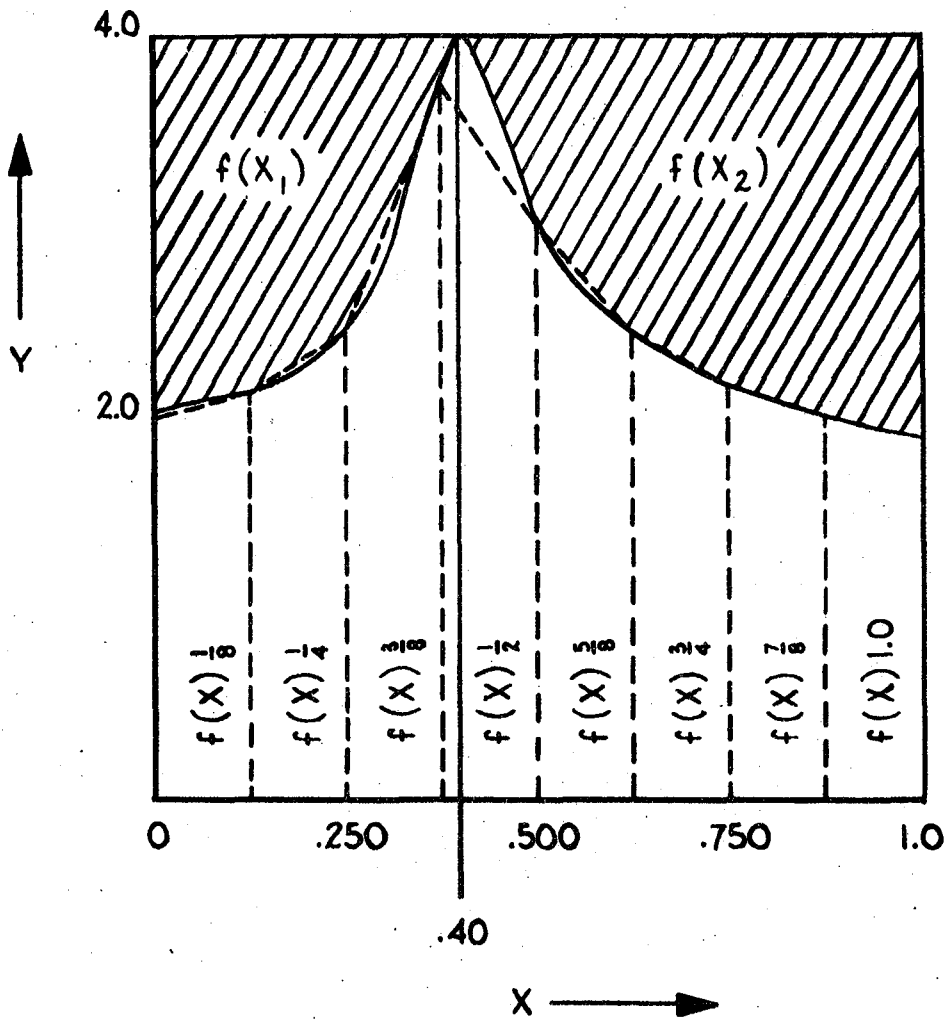


Figure 4-10. "Ill Behaved" Function

4-40. Splitting. Since the nine "breakpoints" are fixed by the logic of the interpolator at intervals of $1/8$ of the independent variable, X (i.e., $0, 1/8X, 1/4X, \dots, X$), then the function as constructed by the interpolator will be the dotted line overlaying figure 4-10. $f(X)$ is badly distorted by the removal of the peak in the vicinity of $X = 0.40$. In order to construct $f(X)$ with accuracy, split $f(X)$ into two functions; $f(X_1)$ for $0 \leq X \leq 0.40$ and $f(X_2)$ for $0.40 < X \leq 1.0$. (See figures 4-11 and 4-12.)

4-41. By rescaling X in the region between $X = 0$ and $X = 0.40$, the new quantity X is defined as $X_1 = \frac{X}{0.4}$ for $0 \leq X \leq .40$.

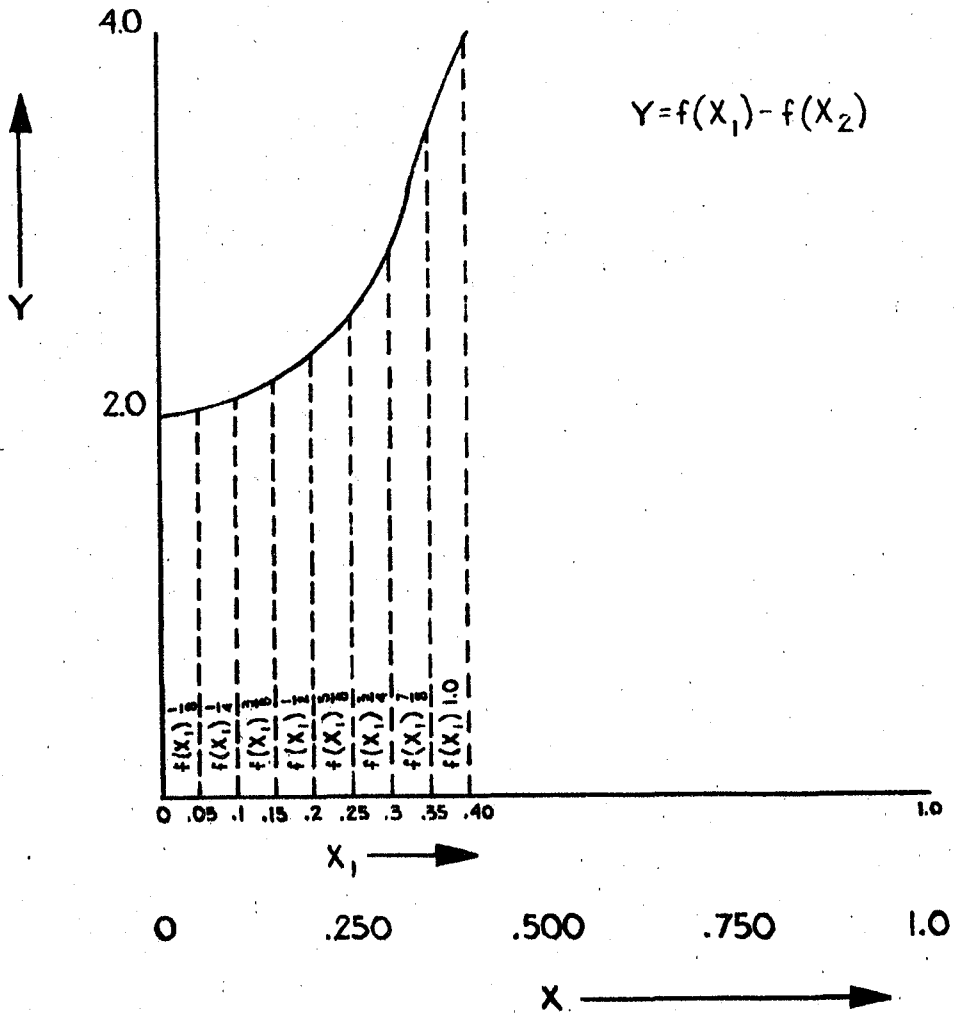


Figure 4-11. Function fX_1

MARK I

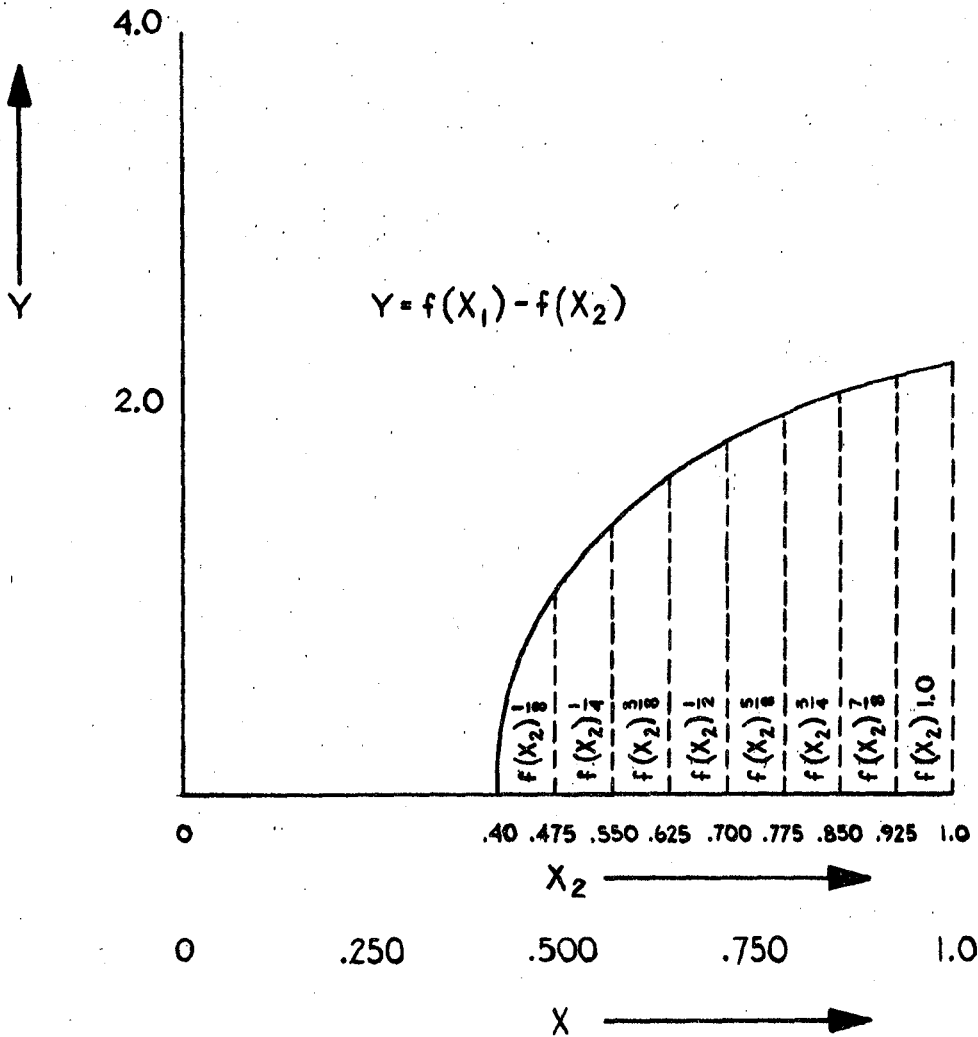


Figure 4-12. Function fX_2

4-42. Rescaling X in the region between $X = .40$ and $X = 1.0$ constructs the new quantity X_2 which is defined as: $fX_2 = X - 0.4/0.6$ for $.40 < X \leq 1.0$.

4-43. In figure 4-10 $Y = f(X)$. The new value of Y after "splitting" the function is: $Y = Y_1 = f(X_1) - f(X_2)$.

4-44. The three independent variable (X , X_1 , and X_2), must be assigned storage locations in core memory. Core memory locations must also be assigned for the independent variables (Y and Y_1).

4-45. An alternate method of programming X_1 and X_2 is setting a Boolean Flag (Flag negative instruction). Using this method, each time the Mark I calculated X , it would be necessary to test the numerical value of X to see if it was in the region of X_1 or X_2 .

MARK I

4-46. Using a Boolean Flag to program figure 4-10, the data curve for X_1 would remain the same as in figure 4-11 while the data curve for X_2 would be the inverse of figure 4-12 as illustrated in figure 4-13. The Boolean equation for these functions would be:

$$Y = A f(X_1) + A^* f(X_2)$$

Where + signifies or, and * boolean invert.

It is not necessary to use a Boolean Flag type program for any curve used with the 727 simulators.

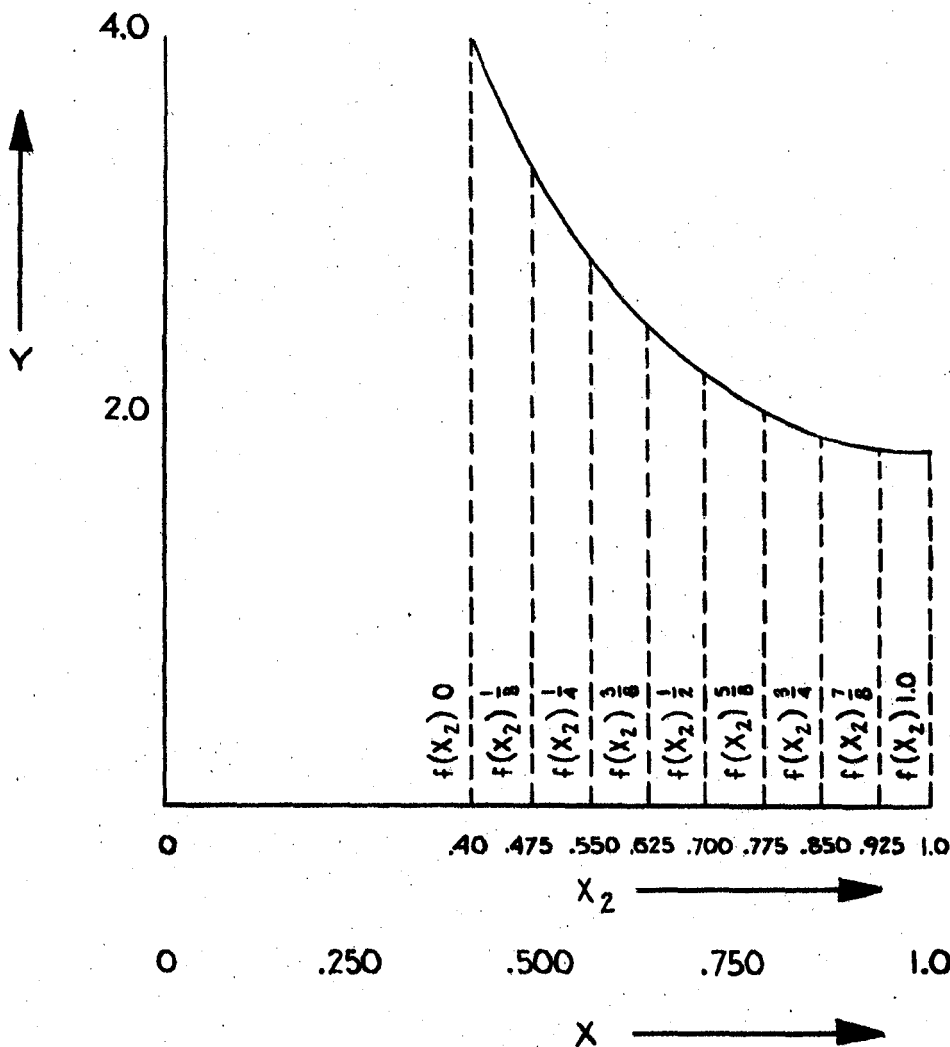


Figure 4-13. Inversion of Figure 4-12

MARK I

4-47. Coordinate Transfer. In many instances the given data curve for an interpolator function does not lie completely in the first quadrant (i.e., part of the data is numerically negative). Since all negative numbers are treated as zero by the interpolator, the coordinate axis must be "transferred" so that the complete curve lies within the first quadrant.

4-48. Figure 4-14 illustrates a given data curve to be placed on the interpolator section of the drum. To ensure positive values for each of the nine breakpoints, add two (the largest negative number) numerically to the independent variable X , and the dependent variable $f(X)$ which equals Y . Let the new values of X and Y be X_1 and Y_1 therefore $X_1 = X + 2$ and $Y_1 = Y + 2 = f(X_1)$ or $Y = f(X_1) - 2$.

4-49. Plotting X_1 and Y_1 , the curve is in the first quadrant (see figure 4-15), and now may be programmed onto the interpolator section of the magnetic drum.

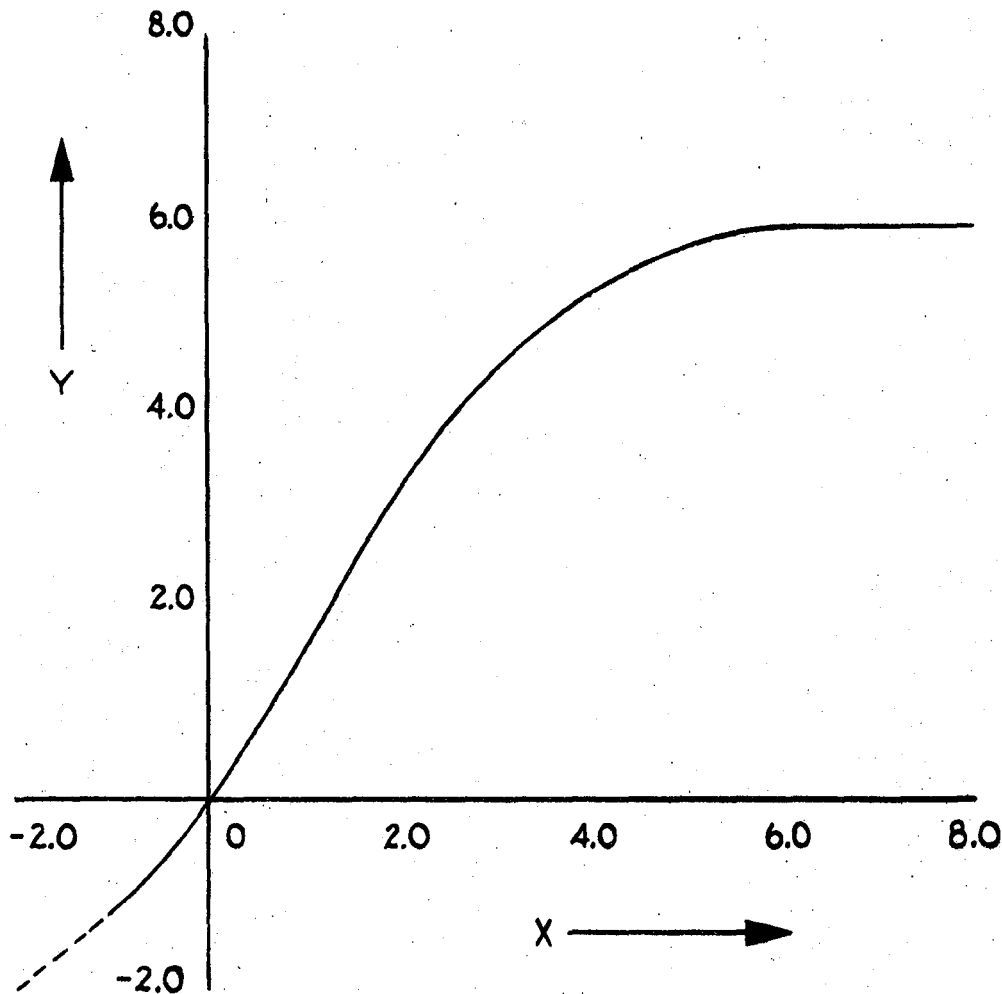


Figure 4-14. Given Data Curve

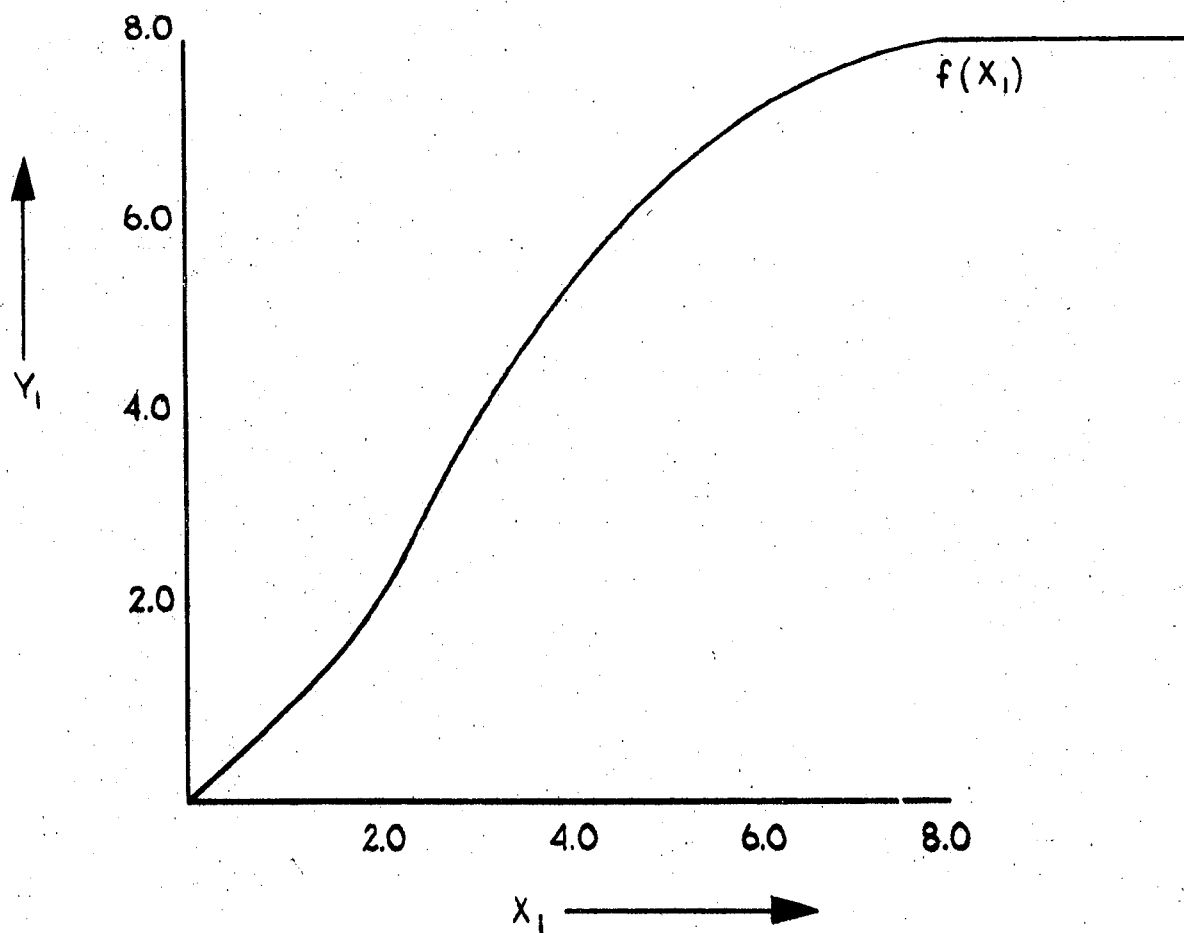


Figure 4-15. Coordinate Transfer of Figure 4-14

4-50. CALCULATION OF ENGINE TRANSIENTS.

4-51. General. Engine transients may occur during start-up, turn-off, change in throttle etc. The example used to explain a transient program will be fuel flow.

4-52. The transient produced in fuel flow (W_f) is caused by a change in throttle position (δth). When the Mark I receives notification that a transient has started because $(\delta th)_{i+1} - (\delta th)_i$ is greater than some constant ϵ , a Boolean flag is set to zero (in the example, flag "A") and a real time clock, t , is set to zero. In later iterations, the clock, t , will be incremented by some constant amount depending on the band this program is written on (refer to paragraph 4-34), until the program determines that the elapsed time from the start of the transient to the present time is greater than a specified amount. The flag will then be set to the non-transient case and the transient will be considered finished. However, the program will continue checking for changes in throttle position $(\delta th)_{i+1} - (\delta th)_i$ to determine if new transients are starting. The program will also consider a difference of sign between the quantities $[(\delta th)_{i+1} - (\delta th)_i]$ or $[(\delta th)_i - (\delta th)_{i+1}]$ as the start of a transient.

MARK I

4-53. The program will compute a W_f that will reflect the transient conditions by means of a multiplying constant $e^{-\lambda t^2}$. This function will be written on the interpolator section of the drum. The value of W_f when the clock was set to zero will be used as the value of W_f for $t = 0$. W_{fc} will be computed using the regular equation for this quantity. The equation used for the transient case will be: $W_f = W_{fc} + (W_{ft=0} - W_{fc})$. For the non-transient case, $W_f = W_{fc}$.

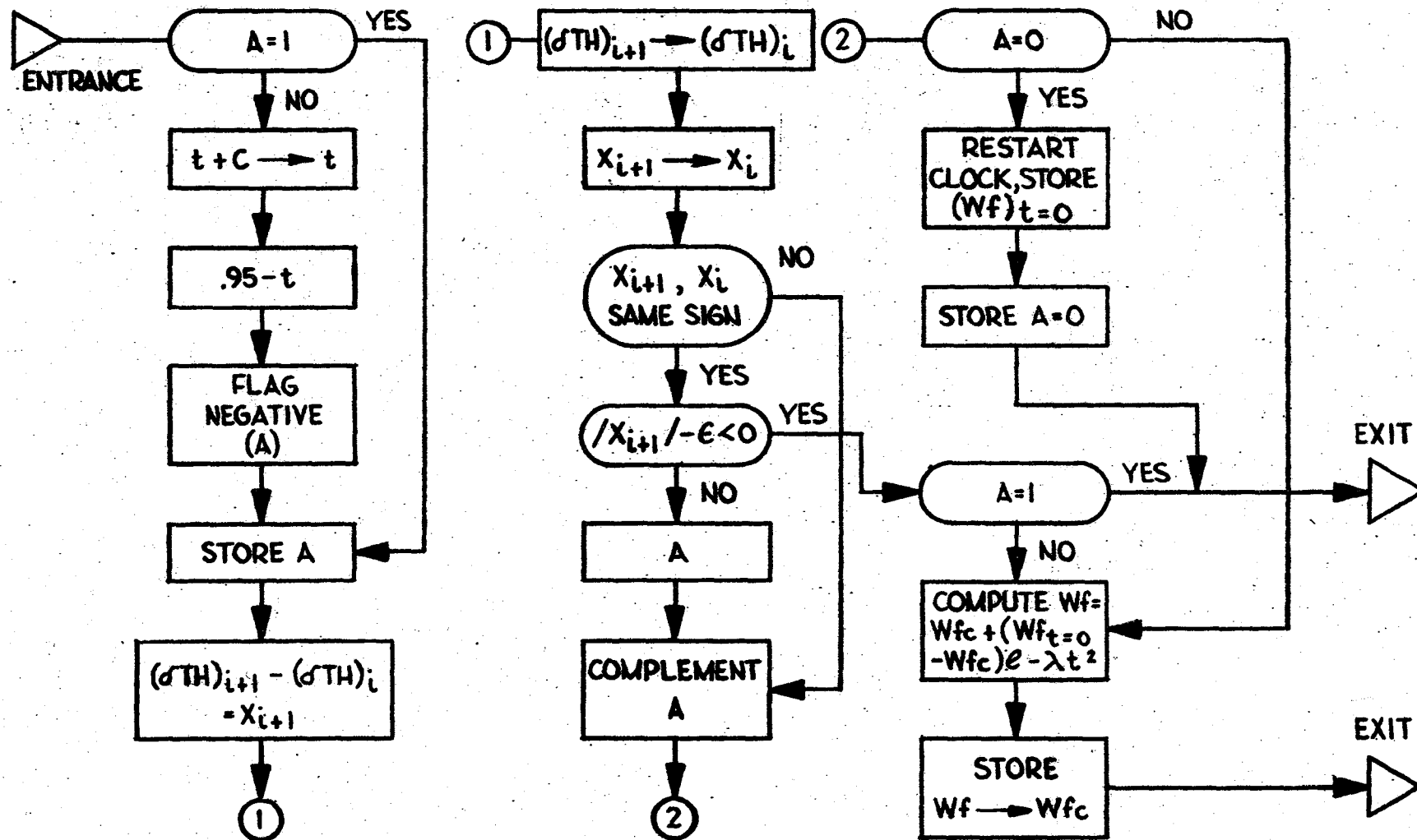
4-54. The flow chart (figure 4-16 Part (A)), and the "Coding and Constant Sheet" (figure 4-16 Part (B)) describe the techniques used. This problem is only intended as an example of programming engine transients, but drawing a flow chart before coding commences is almost absolutely necessary in problems of this type.

4-55. DOUBLE NUMBERS (1 WORD = 2 NUMBERS).

4-56. General. Double numbers will be encountered in problems pertaining to the radio aids portion of the program. Since one word in the radio aids section consists of 20 bits, and these 20 bits may sometimes describe two pieces of data; e.g., the most significant ten bits describe the X coordinate of a radio aid, while the least significant ten bits describe the Y coordinate. When this 20 bit word is loaded into the accumulator, the last four bits of the accumulator are zeros.

4-57. If operations are to be performed with the X coordinate, a right shift of one place clears the number out of the sign location and makes the number positive. The presence of the ten Y bits can only cause an error in the LSB of X. When operations are to be performed on Y, it is necessary to shift the accumulator left nine places, and make the result positive. This may be accomplished by two successive left shift commands, followed by an absolute value command to make the sign of the number positive.

4-58. To form a 20 digit number from two separate ten digit numbers in two different Core Memory locations, load the accumulator with the number that is to form the least significant part of the result, and make the sign positive with an absolute value command. Scale the number right ten places by two successive scale right commands, then scale right three places and left three places to eliminate the three least significant bits. The contents of the accumulator should be as shown in figure 4-17.



MARK I

Figure 4-16. W_f - Transient Part A - (Flow Chart)

CODING AND CONSTANT SHEET
MARK I COMPUTER

DATE JUNE 3, 1963
PROBLEM W1 TRANSIENTS
PROGRAMMER J. DOE

F-2214-A

INSTRUCTION NUMBER	INSTRUCTION	HEX. CODE	HEX. ADD.	SCALE	ARITHMETIC ACCUMULATOR	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
1	BLD	3 3	3 7 7 7								
2	SECP	2 6	0 0 0 4								
3	LDK	2 2	7 4 6 3								
4	SUB	0 2	1 0 0 0	.95 - 1							
5	FLN	1 6	0 0 0 0								
6	RST	3 4	3 7 7 7								
7	LD	2 0	1 0 0 1								
8	SUB	0 2	0 5 0 0		$d'X_{i+1} - (d'X_{i+1} = X_{i+1})$						Store X_{i+1}
9	ST	2 3	1 0 1 7								
10	LD	2 0	1 0 0 1								
11	ST	2 3	0 5 0 0			lost					
12	LD	2 0	1 0 1 6			lost					
13	FLN	1 6	0 0 0 0								
14	RST	3 4	3 7 7 6								Store Sign of X_i
15	LD	2 0	1 0 1 7								
16	ST	2 3	1 0 1 6								
17	FLN	1 6	0 0 0 0								
18	BLD	3 3	3 7 7 5								
19	BIN	3 2	0 0 0 0								Store Sign of X_{i+1}
20	AND	3 1	5 7 7 6								
21	BLD	3 3	3 7 7 6								
22	BIN	3 2	0 0 0 0								
23	AND	3 1	5 7 7 5								
24	OR	3 0	0 0 0 0								
25	SECP	2 6	0 0 1 0								
26	ABS	1 4	0 0 0 0	$X_{i+1}/$							
27	LDK	2 2		ϵ							
28	ENS	1 3	0 0 0 0	$-\epsilon$		lost					
29	ST	2 3	0 0 1 5								
30	ADD	0 1	0 0 0 0	$-\epsilon + X_{i+1}/$							Store Per Letter Zero Slice

Figure 4-16. W1 - Transient Part B - Program (Sheet 1 of 2)

DATE JUNE 3, 1963
 PROBLEM WI TRANSIENTS
 PROGRAMMER J. DOE

CODING AND CONSTANT SHEET
 MARK I COMPUTER

F-2214-A

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE	MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
31	FLN	16	0000									
32	SKP	26	0013									
33	BLD	33	3777									
34	BIN	32	0000									
35	SKP	26	0012									
36	BST	34	3777									
37	LD	20	1001		Wt = 0							
38	ST	23	1002									Store Wt at t = 0
39	LD	20	1015		-C							
40	FLN	16	0000									
41	ZSL	15	0000									
42	ST	23	1000		0 → t							Zero Clock
43	SKP	26										Exit
44	BLD	33	3777									
45	SKP	26										Exit
46	LD	20	1002		Wt at t = 0							
47	SUB	02	1001		$(Wt = 0 - Wt_c)$							
48	MLT	03	1170		$(Wt = 0 - Wt_c) e^{-\lambda t^2}$							
49	NPA	12	0000									
50	NPB	25	3777									
51	NPA	12	0000									
52	NPB	25	3777									
53	ADD	01	1001		Wtct $(Wt = 0 - Wt_c) e^{-\lambda t^2}$							
54	ST	23										Store Wt

MARK I

Figure 4-16. Wf - Transient Part B - Program (Sheet 2 of 2)

MARK I

0 | 0000000000 | YYYYYYYYYY | 000

Figure 4-17. Ten Least Significant Bits

4-59. Load the accumulator with the number that is to form the most significant part, scale right 13 places and then left 13 places, make the sign positive with an absolute value command, and add the contents of the salvage register. The contents of the accumulator will now be as shown in figure 4-18.

0 | xxxxxxxxxxxx | YYYYYYYYYY | 000

Figure 4-18. 20 Bit Number

4-60. The absolute value instructions may be eliminated if it is known that the values of X and Y are positive.

4-61. HANDLING A NUMBER AS A "COARSE" AND "FINE" SUM (1 NUMBER = 2 WORDS).

4-62. General. The situation in flight simulators in which some variable with an extremely large magnitude (e.g., distance, altitude) is calculated by integrating its derivative will be very often encountered by the programmer. With 23-bit resolution in the Mark I, the resolution of the variable may be adequate despite its great magnitude. It must be noted however, that the smallest bit (i.e., the 24th bit) of the word representing that variable may in itself represent a number which is fairly large in magnitude. The magnitude of this least significant bit, defines the smallest increment that may be added to the variable concerned.

4-63. Integration. Integration in the Mark I is accomplished by calculating an incremental change in the quantity concerned and adding that increment to the old value of the quantity. In the equation $X = \int x dt$, if X is extremely large in magnitude, then the LSB of X is correspondingly large, and the magnitude of this LSB is the smallest rate of change of X which can be integrated with accuracy. (A smaller \dot{X} would need a smaller increment to add to X.)

4-64. If it is necessary to "find a smaller increment" to add to X, so that very small rates can be integrated accurately, then it is necessary to magnify the LSB of X, thus improving the resolution.

4-65. This situation is handled by treating X as the sum of two numbers: $X = X_{\text{course}} (X_c) + X_{\text{fine}} (X_f)$. X_c will have the same scale factor as X ordinarily would. \dot{X} will be integrated to generate X_f , where X_f is $2^{10} X_c$. This represents a ten-bit increase in resolution. Each time that X_f is calculated by integrating \dot{X} , it is tested to see if it is large enough to add a significant digit to X_c . If it is large enough, X_f is scaled right ten places and added to X_c . Whatever amount is added to X_c must be subtracted from X_f . A sample problem of this nature is illustrated in figure 4-19 where:

CORRE AND CONSTANT SHEET
MARK I COMPUTER

DATE 5/28/63
PROGRAM "COARSE" AND "FINE" SUM
PROGRAMMER J. JAMES

INSTRUCTION NUMBER	MEMORIC CODE	MEN. ADD.	SCALE	ARITHMETIC ACCUMULATOR	BOOLEAN ACCUMULATOR	BALV. 4	BALV. 3	BALV. 2	BALV. 1
0.1	SUB	0.2	2 ⁻¹⁶	ΔXP					
0.2	ST	0.1	2 ⁻¹⁶	$\Delta XP - (XP)$					
0.3	SCL	1.0	2 ⁻²¹	XP					$\Delta XP + XP = \text{New } XP$
0.4	SCL	1.0	2 ⁻²⁶	XP					Temporarily Store XP
0.5	ST	2.3	2 ⁻²⁶	XP					
0.6	ADD	0.1	2 ⁻²⁶	$XP + XC = XC$					Temporarily Store XP (Calculate XC and Store)
0.7	ST	2.3	2 ⁻²⁶	XC					
0.8	LD	2.0	2 ⁻²⁶	XP					
0.9	SCL	1.0	2 ⁻²¹	XP					
1.0	SCL	1.0	2 ⁻¹⁶	XP					Adjust XP and Store
1.1	SUB	0.2	2 ⁻¹⁶	-XP					
1.2	ST	2.3	2 ⁻¹⁶	-XP					

Figure 4-19. "Coarse" and "Fine" Sum Program

MARK I

Xc is scaled at 2^{-26} and stored in location 0101

-Xf is scaled at 2^{-16} and stored in location 0102

locations 0103 and 0104 are used for temporary storage

ΔXf is scaled at 2^{-16}

Assume ΔXf has been calculated and is now stored in the accumulator.

4-66. LATITUDE-LONGITUDE INFORMATION.

4-67. All radio calculations will use aircraft location stored in units of degrees of Latitude (λ) and Longitude (L) scaled for the continental United States. (See table 4-1.) Figure 4-20 shows the sign convention to be used for the United States.

Table 4-1. Latitude-Longitude Scale

<u>Bit</u>	<u>Degrees</u>	<u>Nautical Miles</u>	<u>Feet</u>
1	± 64	3,840	23,348,239.3
2	32	1,920	11,679,119.65
3	16	960	5,839,559.825
4	8	480	2,919,779.913
5	4	240	1,459,889.956
6	2	120	729,944.978
7	1	60	364,972.489
8	30'	30	182,486.245
9	15'	15	91,243.122
10	7'30"	7.5	45,621.561
11	3'45"	3.75	22,810.781
12	1'52.5"	1.875	11,405.390
13	56.25"	0.9375	5,702.695

MARK I

<u>Bit</u>	<u>Degrees</u>	<u>Nautical Miles</u>	<u>Feet</u>
14	28.125"	0.46875	2,851.3475
15	14.0625"	0.234375	1,425.674
16	7/03125"	0.1171875	712.837
17			356.418
18			178.209
19			89.104
20			44.552
21			22.276
22			11.138
23			5.569
24			2.784

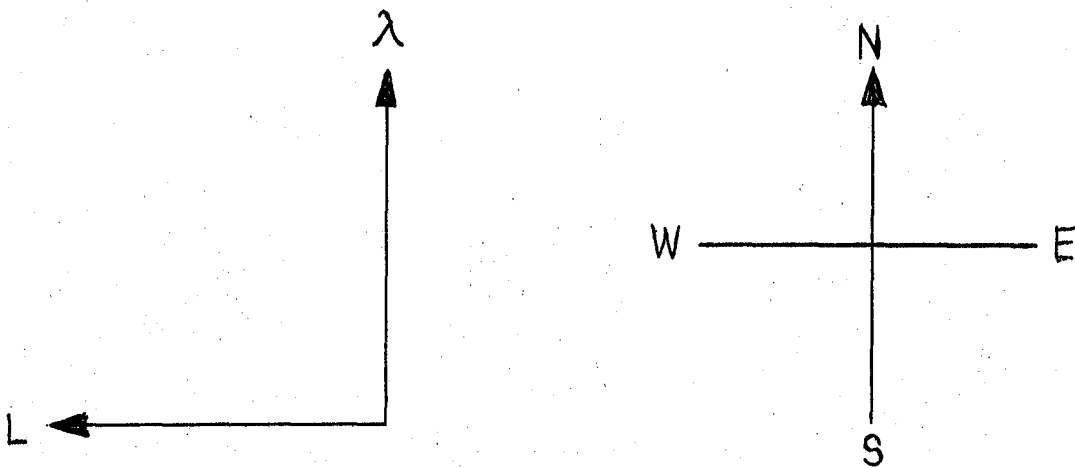


Figure 4-20. Latitude-Longitude Sign Convention

MARK I

4-68. The values of λ and L are derived from the following equations.

$$\text{Latitude} = \lambda' = (2.7411 \times 10^{-6}) \int [\overline{UL}_1 + VM_1 + WN_1 + vW_1]$$

$$\text{Longitude} = L = (2.7411 \times 10^{-6}) (\sec \lambda) \int [\overline{UL}_2 + VM_2 + WN_2 + vW_2]$$

Where: L_1 L_2 , M_1 M_2 , are direction cosines

U, V, and W are translational velocities along the X, Y, and Z axes respectively.

vW_1 and vW_2 are wind velocity components.

The constant 2.7411×10^{-6} is the conversion factor for converting feet to degrees of arc.

4-69. The equations used for converting degrees to nautical miles follow:

$$\lambda' = 60 \lambda$$

$$L' = 60L \cos \lambda$$

where: λ = latitude in degrees of arc

λ' = distance along any meridian in nautical miles (NM)

L = longitude in degrees of arc

L' = distance along the parallel in nautical miles

4-70. COORDINATE SYSTEMS.

4-71. General. Many different coordinate systems are needed for navigation calculations. The basic system will be LATITUDE-LONGITUDE (paragraph 4-66). Other coordinate systems used are the X - Y and a-c rectangular systems and the R - ψ polar system.

4-72. X-Y Rectangular System. The X - Y rectangular system will be used for recorder applications and in small areas where meridian convergence can be neglected. The system is a rectangular system and the X axis always points to TRUE NORTH (see figure 4-21).

4-73. a-b Rectangular System. The a-b rectangular system is used in marker beacon and A-N range calculations for the rotation of the X - Y coordinate system through an angle ψ where $-90^\circ > \psi > +90^\circ$. Figure 4-22 illustrates the sign convention to be used.

MARK I

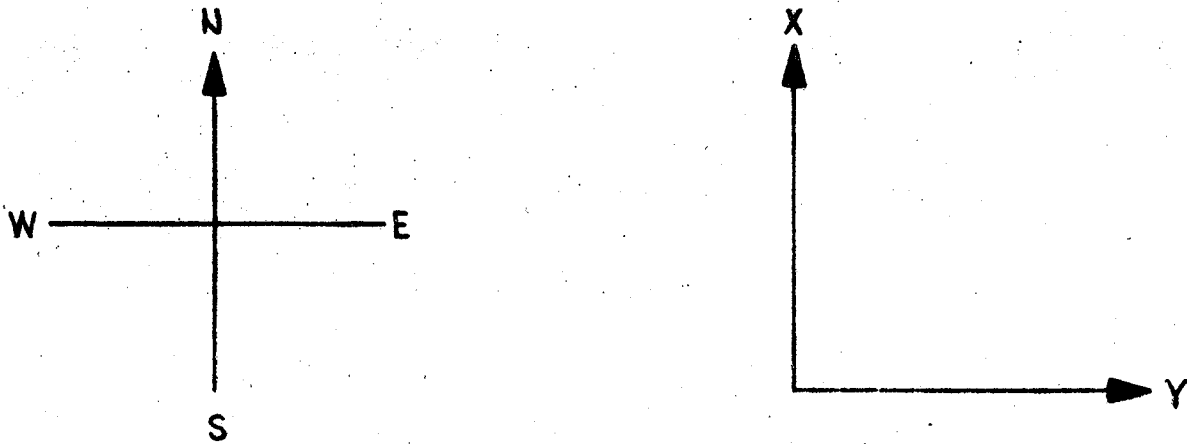


Figure 4-21. X - Y Coordinate System Sign Convention

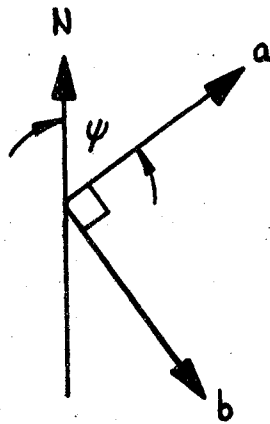


Figure 4-22. a-b Coordinate System Sign Convention

4-74. R - ψ Polar System. The R - ψ polar system is used for bearing and range systems such as in VOR and DME. The sign convention is illustrated in figure 4-23.

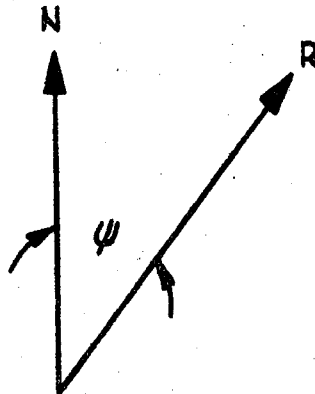


Figure 4-23. R - ψ Polar System Sign Convention

MARK I

4-75. Converting From L- λ to a-b Coordinates.

4-76. For small distances we can assume the L- λ coordinate system to be truly rectangular, thus when converting from a L- λ system to the a-b system (refer to figure 4-24), the following equations can be used:

$$a_{GAS} = 364,816 \left[(L_s - L_a) \cos \lambda_a \sin \psi + (\lambda_a - \lambda_s) \cos \psi \right]$$

$$b_{GAS} = 364,816 \left[(L_s - L_a) \cos \lambda_a \cos \psi - (\lambda_a - \lambda_s) \sin \psi \right]$$

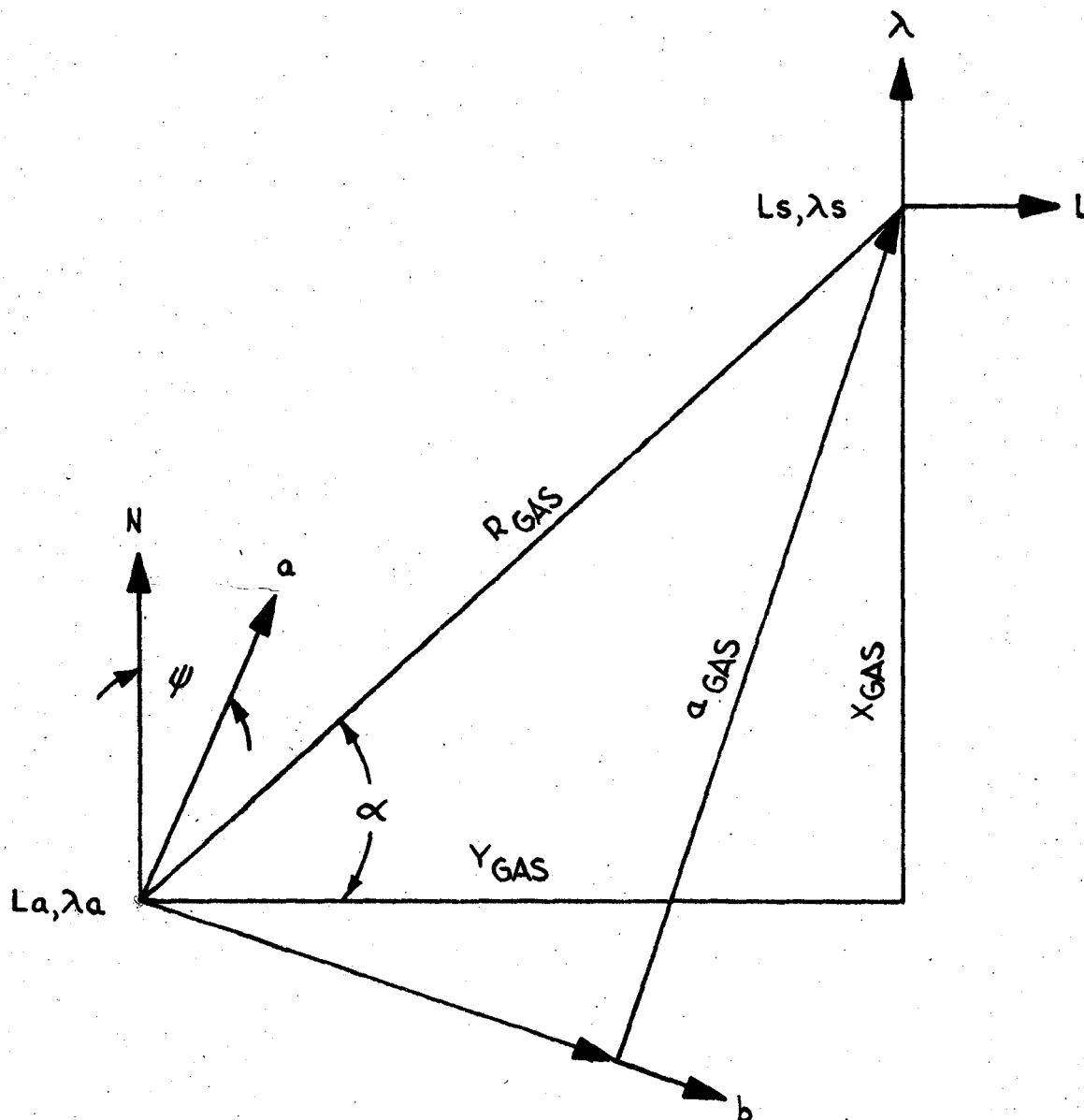


Figure 4-24. Converting From L- λ To a-b Coordinates

MARK I

where L and λ are degrees

$\cos \lambda a$ is a function from the LFI

$\sin \psi$ and cosine ψ are station data words

a_{GAS} and b_{GAS} are in feet

Subscripts - a is for aircraft
s is for station

Derivation

$$\begin{aligned} a_{GAS} &= R_{GAS} \sin (\psi + \alpha) \\ &= R_{GAS} [\sin \psi \cos \alpha + \cos \psi \sin \alpha] \end{aligned} \quad (1)$$

$$\begin{aligned} b_{GAS} &= R_{GAS} \cos (\psi + \alpha) \\ &= R_{GAS} [\cos \psi \cos \alpha - \sin \psi \sin \alpha] \end{aligned} \quad (2)$$

$$\cos \alpha = Y_{GAS} / R_{GAS} \quad (3)$$

$$\sin \alpha = X_{GAS} / R_{GAS} \quad (4)$$

Substituting equations (3) and (4) in equation (1)

$$\begin{aligned} a_{GAS} &= R_{GAS} [\sin \psi Y_{GAS} / R_{GAS} + \cos \psi X_{GAS} / R_{GAS}] \\ a_{GAS} &= Y_{GAS} \sin \psi + X_{GAS} \cos \psi \end{aligned} \quad (5)$$

In like manner equation (2) becomes

$$b_{GAS} = Y_{GAS} \cos \psi - X_{GAS} \sin \psi \quad (6)$$

$$X_{GAS} = 364,816 (\lambda a - \lambda s) \quad (7)$$

$$Y_{GAS} = 364,816 (Ls - La) \cos \lambda a \quad (8)$$

where: 364,816 is the conversion factor for converting degrees to feet.

Substituting equations (7) and (8) in equations (5) and (6)

$$a_{GAS} = 364,816 [(Ls - La) \cos \lambda a \sin \psi + (\lambda a - \lambda s) \cos \psi] \quad (9)$$

$$b_{GAS} = 364,816 [(Ls - La) \cos \lambda a \cos \psi - (\lambda a - \lambda s) \sin \psi] \quad (10)$$

MARK I

4-77. LAMBERT CONFORMAL CONIC PROJECTION CALCULATIONS.

4-78. The recorder plots in an X - Y coordinate system on a Lambert Conformal Conic Projection Chart. Because it plots in an X - Y system it is necessary to convert the aircraft location in the L-λ coordinate system into an X - Y system for the recorder.

4-79. The following equations are to be used for the computation of the X - Y coordinate for the recorder, (Refer to figures 4-25 and 4-26.)

$$\gamma = (L_a - L_0) \sin \phi \quad (1)$$

$$\rho a = \rho_1 + 60 (\lambda a - \lambda_1) + f(\lambda) \quad (2)$$

$$\rho_0 = \rho_1 = 60 (\lambda_0 - \lambda_1) + f(\lambda) \quad (3)$$

$$X_0 = 72913.2 / \mu \rho_0 \quad (4)$$

$$X_c = 72913.2 / \mu (-\rho a) \cos \gamma + X_0 \quad (5)$$

$$Y_c = 72913.2 / \mu \rho a \sin$$

where:

L = longitude (degrees)

λ = latitude (degrees)

ρ = radius of cone (NMI)

γ = degrees

X = X coordinate (inches)

Y = Y coordinate (inches)

μ = scale factor (e.g., with a 1:2,000,000 scale μ = 2,000,000)

72913.2 = number of inches per nautical mile

Subscripts:

0 pertains to chart reference points of (0, 0)

1 and 2 pertains to standard parallel of projection where subscript 1 is for the greater value

MARK I

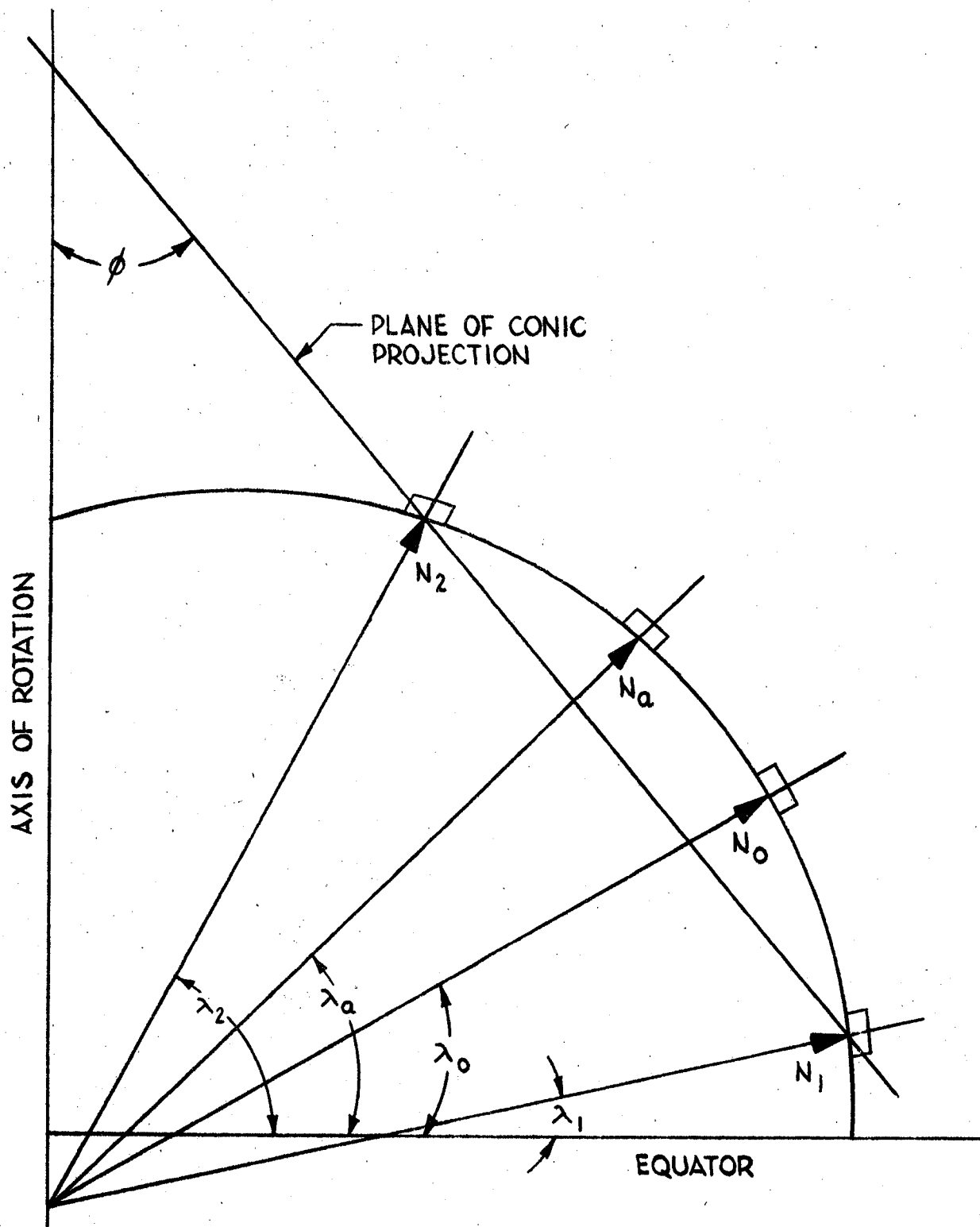


Figure 4-25. Lambert Conic Projection, Plane Perpendicular To Projection

MARK I

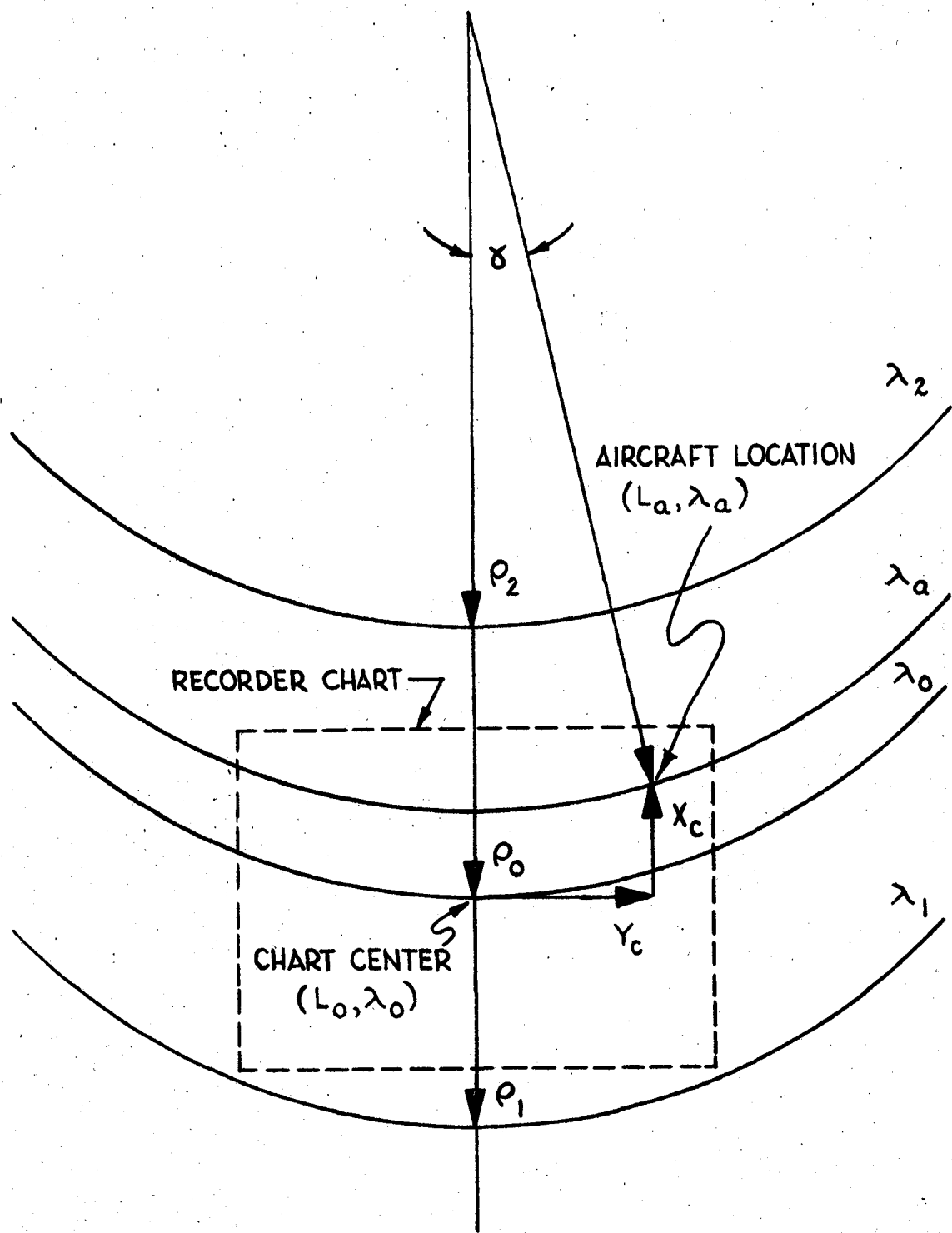


Figure 4-26. Lambert Conic Projection, Chart Plane

MARK I

- a pertains to aircraft location
- c pertains to chart location of pen

m , ϕ , ρ , and $f(\lambda)$ are empirical functions unique to the standard parallels for the projection used. These terms are explained in paragraph 4-77.

4-80. EMPIRICAL FUNCTIONS.

4-81. The cone of projection makes an angle ϕ with the axis of rotation of the earth. The sine of the angle also considers the eccentricity of the earth. The equation for the sine of ϕ follows:

$$\sin \phi = \frac{\log \cos \lambda_1 - \log \cos \lambda_2 + \log N_1 - \log N_2}{\log \tan \left(\frac{\pi}{4} + \frac{\lambda_2}{2} \right) - \log \tan \left(\frac{\pi}{4} + \frac{\lambda_1}{2} \right)}$$

$$N_1 = \frac{a}{\sqrt{1 - E^2 \sin^2 \lambda_1}}$$

$$N_2 = \frac{a}{\sqrt{1 - E^2 \sin^2 \lambda_2}}$$

ρ where E = eccentricity = 0.0822751

a = radius of earth = 3437.75 NM

ρ_1 is the radius of the concentric circle in NMI, representing λ_1 on the chart projection.

$$\rho_1 = \frac{N_1 \cos \lambda_1}{\sin \phi}$$

The values of $\sin \phi$ and ρ_1 for the standard Lambert Projections used with the TWA 727 is as follows:

Standard Parallels	ρ_1	$\sin \phi$
33/45	4591.524 NMI	0.627926

4-82. $f(\lambda a)$ is a correction factor added to equations (2) and (3) (paragraph 4-77), to increase the accuracy of the radii since the 60 (NM/Degrees) is an approximation. The exact value of ρ can be calculated by the following equation. Having the exact value of ρ , the correction factor $[f(\lambda a)]$ can be calculated and plotted as a function of λa .

$$\ln r = -\sin \phi \ln \left[\tan \left(\frac{\pi}{4} + \frac{\lambda}{2} \right) \right] + C_1$$

MARK I

where $C_i = \ln \rho_1 + \sin \phi \ln \left[\tan \left(\frac{\pi}{4} \right) + \left(\frac{\lambda}{2} \right) \right]$

r = the exact radius of ρ at λ

λ = latitude of point in question

Therefore

$$f(\lambda) = r = \rho_1 - 60 (\lambda - \lambda_1)$$

4-83. MARKER BEACONS.

4-84. All types of 75 MC marker beacons are simulated by using the following equations:

a. FM E = $695h/8a^2 + b^2 + 8h^2$

b. BONE E = $600h/8a^2 + b^2 + 4h^2 \left[0.5 + \left| \frac{b}{a} \right| \right]$ where $\left| \frac{b}{a} \right| \leq 1$

c. ILS E = $64h/8a^2 + b^2 + h^2$

d. LFM E = $20h/2a^2 + b^2 + h^2/4 - \frac{80h}{8a^2 + 4b^2 + h^2}$

$$Z E = 72h/8a^2 + 8b^2 + h^2$$

In the above equations:

a = distance from station to aircraft along the minor axis in feet.

b = distance from station to aircraft along the major axis in feet.

h = altitude of the aircraft above the station in feet.

E = signal level at the aircraft in volts.

4-85. LFRR CALCULATIONS.

4-86. General. The four "Coarse Legs" making up the LFRR patterns will be simulated through the use of four circular radiation patterns (see figure 4-27).

4-87. Opposite pairs of circles represent the "A" and "N" signal, the centers of these circles form an "a-b" rectangular coordinate system. The "Course Legs" are the areas where the circles overlap. In order to provide the necessary combination of "Course Legs" it is necessary to provide rotation of the rectangular coordinate system (see figure 4-28). This angle of rotation is always measured from "TRUE NORTH" and the a axis.

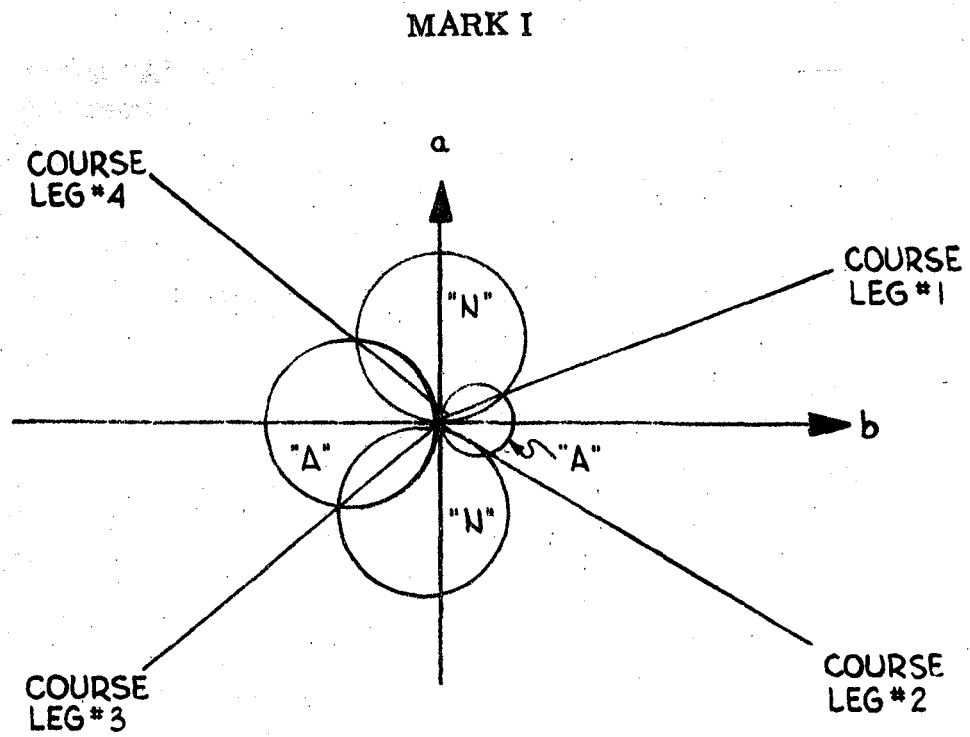


Figure 4-27. A-N Course Legs

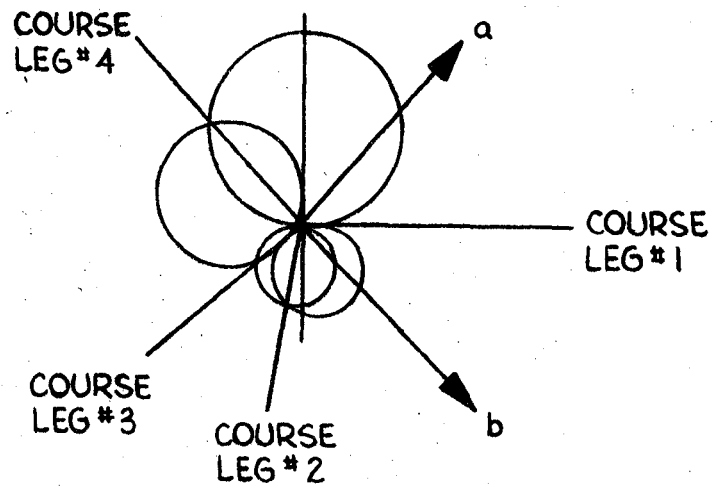


Figure 4-28. A-N Range Rotation

MARK I

4-88. A-N Audio. To simulate the A-N audio, a servo with "A" audio on one end of a potentiometer and "N" audio on the other end of the potentiometer (figure 4-29) is required.

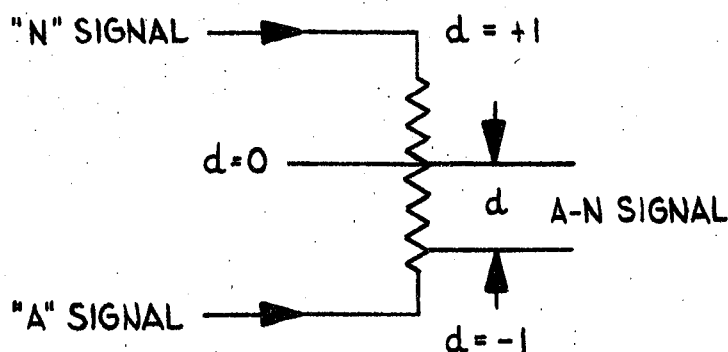


Figure 4-29. A-N Range Audio Servo

4-89. The "A-N Range Audio" servo will have an input which represents the "A" to "N" signal ratio. If d is the servo displacement from center, then $d_{\max} = +1$ and $d_{\min} = -1$. Solving for d as a function of n and a , the following equations are derived:

$$n = \frac{1 + d}{2}$$

$$a = \frac{1 - d}{2}$$

$$\frac{a}{n} = \frac{1 - d}{1 + d}$$

$$a + da = n - dn$$

$$d = \frac{n - a}{n + a} \quad (1)$$

where a and n are the signal levels of the A-N signals of the aircraft.

4-90. Assuming that the "a - b" coordinates to the aircraft have been solved (paragraph 4-73), refer to figures 4-30 and 4-31.

MARK I

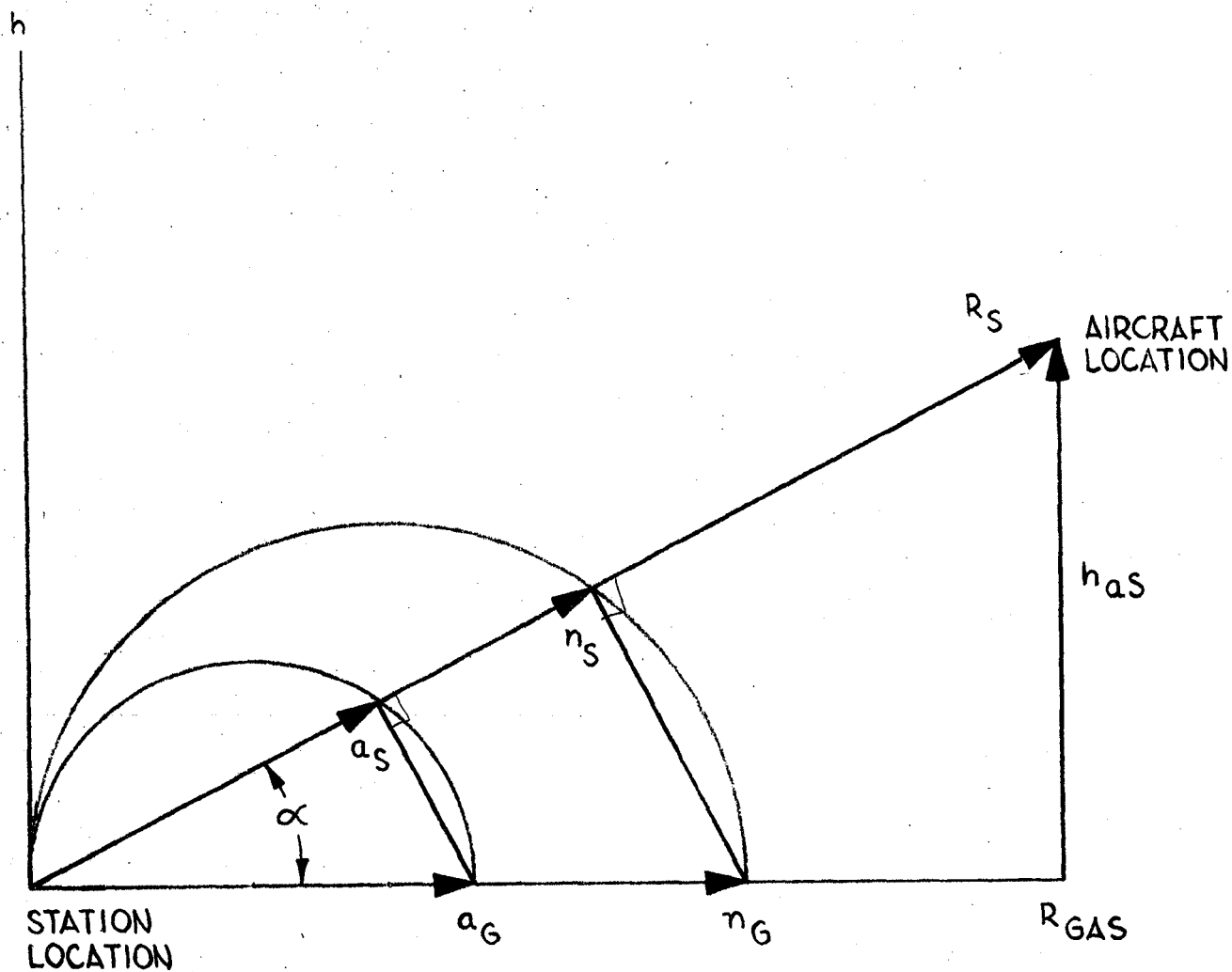


Figure 4-30. A-N Range-Vertical Plane

Since "a" and "n" are the audio signal levels at the aircraft

$$a = \frac{K a_s}{R_s} \quad (2)$$

$$n = \frac{K n_s}{R_s} \quad (3)$$

where K is a constant of proportionality which is dependent on the power and range of the facility

R_s is slant range

a_s and n_s are relative slant range vectors illustrated in figure 4-30.

MARK I

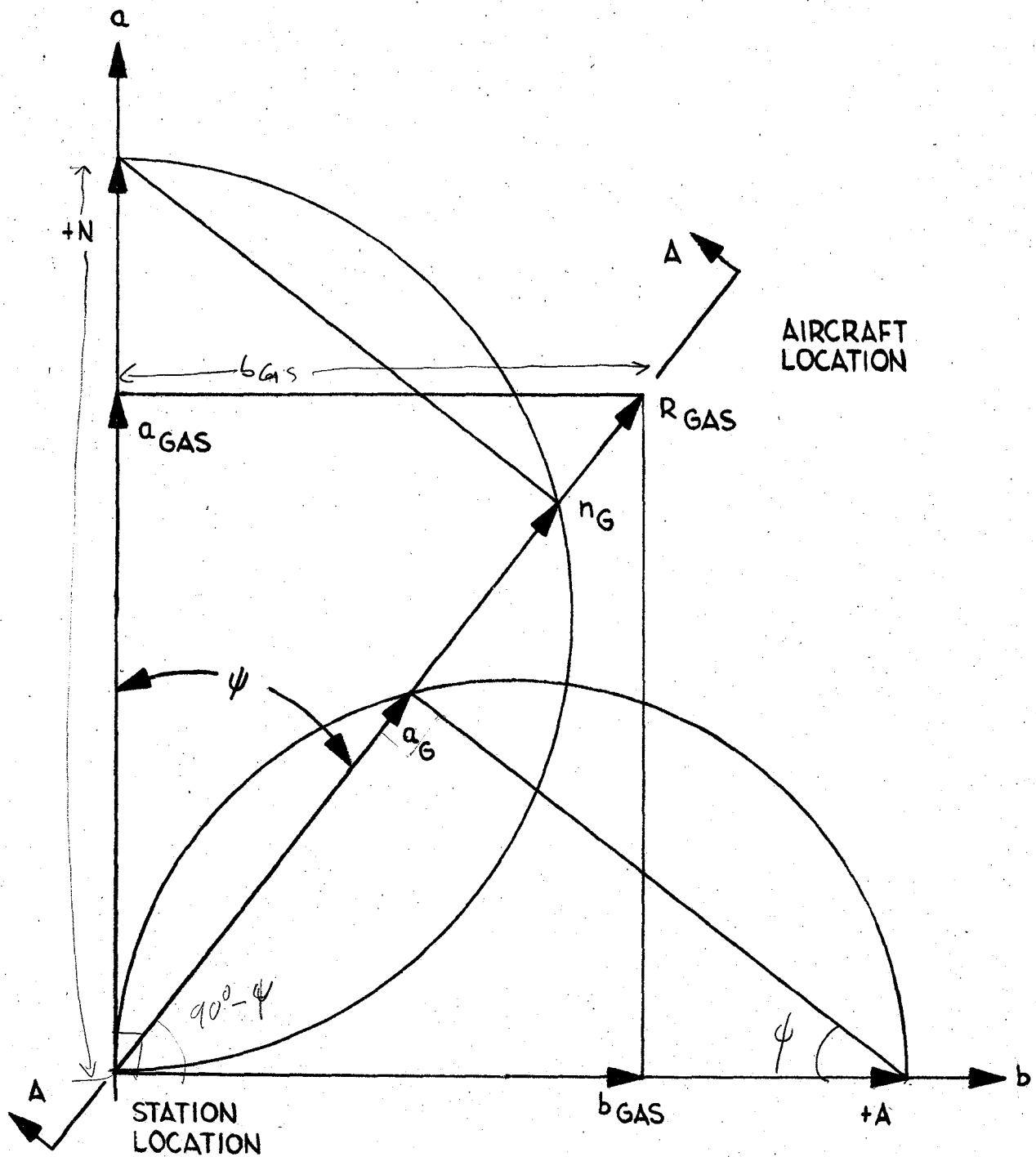


Figure 4-31. A-N Range - Horizontal Plane

MARK I

From figure 4-30

$$a_s = a_G \cos \alpha \quad (4)$$

$$n_s = n_G \cos \alpha \quad (5)$$

$$\cos \alpha = \frac{R_{GAS}}{R_s} \quad (6)$$

From figure 4-31

$$a_G = A \sin \psi \quad (7)$$

$$n_G = N \cos \psi \quad (8)$$

$$\sin \psi = \frac{b_{GAS}}{R_{GAS}} \quad (9)$$

$$\cos \psi = \frac{a_{GAS}}{R_{GAS}} \quad (10)$$

Combining equations (2), (4), (6), (7), and (9)

$$a = \frac{KA b_{GAS}}{R_s^2} \quad (11)$$

Similarly, equations (3), (5), (6), (8), and (10) become

$$n = \frac{KN a_{GAS}}{R_s^2} \quad (12)$$

Substituting equations (11) and (12) into equation (1), the servo input becomes

$$\frac{KN a_{GAS}}{R_s^2} - \frac{KA b_{GAS}}{R_s^2}$$

$$d = \frac{KN a_{GAS}}{R_s^2} + \frac{KA b_{GAS}}{R_s^2}$$

$$d = \frac{N a_{GAS} - A b_{GAS}}{N a_{GAS} + A b_{GAS}} \quad (13)$$

4-91. The diameters of the four circular patterns required on the "Radio Facility Data" sheet are obtained by using the following equations:

$$\theta = \gamma_3 - \gamma_4 + 180^\circ$$

MARK I

$$\phi = \gamma_1 - \gamma_2 + 180^\circ$$

$$\alpha = \gamma_3 - \gamma_2$$

$$\beta = \gamma_1 - \gamma_4 + 360^\circ$$

where γ_1 through γ_4 are given

$$k = \tan(\beta - \theta) + \left[\frac{1}{\tan \alpha \tan \theta} \right] [\tan \alpha + \tan \theta + \tan(\beta - \theta)]$$

$$\tan b = \frac{-k + \sqrt{k^2 + 4}}{2}$$

$$\epsilon^\circ = \gamma_3^\circ - b^\circ - 180^\circ$$

where ϵ° is the angle of rotation of the pattern

$$a = \theta - b$$

$$c = \beta - a$$

$$d = \alpha - b$$

$$D = 1 \sqrt{\left(\frac{\tan b}{\tan d} \right)^2 + \tan^2 a + \tan^2 b + 1}$$

$$A = /D \tan a/$$

$$C = /D \tan b/$$

$$B = /C \tan d/$$

where A, B, C and D are the diameters of the four circular patterns.

4-92. A sample "A-N Range Data Sheet" is shown in figure 4-32.

4-93. The A-N Range pattern for the information contained in row 1 of figure 4-32 is shown in figure 4-33.

MARK I

GIVEN ANGLES								ANGLE OF ROTATION		CIRCLE DIAMETERS								
$\gamma_1 + 10^6$		$\gamma_2 + 10^6$		$\gamma_3 + 10^6$		$\gamma_4 + 10^6$		$\epsilon \pm 10,000$		A + 100		B + 100		C + 100		D + 100		
1	1000	090.0	1000	175.0	1000	229.0	1000	346.0	10	029.225	10	0.6251	10	0.34814	10	0.23709	10	0.66056
2	1000	049.0	1000	156.0	1000	229.0	1000	336.0	10	012.499	10	0.42010	10	0.56841	10	0.42060	10	0.56841
5	1000	057.0	1000	107.0	1000	237.0	1000	302.0	-10	004.566	10	0.51847	10	0.28073	10	0.71026	10	0.38457
13	1000	002.0	1000	092.0	1000	182.0	1000	272.0	-10	043.000	10	0.50000	10	0.50000	10	0.50000	10	0.50000
25	1000	049.0	1000	148.0	1000	229.0	1000	310.0	10	004.000	10	0.57206	10	0.57206	10	0.41562	10	0.41562
31	1000	041.0	1000	123.0	1000	221.0	1000	303.0	-10	008.000	10	0.53366	10	0.46390	10	0.53366	10	0.46390

Figure 4-32. A-N Range Data Sheet

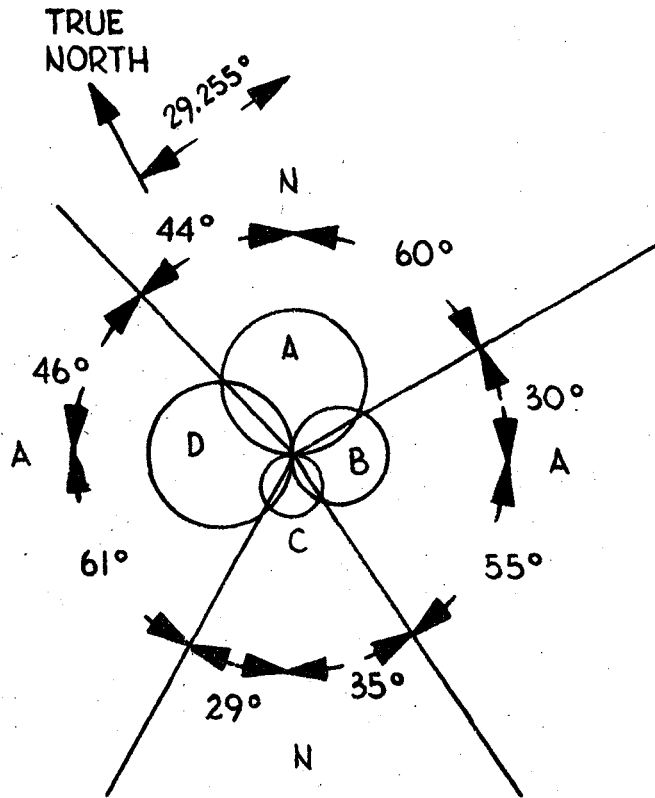


Figure 4-33. A-N Pattern for Row 1 Figure 4-32

MARK I

4-94. SAWTOOTH GENERATION FOR CONTINUOUS ROTATION SERVO DRIVE.

4-95. General. In order to drive the continuous-rotation servos associated with the simulator peripheral equipment, it is necessary to generate two voltages linear with respect to the shaft angle as shown in figure 4-34.

4-96. If the angle exists explicitly in core memory, there will be a linear function of the angle. This function may have to be modified in some way to get it in a form similar to the "Red" sawtooth of figure 4-34 and, then have unity added to or subtracted from it to get the "Black" sawtooth. This is a matter of routine programming.

4-97. If, however, the sine and cosine of the angle is in core memory the problem is more complex. The starting point is a truncated series for the arcsine:

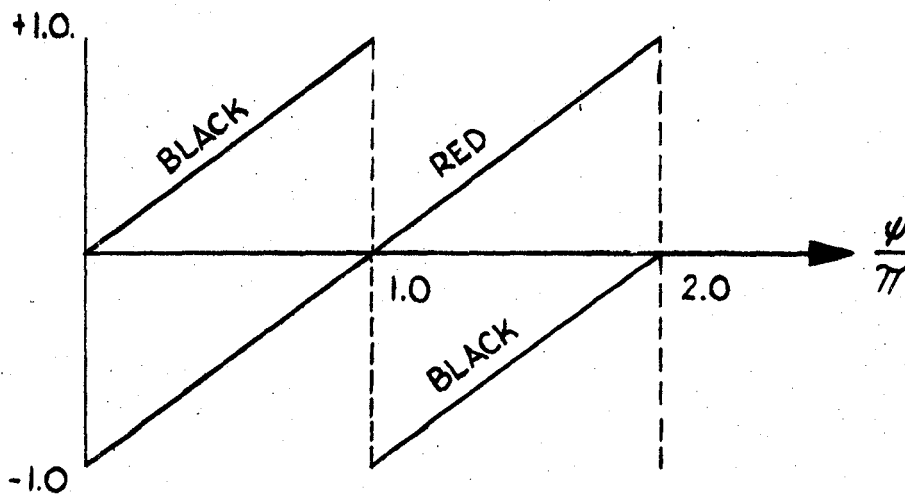


Figure 4-34. Sawtooth Functions

MARK I

$$\theta = \sin^{-1} Z = Z \left[a' + b' \cdot Z^2 \right] \quad (1)$$

where $a' = 0.986706$
 $b' = 0.24803$

4-98. Equation (1), with the given value of the constants, is valid for $-45^\circ \leq \theta \leq +45^\circ$. It is exact at zero and at the end points and has a maximum error of 7.32 minutes in this range.

4-99. Relationship Between θ and ψ . Because of the restricted range of validity of equation (1), the quadrant in which ψ lies must be determined to operate on it appropriately. If the angle lies in the first quadrant, subtraction of 45° guarantees a value for θ within the valid range. Likewise, for a second quadrant angle subtract 135° ; third quadrant 225° , and fourth quadrant 315° . Following this scheme the following equations were derived:

First quadrant: $Z = \sin \theta = \sin (\psi - 45^\circ)$
 $= \sin \psi \cos 45^\circ = \cos \psi \sin 45^\circ$
 $= \frac{1}{\sqrt{2}} [\sin \psi - \cos \psi] \quad (2)$

Second quadrant $Z = \theta = \sin (\psi - 135^\circ)$
 $= \sin \psi \cos 135^\circ - \cos \psi \sin 135^\circ$
 $= \frac{1}{\sqrt{2}} [\sin \psi + \cos \psi] \quad (3)$

Third quadrant: $Z = \sin \theta = \sin (\psi - 225^\circ)$
 $= \sin \psi \cos 225^\circ - \cos \psi \sin 225^\circ$
 $= \frac{1}{\sqrt{2}} [\sin \psi - \cos \psi] \quad (4)$

Fourth quadrant: $Z = \theta = \sin (\psi - 315^\circ)$
 $= \sin \psi \cos 315^\circ - \cos \psi \sin 315^\circ$
 $= \frac{1}{\sqrt{2}} (\sin \psi + \cos \psi) \quad (5)$

Handwritten note:
 ~~$0.986706 + 0.24803$~~
 ~~1.234726~~
 1.234726

MARK I

4-100. Equations (2) through (5) all have the same form, differing only in their prefix signs which are systematic, alternating from quadrant to quadrant. To simplify the equations the following identities are assumed:

$$x = \sin \psi, y = \cos \psi, \text{ and } H = |x| = |y|$$

Equation (1) becomes:

$$\theta = \frac{+H}{2} \left[a' + \frac{b' H^2}{2} \right] \quad (1a)$$

or, normalizing with respect to π

$$\theta' = \pm H \left[a' + bH^2 \right] \quad (6)$$

where: $a = \frac{a'}{\sqrt{2\pi}} = 0.22208686$

$$b = \frac{b'}{2\sqrt{2\pi}} = 0.02791314$$

The plus sign applies in quadrants I and III, and the minus sign in quadrants II and IV.

4-101. The relationship required between θ and ψ , as defined in paragraph 4-99 and as given by equation (6), in normalized coordinates, is shown in figure 4-35.

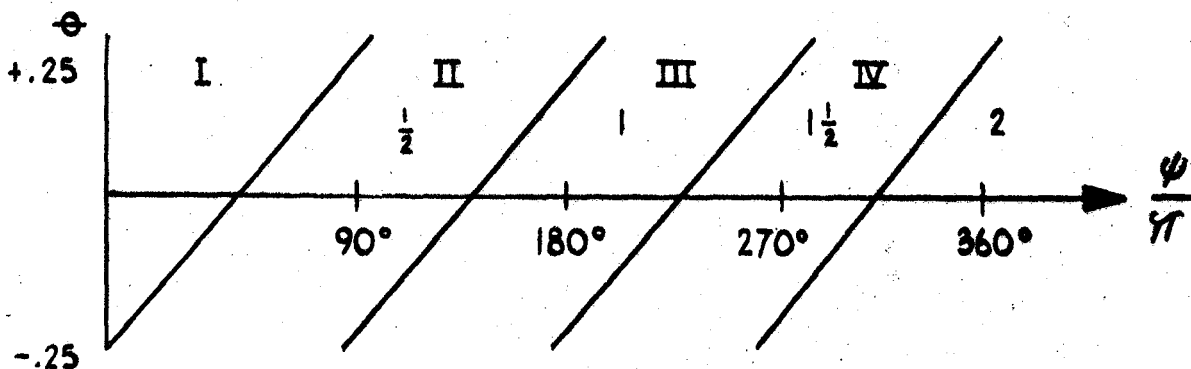


Figure 4-35. Relationship Between θ and ψ In Normalized Ordinates

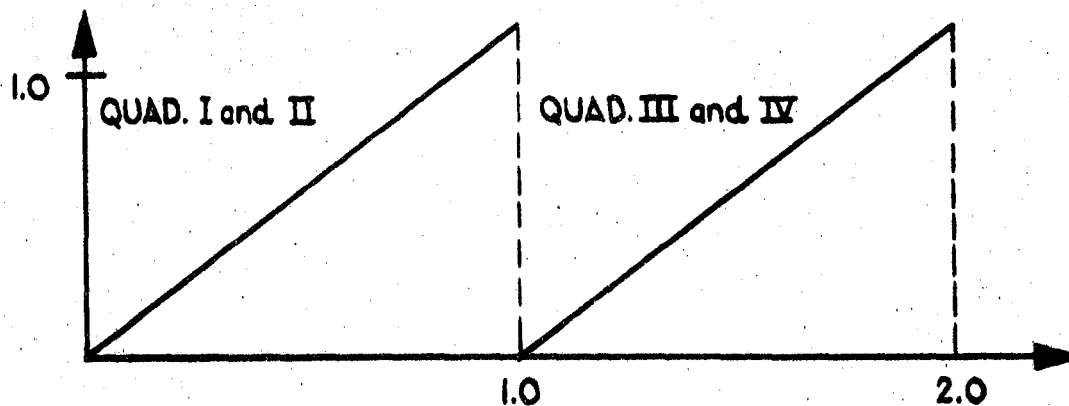


Figure 4-36. Results of Addition to Figure 4-35

4-102. Comparison of figures 4-34 and 4-35 illustrates what must be done in programming to compute the sawtooth. If one-fourth is added to the curves in figure 4-35 corresponding to quadrants I and III, and three-fourths to the curves for quadrants II and IV the result will be as shown in figure 4-36.

4-103. If the angle lies in quadrant I or quadrant II equation (6) has effectively given the "Black" sawtooth. If the angle is in quadrant III or IV solve for the "Red" sawtooth. In either case it is only necessary to subtract unity to obtain the other function.

4-104. Quadrant detection is achieved by defining three Boolean functions:

1. $K_1 = 1$ when $\sin \psi < 0$
2. $K_2 = 1$ when $\cos \psi < 0$
3. $K_3 = K_1 \oplus K_2 = K_1\bar{K}_2 + \bar{K}_1K_2 = 1$ when $K_1 = K_2$
 or $K_3 = \overline{K_1 \oplus K_2} = \bar{K}_1\bar{K}_2 + K_1K_2 = 1$ when $K_1 = K_2$

4-105. $K_1 = 1$ means that $\pi\psi < 2\pi$ and $K_3 = 1$. In the second sense it means that the angle is either in quadrant I or quadrant III. The second form for K_3 is more convenient in implementing the program. These two functions are sufficient to establish all necessary conditions.

4-106. Figure 4-37 is a sample problem of this nature. The "Black" sawtooth is assumed to be stored in core memory location 0646, and the "Red" sawtooth in 0647. Other locations, while given, were chosen at random.

DATE 26 MAY 1963
 PROBLEM 360° SERVO DRIVE
 PROGRAMMER R. E. MACK

CODING AND CONSTANT SHEET
 MARK I COMPUTER

F-2214-A

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE	MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV.				REMARKS	
								1	2	3	4		
01	LD	20	2412	2°	$y = \cos \psi$								
02	FLN	16	0000			k2							k2 = 1 In Quadrants II and III
03	ABS	14	0000		$y = / \cos \psi /$								
04	LD	20	2411		$x = \sin \psi$								
05	FLN	16	0000			k1							k1 = 1 In Quadrants III and IV
06	ABS	14	0000		$x = / \sin \psi /$								
07	SUB	02	0000		$ x - y \triangleq H$								
08	ST	23	3766	2°	H								
09	SQ	05	0000										
10	BLD	33	0000			k2							
11	AND	31	0000			k1 k2							
12	BLD	33	0000			k1							
13	OR	30	0002		H ²	k1 + k2							
14	MLT	03	2460										
15	BIN	32	0000			$\overline{K1} \overline{K2}$							
16	OR	30	0000			$\overline{K3} = \overline{K1} \oplus \overline{K2} = k1 k2 + \overline{K1} \overline{K2}$							$\overline{K3} = 1$ In Quadrants I and III
17	NPA	12	0000										
18	NPB	25	3777		bH^2								
19	ADD	01	2461		$a + bH^2$								
20	MLT	03	3760										
21	NPA	12	0000										
22	NPB	25	3777										
23	NPA	12	0000										
24	NPB	25	3777		$\Theta = H(a + bH^2)$								
25	SKP	26	0002										Skip If In Quadrants I or III
26	INS	13	0000		$\Theta = H(a + bH^2)$								
27	ADD	01	2462		$\Theta + 1/2$								
28	ADD	01	2463		$\Theta + 1/4$ or $\Theta + 3/4$								Dependent on Conditional Skip
29	BLD	33	0001			k1							k1 = 1 If Red Sawtooth Has Been Computed
30	IST	24	0648										Either Red or Black

MARK I

Figure 4-37. 360° Servo Drive (Sheet 1 of 2)

DATE 26 MAY 1963
 PROBLEM 360° SERVO DRIVE
 PROGRAMMER R. E. MACK

CODING AND CONSTANT SHEET
 MARK I COMPUTER

F-2214-A

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE	MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
3 1	SUB	0 2	2 4 6 4									Subtract One From the Contents of the Accumulator to Form the Remaining Sawtooth
3 2	BIN	3 2	0 0 0 0			ET						
3 3	IST	2 4	0 6 4 6									
3 4	LD	2 0	0 6 4 7		"Red" Sawtooth							
3 5	SCL	1 0	1 0 0 2		1/4 ("Red" Sawtooth)							Take the "Red" Sawtooth Which Varies From -1 to +1 Over 360°, Divide by Four and Add One-Fourth. The "Red" Sawtooth Will Now Vary From -1/2 to +1/2
3 6	ADD	0 1	2 4 6 3		1/4 ("Red" Sawtooth) + 1/4							
3 7	ST	2 3	1 0 0 0									
												The Above Program Assumes That Steps 34 Through 37 Have Been Completed Previously

MARK I

Figure 4-37. 360° Servo Drive (Sheet 2 of 2)

MARK I

4-107. RATE DRIVE FOR CONTINUOUS ROTATION SERVOS.

4-108. General. Functions such as ADF manual loop drive or gyro precession terms require a method of driving position-servos in such a way as to give the effect of velocity servo performance. The sample program discussed in the following paragraphs gives this effect.

4-109. Two assumptions are to be made in this sample program. The first is that a modified form of the "Red" sawtooth (refer to paragraphs 4-94 through 4-106), associated with the angular function involved (see figure 4-38), has been generated and stored in the machine as part of the basic sawtooth-generation program (paragraph 4-106).

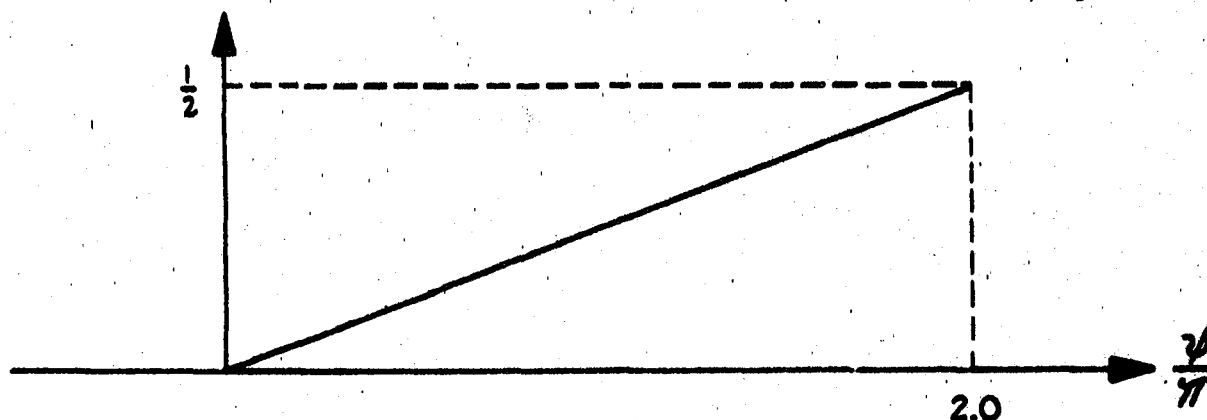


Figure 4-38. Modified "Red" Sawtooth

4-110. The second assumption is that an incremental angle, $\Delta\psi$, as a function of the required rate and the band on which the program has been written has also been stored in the Mark I.

4-111. The modified "Red" sawtooth as shown in figure 4-38 is used for two reasons. First, it makes the program overflow-proof, and, second, it simplifies the generation of Boolean control functions. Let the following functions hold true.

Arithmetic:

$\Delta\psi$ = Incremental Angle

ψR = Last computed value of modified sawtooth

$\psi'R = \psi R + \Delta\psi$ = New value of modified sawtooth

Boolean:

A = 1 when $\Delta\psi$ is negative

B = 1 when $(\psi'R - 1/2)$ is negative

C = 1 when $\psi'R$ is negative

MARK I

4-112. Examination of figure 4-38 shows that there are two critical points for $\psi' R$ to be checked. Obviously, if $\psi' R$ has a value near zero and $\Delta\psi$ is negative, $\psi' R$ must be checked to see if it is negative. If $\psi' R$ is negative add one-half to obtain the correct value. If $\psi' R$ has a value near one-half and $\Delta\psi$ is positive, $\psi' R$ must be checked to see if it is greater than one-half. If this condition exists, subtract one-half to obtain the correct value. Under any other circumstances, the computed value of $\psi' R$ is the correct value.

4-113. $\psi' R$ must be "operated" on to retrieve the correct form for the "Red" sawtooth, and either add or subtract one, as required, to obtain the "Black" sawtooth. Figure 4-39 is a sample program for a problem of this type.

4-114. DIAGNOSTIC PROGRAM.

4-115. Diagnostic programs serve as a check to ensure that the Mark I is performing functions within its capabilities (adding, subtracting, multiplying etc.).

4-116. Diagnostic programs utilize the "Conditional Stop" instruction in conjunction with the "Conditional Skip" instruction in all phases of the program (i.e., if a certain condition is met, skip to the next part of the program; if not, stop). As readily seen this type of program is a valuable aid to maintenance personnel.

4-117. A sample diagnostic program to check the multiplication process within the Mark I is illustrated in figure 4-40.

4-118. PUNCHED CARDS.

4-119. General. IBM type 5081 punched paper cards are used to contain the permanent program for the Mark I. Each card has 80 vertical columns and ten horizontal rows numbered zero through nine. Above row zero there is space for two punches. The "eleven" punch is parallel with and directly above row zero, with the "twelve" punch in parallel and above the "eleven" punch.

4-120. The allowable characters to be punched on the cards for use in conjunction with the Mark I and Tape Preparation Unit (including Card Reader), are the ten numerics (zero through nine), all upper case alphabets, and the following special characters:

- a. Left Parenthesis (Punch in rows 0, 4, and 8)
- b. Right Parenthesis (Punch in rows 12, 4, and 8)
- c. Left Bracket (Punch in rows 11, 3, and 8)
- d. Right Bracket (Punch in rows 0, 3, and 8)
- e. Equal Sign (Punch in rows 3 and 8)

DATE 26 MAY 1963
 PROBLEM VELOCITY SERVO DRIVE
 PROGRAMMER J. HOOP

CODING AND CONSTANT SHEET
 MARK I COMPUTER

PAGE 1 OF 1

F-2214-A

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE	MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
01	LD	20	2763		$\Delta \psi$							Load Incremental Angle
02	FLN	16	0000			A						$A = 1 \Rightarrow \Delta \psi < 0$
03	ADD	01	1000		$\Delta \psi + \psi R = \psi R'$							Form ψR
04	FLN	16	0000			C						$C = 1 = \psi R = 0$
05	SUB	02	2111		$\psi R - 1/2$							
06	FLN	16	0000			B						$B = 1 \Rightarrow \psi R - 1/2 < 0$
07	OR	30	0000			A + B						
08	BIN	32	0000			$A + B = \bar{A}\bar{B}$						
09	SKP	26	0000									
10	ADD	01	2111		ψR							Add 1/2 to Recover ψR
11	BLD	33	0001			A						
12	AND	31	0001			AC						
13	BIN	32	0000			$\overline{AC} = \bar{A} + \bar{C}$						
14	SKP	26	0001									
15	ADD	01	2111		$\psi R + 1/2$							
16	ST	23	2000		ψR							
17	SUB	02	1005		$\psi R - 1/4$							
18	SCL	10	1002		$4 \sqrt{\psi R - 1/4}$							
19	ST	23	2001									Store "Red" Sawtooth
20	FLN	16	0000			D						$D = 1 \Rightarrow \psi R - 1/4 < 0$
21	SKP	26	0003									
22	SUB	02	2500		$4 \sqrt{\psi R - 1/4} - 1$							Subtract One to Get "Black" Sawtooth
23	BIN	32	0000			\bar{D}						
24	SKP	26	0001									
25	ADD	01	2500		$4 \sqrt{\psi R - 1/4} + 1$							Add One to Get "Black" Sawtooth
26	ST	23			$4 \sqrt{\psi R - 1/4} + 1$ or $4 \sqrt{\psi R - 1/4} - 1$							Store "Black" Sawtooth

MARK I

Figure 4-39. Velocity Servo Drive Program

DATE 6-27-63
 PROBLEM DIAGNOSTIC TEST (MULTIPLY)
 PROGRAMMER S. JONES

CODING AND CONSTANT SHEET
 MARK I COMPUTER

PAGE 1 OF 1

F-2214-A

INSTRUCTION NUMBER	MNEMONIC CODE	O.P. CODE	MEM. ADD.	SCALE	ARITHMETIC ACCUMULATOR	SALV.	BOOLEAN ACCUMULATOR	SALV. 1	SALV. 2	SALV. 3	SALV. 4	REMARKS
0 1	LDK	2 2	5 2 5 2		101010101							Load Constant
0 2	SCL	1 0	1 0 0 5									Scale Right Five Places
0 3	SCL	1 0	1 0 0 5									Scale Right Five Places
0 4	SCL	1 0	1 0 0 2									Scale Right Two Places
0 5	LDK	2 2	5 2 5 2		101010101							Load Constant
0 6	ADD	0 1	0 0 0 0		10101010101010101010101 = N = 2/3							Add Salvage Register to Accumulator to Form Constant N = 2/3
0 7	LDK	2 2	2 0 0 0		2 ⁻² = (1/4)							Load Constant
0 8	MLT	0 3	0 0 0 0		2/3 (2 ⁻²)							Multiply By Salvage
0 9	NPA	1 2	0 0 0 0									
1 0	NPB	2 5	3 7 7 7									
1 1	NPA	1 2	0 0 0 0									
1 2	NPB	2 5	3 7 7 7		2/12 = 1/6							
1 3	SFT	1 1	0 0 0 2		1/6 (4) = 2/3 = A							Shift Two Places To Form Constant A = 2/3
1 4	SUB	0 2	0 0 0 0									Subtract Salvage (A - N = Error)
1 5	SCL	1 0	0 0 0 5									
1 6	SCL	1 0	0 0 0 5									
1 7	SCL	1 0	0 0 0 5									
1 8	SCL	1 0	0 0 0 5									
1 9	SCL	1 0	0 0 0 2									
2 0	SFT	1 1	0 0 0 1		(+)							Place The Last Digit Of Answer In The Sign Location
2 1	INV	1 3	0 0 0 0		(-)							
2 2	FLN	1 6	0 0 0 0									
2 3	SKP	2 6	0 0 0 1									Skip To Next Phase Of Program If Answer Correct (Equals 0)
2 4	STP	2 7	0 0 0 0									Stop If Answer Incorrect

MARK I

Figure 4-40. Diagnostic Program

MARK I

- f. Plus Sign (Punch in rows 4 and 8)
- g. Minus Sign (Punch in row 11)
- h. Decimal Point (period) (Punch in rows 12, 3, and 8)
- i. Asterisk (Punch in rows 11, 4, and 8)
- j. Division Sign (Punch in rows 0 and 1)
- k. Ampersand or Plus Sign (Punch in row 12)*

*Used to arm the TPU

NOTE

An "11" punch plus one of the allowable numerics punched in the same column is used for the flag bit. A "12" punch and "11" punch in the same column constitutes the Block End Code.

4-121. Figure 4-41 shows all allowable characters that may be punched on a card when used with the Mark I and Tape Preparation Unit.

4-122. The first card for the first quadrant of each General Purpose or Interpolator band must contain a "12" punch followed by seven NPA instructions. For all other General Purpose or Interpolator band quadrants, and the four Data Preselector band quadrants, the first card must contain a "12" punch followed by one NPA instruction.

4-123. General, Interpolator, Preselector and Core Memory programs have individual card formats.

4-124. General Program Card Formats. General Programs may have either of two card formats:

- a. One instruction per card (same as the "Coding and Constant" sheets).
- b. Eight instructions per card plus a sort number, and an equation "header" card for each individual program within the overall General Program.

4-125. The card format using one instruction per card is as follows:

- a. Column 1 through column 4 are reserved for the equation number. The equation number is dependent upon the type of program being prepared. Table 4-2 lists the equation numbers for the various types of General Programs.

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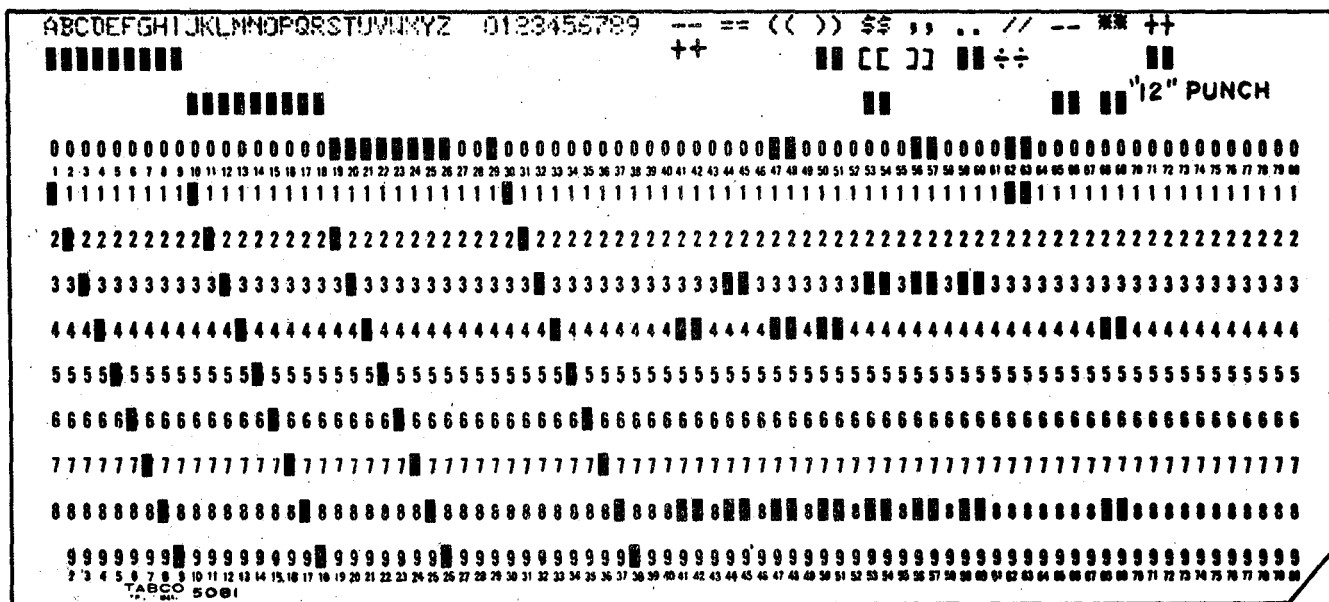


Figure 4-41. IBM Type 5081 Paper Card

Table 4-2. General Program Equation Numbering System

<u>Equation Numbers</u>	<u>Simulator Section</u>
000 - 0999	Flight Equations
1000 - 1999	Expansion
2000 - 2999	Flight Accessories
3000 - 3999	Expansion
4000 - 4999	Engines
5000 - 5250	Air Conditioning, Pressurization etc.
5251 - 5500	Electrical
5501 - 5750	Hydraulics
5751 - 5999	Expansion
6000 - 6999	Engine Accessories
7000 - 7999	Expansion
8000 - 8999	Nav. Comm.
9000 - 9499	Expansion
9500 - 9999	Misc. Simulator

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- b. Columns 5 through 7 are used for the instruction numbers within the specific program.
- c. Column 8 always has a "12" punch to inform the TPU that an instruction is about to be received.
- d. Columns 9 and 10 are used for the O.P. Code.
- e. Column 11 is left blank.
- f. Column 12 through column 15 are reserved for the memory address.
- g. Column 16 always has an "A" punch which disables the TPU.
- h. Column 17 contains either a plus or minus sign for the scale factor.
- i. Columns 18 and 19 are reserved for the scaling factor.
- j. Column 20 is left blank.
- k. Columns 21 through 80 are reserved for remarks.

4-126. The card formats using an equation "header" card and eight instructions per card are as follows:

- a. Equation "header" card.

(1) Columns 1 through 4 contain the equation number. (Refer to paragraph 4-125.)

(2) Columns 5 through 20 are left blank.

(3) Column 21 is either F, M, or S to indicate the type of band to be used.

(4) Column 22 would contain a number one through eight to indicate which one of the particular bands is to be used.

(5) Column 23 is used to indicate which drum quadrant the equation is on. If the equation is for slow band four quadrant three, column 21 would contain S, column 22 would be four and column 23 would be three.

(6) Column 24 is left blank.

(7) Columns 25 through 26 contain the three digits giving the total number of instructions for the equation. (The header card is considered an instruction.) Thus, a 29 step program appears as 030.

(8) Column 27 is left blank.

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- (9) The trainer designation is printed using columns as required.
- (10) The equation name is printed after the trainer designation.
- (11) The name or initials of the programmer follows the equation name.
- (12) The initials of person making the current revision (where applicable) follow the original programmer's name or initials.
- (13) Next the date is printed (this is the original date of the program unless revisions have been made, in which case, the current revision date is used).
- (14) Last, the current revision letter is printed (when applicable).

b. Eight instructions per card format.

(1) Column 1 of the first card in the program contains a "12" punch followed by the NPA instruction. All other cards required in the program would have a "12" punch in column 1 followed by the O.P. Code and Memory Address.

(2) Columns 11, 21, 31, 41, 51, 61 and 71 all contain a "12" punch followed by the O.P. Code and Memory Address.

(3) Columns 78 through 80 contain the octal number of the card in the General Program.

4-127. Linear Function Interpolator Card Formats. The card format for all Interpolator programs is consistent except for the number of cards required to complete the program and the sort number. The sort number is a combination of two alphabetic and three numerics starting with AA001. Card formats for one, two and three variable functions follows.

4-128. Single Variable Function. A single variable function will require five cards to complete the program. All cards will have a "12" punch in column 1 followed by an "11" punch plus the start of the first word in column 2. (The "11" punch is used for the flag bit.) There will be an "A" punched in column 73 of all cards in the program, and the sort number punched in columns 76 through 80.

Card 1. The control word will be punched starting with 100 in column 2.

Card 2. The address of the independent variable X punched five times starting in columns 2, 10, 18, 26 and 34, and preceded by a "12" punch.

Card 3. Contains the dependent variables starting in column 2. Each additional dependent variable will be punched starting eight columns from the start of its predecessor. All dependent variables will be preceded by a "12" punch.

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Card 4. Contains the computer time starting in columns 2 and 10 and preceded by a "12" punch.

Card 5. Contains the answer address repeated five times. This card will also have an "11" punch in column 34.

4-129. Two Variable Function. A two variable function will require a maximum of 14 cards to complete the program depending upon the size of the data field.

Card 1. Same as Card 1 paragraph 4-128 except the control word will start with 200 in column 2.

Card 2. Same as Card 2 paragraph 4-128.

Card 3. Address of independent variable Y. Card format is the same as Card 2 paragraph 4-128.

Card 4. Same as Card 3 paragraph 4-128.

Card 5- Card 12 (where required). Same as Card 3 paragraph 4-128 except there will not be an 11 punch in column 2 in any of these cards.

Card 13. Computer Time. Same as Card 4 paragraph 4-128 except repeated in columns 18 and 26.

Card 14. Answer Address. Same as Card 5 paragraph 4-128.

4-130. Three Variable Function. A three variable function could require up to 87 cards to complete the program.

Card 1. Same as Card 1 paragraph 4-128 except the control word will start with 300 in column 2.

Card 2 and Card 3. Same as Card 2 and 3 paragraph 4-129.

Card 4. Address of the independent variable Z. Card format is the same as Card 2 paragraph 4-128.

Card 5. Same as Card 4 paragraph 4-129.

Card 6 - Card 85 (where required). Same as Card 5 - Card 12 paragraph 4-129.

Card 86. Same as Card 13 paragraph 4-129 except repeated in columns 34 and 42.

Card 87. Same as Card 5 paragraph 4-128.

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4-131. Data Preselector Card Format. The card format for Data Preselector programs is consistent except for the number of cards required to program the various groups of facilities. (See Appendix A.)

4-132. Each Data Preselector Card will contain the following information:

- a. Type of facility
- b. Call letters
- c. Memory address . (Refer to paragraph 3-64.)
- d. Simulator designation
- e. Facility information (one word per card i.e., latitude, longitude, frequency etc.).

The binary equivalent of the facility information may also be punched on the card, but this is optional.

4-133. A "12" punch used to inform the TPU that information is about to be received must be in the column directly preceding the facility information.

4-134. Data Preselector cards will have the first letter of the facility type punched in column 1, and the last numeric of the facility information (binary equivalent only) in column 80. All other information is approximately evenly spaced across the card.

4-135. Core Memory Cards. The punched paper cards used in conjunction with the Core Memory have no specific card format. The only requirement is that a "12" punch appear in the column directly preceding the Core Memory word. The Core Memory card usually contains from one to four Core Memory words.

4-136. TAPE FORMATS.

4-137. Work Tapes. A paper work tape shall be prepared on the Tape Preparation Unit (TPU) through keyboard entry or by using the tape reader to copy another work tape. Work tapes shall have a maximum content of one 1,024-word block of data, and shall not be used to operate the drum loader. Work tapes can be reproduced with blank spaces but shall ignore deletes.

4-138. Work Tape Special Codes. The following special codes shall be included in a work tape:

- a. Block End, or Stop Code: 11111·001 shall indicate the end point of a quadrant (block of 1,024 words).

MARK I

b. Delete Code: 1111:111 shall be used by the operator to delete any desired tape data word. This code must be punched over all lines of the work to be deleted.

c. Gap Code: 0000:000 shall be used as desired between data words to provide tape gaps for later insertion of modified words or for tape splicing. A work tape may be spliced between any two data words.

d. Dummy Code: 0111 shall be placed at the most signification end of the first line of each data word except for general purpose instruction words. This dummy code will be punched automatically in each first line when used.

4-139. Master Tapes. A master tape (paper backed Mylar) shall be prepared on the TPU by using: (1) the tape reader to copy a work tape or a previous master tape; (2) keyboard entry, or (3) readout of the accumulator or core memory contents.

4-140. The form of the data words on a master tape shall be identical with their form on a work tape, but delete codes shall not be permitted on the master, and there will be no gap codes, except between data blocks. The transformation of a work tape to a master tape shall consist of removal of all deleted data words and of all gaps within the data block.

4-141. If the master tape contains more than one data block, the succeeding blocks must be arranged in block address order. The setting of the first block address into the drum loader is performed manually, but succeeding blocks shall be transferred automatically to addresses in ascending order. Table 4-3 lists the address for the first word in each block (quadrant), and the band on which the quadrant is located.

4-142. The final block of a multiple-block master tape will have a block end code (paragraph 4-138) modified to a reel end code: 1111.101, through the operation of a manual keyboard control. In a single-block master tape, the block end code will stop the drum loader, but in a multiple-block master, a control change will cause the block end code only to load the block data and then continue, while the reel end code stops the drum loader.

4-143. Each tape used for loading the first quadrant of every General Purpose or Interpolator band must be started with seven NPA instructions while every other quadrant associated with either the General Purpose or Interpolator bands must be started with one NPA instruction. Data Preselector tape need only have one NPA instruction for the start of each quadrant.

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Table 4-3. Drum Loader Quadrant Addresses

<u>BAND</u>	<u>QUADRANT</u>	<u>ADDRESS</u>
FAST	1	000
	2	001
	3	002
	4	003
MEDIUM 1	1	010
	2	011
	3	012
	4	013
MEDIUM 2	1	020
	2	021
	3	022
	4	023
MEDIUM 3	1	030
	2	031
	3	032
	4	033
SLOW 1	1	040
	2	041
	3	042
	4	043
SLOW 2	1	050
	2	051
	3	052
	4	053
SLOW 3	1	060
	2	061
	3	062
	4	063
SLOW 4	1	070
	2	071
	3	072
	4	073

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Table 4-3. Drum Loader Quadrant Addresses (Cont)

<u>BAND</u>	<u>QUADRANT</u>	<u>ADDRESS</u>
INTERPOLATOR 1	1	130
	2	131
	3	132
	4	133
INTERPOLATOR 2	1	140
	2	141
	3	142
	4	143
INTERPOLATOR 3	1	150
	2	151
	3	152
	4	153
INTERPOLATOR 4	1	160
	2	161
	3	162
	4	163
DATA PRESELECTOR	1	170
	2	171
	3	172
	4	173

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4-144. PREPARATION OF DUPLICATE TAPE (CHANGE IN ONE OR MORE COMPUTER WORDS).

4-145. To prepare a new tape with corrections or changes in certain address locations (tape to tape), proceed as follows:

a. Set the four location digiswitch (located on the tape reader panel) to the first address where a correction is to occur.

b. Activate the proper mode button for the type of tape to be changed (i.e., General Purpose, Interpolator, Data Preselector etc.).

c. Place the Tape Preparation Unit in the tape reader mode by activating either the "Master Tape" or "Work Tape" buttons.

d. Press the "select" button, then the "start" button both located below the digiswitch.

e. When the tape reader stops, activate the keyboard select switch and enter the new computer word or words via the keyboard.

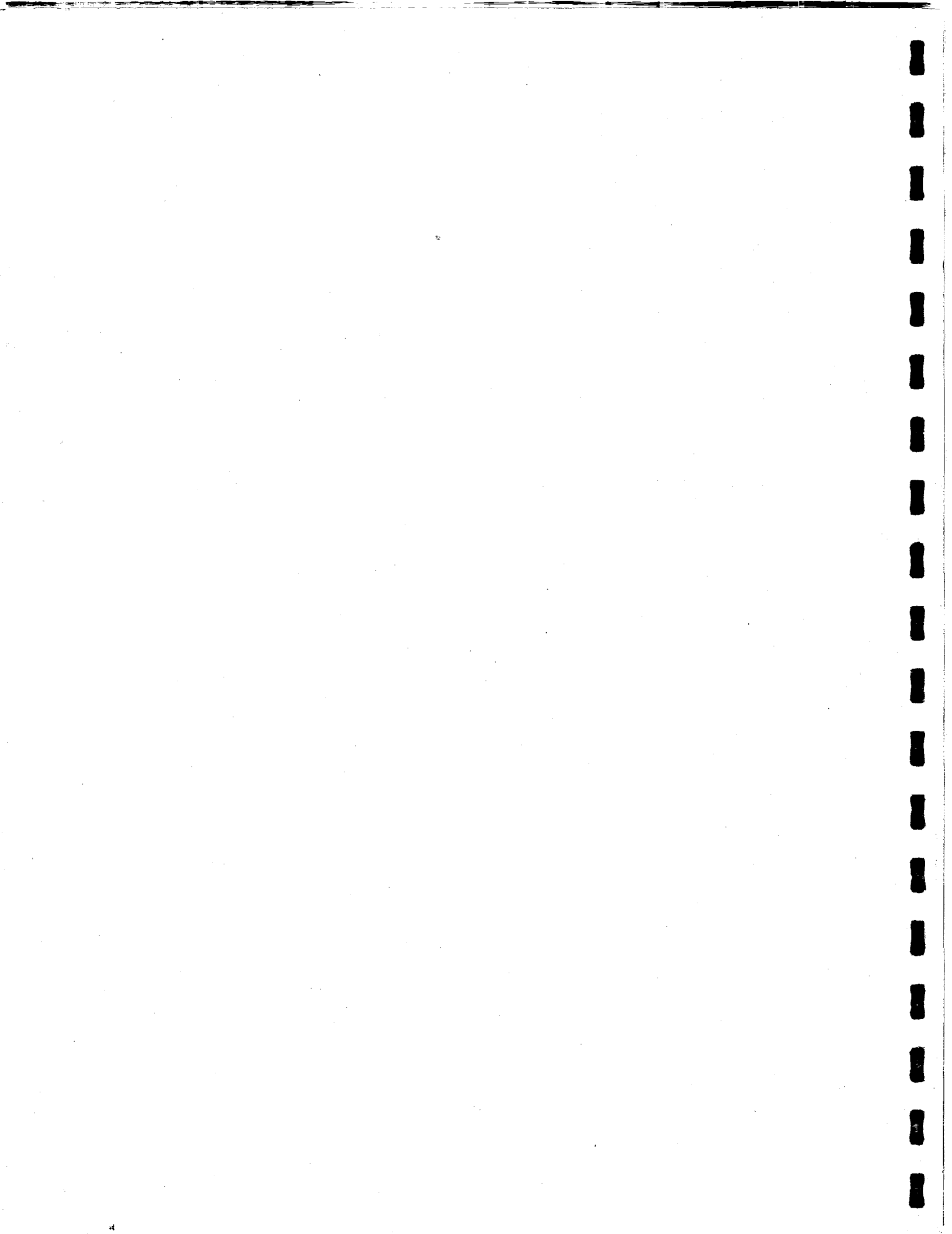
f. Activate the "tape reader" button.

g. Activate the "continue" button.

h. Activate the "start" button.

NOTE

The master clear button must be activated when changing modes.



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APPENDIX A

MARK I COMPUTER MNEMONIC AND NUMERIC CODES

<u>Operation</u>	<u>Mnemonic Code</u>	<u>Numeric Code</u>
Add	ADD	01
Subtract	SUB	02
Multiply	MLT	03
Negative Multiply	NMT	04
Square	SQ	05
Divide	DIV	06
Square Root Step	SRS	07
Scale	SCL	10
Shift	SFT	11
No-Operation	NPA	12
Invert Sign	INS	13
Absolute Value	ABS	14
Zero Slice	ZSL	15
Flag Negative	FLN	16
Load Accumulator	LD	20
Index Load Accumulator	ILD	21
Load Constant	LDK	22
Store Accumulator	ST	23
Index Store Accumulator	IST	24
No-Operation	NPB	25
Conditional Skip	SKP	26
Conditional Stop	STP	27
Boolean Sum	OR	30
Boolean Product	AND	31
Invert Boolean Accumulator	BIN	32
Load Boolean Accumulator	BLD	33
Store Boolean Accumulator	BST	34
Tape Stop Code	TRS	37

10 right

MARK I

TABLES OF POWERS OF 2

2^n	n	2^{-n}																		
1	0	1.0																		
2	1	0.5																		
4	2	0.25																		
8	3	0.125																		
16	4	0.062	5																	
32	5	0.031	25																	
64	6	0.015	625																	
128	7	0.007	812	5																
256	8	0.003	906	25																
512	9	0.001	953	125																
1 024	10	0.000	976	562	5															
2 048	11	0.000	488	261	25															
4 096	12	0.000	244	140	625															
8 192	13	0.000	122	070	312	5														
16 384	14	0.000	061	035	156	25														
32 768	15	0.000	030	517	578	125														
65 536	16	0.000	015	258	789	062	5													
131 072	17	0.000	007	629	394	531	25													
262 144	18	0.000	003	814	697	265	625													
524 288	19	0.000	001	907	348	632	812	5												
1 048	20	0.000	000	953	674	316	406	25												
2 097	21	0.000	000	476	837	158	203	125												
4 194	22	0.000	000	238	418	579	101	562	5											
8 388	23	0.000	000	119	209	289	550	781	25											
16 777	24	0.000	000	059	604	644	775	390	625											
33 554	25	0.000	000	029	802	322	387	695	312	5										
67 108	26	0.000	000	014	901	161	193	847	656	25										
134 217	27	0.000	000	007	450	580	596	923	828	125										
268 435	28	0.000	000	003	725	290	298	461	914	062	5									
536 870	29	0.000	000	001	862	645	149	230	957	031	25									
1 073	30	0.000	000	000	931	322	574	615	478	515	625									
2 147	31	0.000	000	000	465	661	287	307	739	257	812	5								
4 294	32	0.000	000	000	232	830	643	653	869	628	906	25								
8 589	33	0.000	000	000	116	415	321	826	934	814	453	125								
17 179	34	0.000	000	000	058	207	660	913	467	407	226	562	5							
34 359	35	0.000	000	000	029	103	830	456	733	703	613	261	25							
68 719	36	0.000	000	000	014	551	915	228	366	851	806	640	625							
137 438	37	0.000	000	000	007	275	957	614	183	425	903	320	312	5						
274 877	38	0.000	000	000	003	637	978	807	091	712	951	660	156	25						
549 755	39	0.000	000	000	001	818	989	403	545	858	475	830	078	125						

MARK I

RADIO AIDS TYPE CODES

Type Code 1 - MM

Type Code 2 - OM

Type Code 3 - FM

LFM
BONE
Z

Type Code 4 - ILS

ILSDME

Type Code 5 - LVR

MVR
HVR
LVTDME
MVRDME
HVRDME
LVRLTC
LVRMTC
LVRHTC
MVRLTC
MVRMTC
MVRHTC
HVRLTC
HVRMTC
HVRHTC
LTC
MTC
HTC
UHF DF

Type Code 6 - H

HH
MH
BC
LMM
LOM

Type Code 7 - MA

MAZ
ML
MLZ
MRA
MRAZ
MRL
MRLZ
RA
RAZ
RL
RLZ

MARK I

RADIO PRESELECTOR TYPE CODE WORDS

Type Code 1 or 2 MM or OM

- Card 1 - Word 1 0
- Card 2 - Word 2 * 0 0 0 0 0 0 0 0 0 * 1 1 1 1 1 1 1 1 1 1
- Card 3 - Word 3 Latitude lower (10) Latitude upper (10)
- Card 4 - Word 4 Longitude lower (10) Longitude upper (10)
- Card 5 - Word 5 Sign (1) Latitude (19)
- Card 6 - Word 6 Sign (1) Longitude (19)
- Card 7 - Word 7 sine of axis (10) cosine of axis (10)
- Card 8 - Word 8 MISC (6) 0 0 0 0 elevation +1000 (10)

Type Code 3 FM, Z, BONE, LFM

- Card 1 - Word 1 0
- Card 2 - Word 2 * 0 0 0 0 0 0 0 0 0 * 1 1 1 1 1 1 1 1 1 1
- Card 3 - Word 3 Latitude lower (10) Latitude upper (10)
- Card 4 - Word 4 Longitude lower (10) Longitude upper (10)
- Card 5 - Word 5 Sign (1) Latitude (19)
- Card 6 - Word 6 Sign (1) Longitude (19)
- Card 7 - Word 7 sine of axis (10) cosine of axis (10)
- Card 8 - Word 8 type (4) 0 0 0 0 0 0 elevation +1000 (10)
- Card 9 - Word 9 call letters (16) MISC (4) (16 one's for Z)
- Card 10 - Word 10 call letters (16) MISC (2) 00 (16 one's for Z)
- Card 11 - Word 11 call letters (16) 0 0 0 0 (16 one's for Z)
- Card 12 - Word 12 call letters (16) 0 0 0 0 (16 one's for Z)

Type Code 4 ILS, ILS/DME

- Card 1 - Word 1 0
- Card 2 - Word 2 frequency (10) frequency (10)
- Card 3 - Word 3 Latitude lower (10) Latitude upper (10)
- Card 4 - Word 4 Longitude lower (10) Longitude upper (10)
- Card 5 - Word 5 Sign (1) Latitude (19)
- Card 6 - Word 6 Sign (1) Longitude (19)
- Card 7 - Word 7 Sine of axis (10) cosine of axis (10)
- Card 8 - Word 8 1 DME MISC (6) Elevation +1000 (12) (10 for ILS, 11 for ILS/DME)
- Card 9 - Word 9 Call letter (16) g.p.a. (4) (MSB)
- Card 10 - Word 10 Call letters (16) g.p.a. (4) (LSB)
- Card 11 - Word 11 Call letters (16) RL - R_{tg} (4) (MSB)
- Card 12 - Word 12 Call letters (16) RL - R_{tg} (4) (LSB)

Type Code 6 RBN, LOM, LMM, BC

- Card 1 - Word 1 0
- Card 2 - Word 2 frequency lower (10) frequency upper (10)

- Card 3 - Word 3 Latitude lower (10) Latitude upper (10)
- Card 4 - Word 4 Longitude lower (10) Longitude upper (10)
- Card 5 - Word 5 Sign (1) Latitude 19
- Card 6 - Word 6 Sign (1) Longitude 19
- Card 7 - Word 7 0 frequency 12 0 0 0 0 0 0 0
- Card 8 - Word 8 0 power (9) elevation +1000 (10)
- Card 9 - Word 9 Call letters (16) MISC (4)
- Card 10 - Word 10 Call letters (16) MISC (2) 0 0
- Card 11 - Word 11 Call letters (16) 0 0 0 0
- Card 12 - Word 12 Call letters (16) 0 0 0 0

Type Code 7 LFRR

- Card 1 - Word 1 0
- Card 2 - Word 2 frequency lower (10) frequency upper (10)
- Card 3 - Word 3 Latitude lower (10) Latitude upper (10)
- Card 4 - Word 4 Longitude lower (10) Longitude upper (10)
- Card 5 - Word 5 Sign (1) Latitude (19)
- Card 6 - Word 6 Sign (1) Longitude (19)
- Card 7 - Word 7 0 frequency (12) 0 0 0 0 0 0 0
- Card 8 - Word 8 1 power 9 elevation +1000 (10)
- Card 9 - Word 9 0
- Card 10 - Word 10 Call letters (16) MISC (4)
- Card 11 - Word 11 Call letters (16) MISC (2) 0 0
- Card 12 - Word 12 Call letters (16) 0 0 0 0
- Card 13 - Word 13 diameter circle 1 (10) diameter circle 2 (10)
- Card 14 - Word 14 diameter circle 3 (10) diameter circle 4 (10)
- Card 15 - Word 15 sine axis (10) cosine axis (10)
- Card 16 - Word 16 Sine mag. var. (10) 0 cosine mag. var. (9)

Type Code 5 VOR, TACAN, UHF/DF

- Card 1 - Word 1 0
- Card 2 - Word 2 frequency (10) frequency (10)
- Card 3 - Word 3 Latitude lower (10) Latitude upper (10)
- Card 4 - Word 4 Longitude lower (10) Longitude upper (10)
- Card 5 - Word 5 Sign (1) Latitude (19)
- Card 6 - Word 6 Sign (1) Longitude (19)
- Card 7 - Word 7 sine mag. var. (1) 0 cosine mag. var. (9)
- Card 8 - Word 8 0 type (6) 0 0 0 elevation +1000 (10)
- Card 9 - Word 9 Call letters (16) MISC (4)
- Card 10 - Word 10 Call letters (16) MISC (2) 0 0
- Card 11 - Word 11 Call letters (16) 0 0 0 0
- Card 12 - Word 12 Call letters (16) 0 0 0 0

* Octal Input

- 1. 03 (0 to 1/2)
- 2. 27 (1/2 to full)
- 3. 07 (0 to full)

Binary Output

- 0000000000111111111
- 1000000000111111111
- 0000000000111111111

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OCTAL-DECIMAL INTEGER CONVERSION TABLE (Cont)

4000 to 4777 (Octal) | 2048 to 2559 (Decimal)
Octal Decimal
10000 - 4096
20000 - 8192
30000 - 12288
40000 - 16384
50000 - 20480
60000 - 24576
70000 - 28672

Table with 8 columns (0-7) and rows of octal values (4000-4370, 4200-4270, 4300-4370).

Table with 8 columns (0-7) and rows of octal values (4400-4470, 4500-4570, 4600-4670, 4700-4770).

5000 to 5777 (Octal) | 2560 to 3071 (Decimal)

Table with 8 columns (0-7) and rows of octal values (5000-5070, 5100-5170, 5200-5270, 5300-5370).

Table with 8 columns (0-7) and rows of octal values (5400-5470, 5500-5570, 5600-5670, 5700-5770).

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OCTAL-DECIMAL FRACTION CONVERSION TABLE

OCTAL	DEC.	OCTAL	DEC.	OCTAL	DEC.	OCTAL	DEC.
.000	.000000	.100	.125000	.200	.250000	.300	.375000
.001	.001953	.101	.126953	.201	.251953	.301	.376953
.002	.003906	.102	.128906	.202	.253906	.302	.378906
.003	.005859	.103	.130859	.203	.255859	.303	.380859
.004	.007812	.104	.132812	.204	.257812	.304	.382812
.005	.009765	.105	.134765	.205	.259765	.305	.384765
.006	.011718	.106	.136718	.206	.261718	.306	.386718
.007	.013671	.107	.138671	.207	.263671	.307	.388671
.010	.015625	.110	.140625	.210	.265625	.310	.390625
.011	.017578	.111	.142578	.211	.267578	.311	.392578
.012	.019531	.112	.144531	.212	.269531	.312	.394531
.013	.021484	.113	.146484	.213	.271484	.313	.396484
.014	.023437	.114	.148437	.214	.273437	.314	.398437
.015	.025390	.115	.150390	.215	.275390	.315	.400390
.016	.027343	.116	.152343	.216	.277343	.316	.402343
.017	.029296	.117	.154296	.217	.279296	.317	.404296
.020	.031250	.120	.156250	.220	.281250	.320	.406250
.021	.033203	.121	.158203	.221	.283203	.321	.408203
.022	.035156	.122	.160156	.222	.285156	.322	.410156
.023	.037109	.123	.162109	.223	.287109	.323	.412109
.024	.039062	.124	.164062	.224	.289062	.324	.414062
.025	.041015	.125	.166015	.225	.291015	.325	.416015
.026	.042968	.126	.167968	.226	.292968	.326	.417968
.027	.044921	.127	.169921	.227	.294921	.327	.419921
.030	.046875	.130	.171875	.230	.296875	.330	.421875
.031	.048828	.131	.173828	.231	.298828	.331	.423828
.032	.050781	.132	.175781	.232	.300781	.332	.425781
.033	.052734	.133	.177734	.233	.302734	.333	.427734
.034	.054687	.134	.179687	.234	.304687	.334	.429687
.035	.056640	.135	.181640	.235	.306640	.335	.431640
.036	.058593	.136	.183593	.236	.308593	.336	.433593
.037	.060546	.137	.185546	.237	.310546	.337	.435546
.040	.062500	.140	.187500	.240	.312500	.340	.437500
.041	.064453	.141	.189453	.241	.314453	.341	.439453
.042	.066406	.142	.191406	.242	.316406	.342	.441406
.043	.068359	.143	.193359	.243	.318359	.343	.443359
.044	.070312	.144	.195312	.244	.320312	.344	.445312
.045	.072265	.145	.197265	.245	.322265	.345	.447265
.046	.074218	.146	.199218	.246	.324218	.346	.449218
.047	.076171	.147	.201171	.247	.326171	.347	.451171
.050	.078125	.150	.203125	.250	.328125	.350	.453125
.051	.080078	.151	.205078	.251	.330078	.351	.455078
.052	.082031	.152	.207031	.252	.332031	.352	.457031
.053	.083984	.153	.208984	.253	.333984	.353	.458984
.054	.085937	.154	.210937	.254	.335937	.354	.460937
.055	.087890	.155	.212890	.255	.337890	.355	.462890
.056	.089843	.156	.214843	.256	.339843	.356	.464843
.057	.091796	.157	.216796	.257	.341796	.357	.466796
.060	.093750	.160	.218750	.260	.343750	.360	.468750
.061	.095703	.161	.220703	.261	.345703	.361	.470703
.062	.097656	.162	.222656	.262	.347656	.362	.472656
.063	.099609	.163	.224609	.263	.349609	.363	.474609
.064	.101562	.164	.226562	.264	.351562	.364	.476562
.065	.103515	.165	.228515	.265	.353515	.365	.478515
.066	.105468	.166	.230468	.266	.355468	.366	.480468
.067	.107421	.167	.232421	.267	.357421	.367	.482421
.070	.109375	.170	.234375	.270	.359375	.370	.484375
.071	.111328	.171	.236328	.271	.361328	.371	.486328
.072	.113281	.172	.238281	.272	.363281	.372	.488281
.073	.115234	.173	.240234	.273	.365234	.373	.490234
.074	.117187	.174	.242187	.274	.367187	.374	.492187
.075	.119140	.175	.244140	.275	.369140	.375	.494140
.076	.121093	.176	.246093	.276	.371093	.376	.496093
.077	.123046	.177	.248046	.277	.373046	.377	.498046

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OCTAL-DECIMAL FRACTION CONVERSION TABLE (Cont)

OCTAL	DEC.	OCTAL	DEC.	OCTAL	DEC.	OCTAL	DEC.
.00000	.00000	.000100	.000244	.000200	.000488	.000300	.000732
.00001	.00003	.000101	.000247	.000201	.000492	.000301	.000736
.00002	.00007	.000102	.000251	.000202	.000496	.000302	.000740
.00003	.00011	.000103	.000255	.000203	.000499	.000303	.000743
.00004	.00015	.000104	.000259	.000204	.000503	.000304	.000747
.00005	.00019	.000105	.000263	.000205	.000507	.000305	.000751
.00006	.00022	.000106	.000267	.000206	.000511	.000306	.000755
.00007	.00026	.000107	.000270	.000207	.000514	.000307	.000759
.00010	.00030	.000110	.000274	.000210	.000518	.000310	.000762
.00011	.00034	.000111	.000278	.000211	.000522	.000311	.000766
.00012	.00038	.000112	.000282	.000212	.000526	.000312	.000770
.00013	.00041	.000113	.000286	.000213	.000530	.000313	.000774
.00014	.00045	.000114	.000289	.000214	.000534	.000314	.000778
.00015	.00049	.000115	.000293	.000215	.000537	.000315	.000782
.00016	.00053	.000116	.000297	.000216	.000541	.000316	.000785
.00017	.00057	.000117	.000301	.000217	.000545	.000317	.000789
.00020	.00061	.000120	.000305	.000220	.000549	.000320	.000793
.00021	.00064	.000121	.000308	.000221	.000553	.000321	.000797
.00022	.00068	.000122	.000312	.000222	.000556	.000322	.000801
.00023	.00072	.000123	.000316	.000223	.000560	.000323	.000805
.00024	.00076	.000124	.000320	.000224	.000564	.000324	.000808
.00025	.00080	.000125	.000324	.000225	.000568	.000325	.000812
.00026	.00083	.000126	.000328	.000226	.000572	.000326	.000816
.00027	.00087	.000127	.000331	.000227	.000576	.000327	.000820
.00030	.00091	.000130	.000335	.000230	.000579	.000330	.000823
.00031	.00095	.000131	.000339	.000231	.000583	.000331	.000827
.00032	.00099	.000132	.000343	.000232	.000587	.000332	.000831
.00033	.00102	.000133	.000347	.000233	.000591	.000333	.000835
.00034	.00106	.000134	.000350	.000234	.000595	.000334	.000839
.00035	.00110	.000135	.000354	.000235	.000598	.000335	.000843
.00036	.00114	.000136	.000358	.000236	.000602	.000336	.000846
.00037	.00118	.000137	.000362	.000237	.000606	.000337	.000850
.00040	.00122	.000140	.000366	.000240	.000610	.000340	.000854
.00041	.00125	.000141	.000370	.000241	.000614	.000341	.000858
.00042	.00129	.000142	.000373	.000242	.000617	.000342	.000862
.00043	.00133	.000143	.000377	.000243	.000621	.000343	.000865
.00044	.00137	.000144	.000381	.000244	.000625	.000344	.000869
.00045	.00141	.000145	.000385	.000245	.000629	.000345	.000873
.00046	.00144	.000146	.000389	.000246	.000633	.000346	.000877
.00047	.00148	.000147	.000392	.000247	.000637	.000347	.000881
.00050	.00152	.000150	.000396	.000250	.000640	.000350	.000885
.00051	.00156	.000151	.000400	.000251	.000644	.000351	.000888
.00052	.00160	.000152	.000404	.000252	.000648	.000352	.000892
.00053	.00164	.000153	.000408	.000253	.000652	.000353	.000896
.00054	.00167	.000154	.000411	.000254	.000656	.000354	.000900
.00055	.00171	.000155	.000415	.000255	.000659	.000355	.000904
.00056	.00175	.000156	.000419	.000256	.000663	.000356	.000907
.00057	.00179	.000157	.000423	.000257	.000667	.000357	.000911
.00060	.00183	.000160	.000427	.000260	.000671	.000360	.000915
.00061	.00186	.000161	.000431	.000261	.000675	.000361	.000919
.00062	.00190	.000162	.000434	.000262	.000679	.000362	.000923
.00063	.00194	.000163	.000438	.000263	.000682	.000363	.000926
.00064	.00198	.000164	.000442	.000264	.000686	.000364	.000930
.00065	.00202	.000165	.000446	.000265	.000690	.000365	.000934
.00066	.00205	.000166	.000450	.000266	.000694	.000366	.000938
.00067	.00209	.000167	.000453	.000267	.000698	.000367	.000942
.00070	.00213	.000170	.000457	.000270	.000701	.000370	.000946
.00071	.00217	.000171	.000461	.000271	.000705	.000371	.000949
.00072	.00221	.000172	.000465	.000272	.000709	.000372	.000953
.00073	.00225	.000173	.000469	.000273	.000713	.000373	.000957
.00074	.00228	.000174	.000473	.000274	.000717	.000374	.000961
.00075	.00232	.000175	.000476	.000275	.000720	.000375	.000965
.00076	.00236	.000176	.000480	.000276	.000724	.000376	.000968
.00077	.00240	.000177	.000484	.000277	.000728	.000377	.000972

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OCTAL-DECIMAL FRACTION CONVERSION TABLE (Cont)

OCTAL	DEC.	OCTAL	DEC.	OCTAL	DEC.	OCTAL	DEC.
.000400	.000976	.000500	.001220	.000600	.001464	.000700	.001708
.000401	.000980	.000501	.001224	.000601	.001468	.000701	.001712
.000402	.000984	.000502	.001228	.000602	.001472	.000702	.001716
.000403	.000988	.000503	.001232	.000603	.001476	.000703	.001720
.000404	.000991	.000504	.001235	.000604	.001480	.000704	.001724
.000405	.000995	.000505	.001239	.000605	.001483	.000705	.001728
.000406	.000999	.000506	.001243	.000606	.001487	.000706	.001731
.000407	.001003	.000507	.001247	.000607	.001491	.000707	.001735
.000410	.001007	.000510	.001251	.000610	.001495	.000710	.001739
.000411	.001010	.000511	.001255	.000611	.001499	.000711	.001743
.000412	.001014	.000512	.001258	.000612	.001502	.000712	.001747
.000413	.001018	.000513	.001262	.000613	.001506	.000713	.001750
.000414	.001022	.000514	.001266	.000614	.001510	.000714	.001754
.000415	.001026	.000515	.001270	.000615	.001514	.000715	.001758
.000416	.001029	.000516	.001274	.000616	.001518	.000716	.001762
.000417	.001033	.000517	.001277	.000617	.001522	.000717	.001766
.000420	.001037	.000520	.001281	.000620	.001525	.000720	.001770
.000421	.001041	.000521	.001285	.000621	.001529	.000721	.001773
.000422	.001045	.000522	.001289	.000622	.001533	.000722	.001777
.000423	.001049	.000523	.001293	.000623	.001537	.000723	.001781
.000424	.001052	.000524	.001296	.000624	.001541	.000724	.001785
.000425	.001056	.000525	.001300	.000625	.001544	.000725	.001789
.000426	.001060	.000526	.001304	.000626	.001548	.000726	.001792
.000427	.001064	.000527	.001308	.000627	.001552	.000727	.001796
.000430	.001068	.000530	.001312	.000630	.001556	.000730	.001800
.000431	.001071	.000531	.001316	.000631	.001560	.000731	.001804
.000432	.001075	.000532	.001319	.000632	.001564	.000732	.001808
.000433	.001079	.000533	.001323	.000633	.001567	.000733	.001811
.000434	.001083	.000534	.001327	.000634	.001571	.000734	.001815
.000435	.001087	.000535	.001331	.000635	.001575	.000735	.001819
.000436	.001091	.000536	.001335	.000636	.001579	.000736	.001823
.000437	.001094	.000537	.001338	.000637	.001583	.000737	.001827
.000440	.001098	.000540	.001342	.000640	.001586	.000740	.001831
.000441	.001102	.000541	.001346	.000641	.001590	.000741	.001834
.000442	.001106	.000542	.001350	.000642	.001594	.000742	.001838
.000443	.001110	.000543	.001354	.000643	.001598	.000743	.001842
.000444	.001113	.000544	.001358	.000644	.001602	.000744	.001846
.000445	.001117	.000545	.001361	.000645	.001605	.000745	.001850
.000446	.001121	.000546	.001365	.000646	.001609	.000746	.001853
.000447	.001125	.000547	.001369	.000647	.001613	.000747	.001857
.000450	.001129	.000550	.001373	.000650	.001617	.000750	.001861
.000451	.001132	.000551	.001377	.000651	.001621	.000751	.001865
.000452	.001136	.000552	.001380	.000652	.001625	.000752	.001869
.000453	.001140	.000553	.001384	.000653	.001628	.000753	.001873
.000454	.001144	.000554	.001388	.000654	.001632	.000754	.001876
.000455	.001148	.000555	.001392	.000655	.001636	.000755	.001880
.000456	.001152	.000556	.001396	.000656	.001640	.000756	.001884
.000457	.001155	.000557	.001399	.000657	.001644	.000757	.001888
.000460	.001159	.000560	.001403	.000660	.001647	.000760	.001892
.000461	.001163	.000561	.001407	.000661	.001651	.000761	.001895
.000462	.001167	.000562	.001411	.000662	.001655	.000762	.001899
.000463	.001171	.000563	.001415	.000663	.001659	.000763	.001903
.000464	.001174	.000564	.001419	.000664	.001663	.000764	.001907
.000465	.001178	.000565	.001422	.000665	.001667	.000765	.001911
.000466	.001182	.000566	.001426	.000666	.001670	.000766	.001914
.000467	.001186	.000567	.001430	.000667	.001674	.000767	.001918
.000470	.001190	.000570	.001434	.000670	.001678	.000770	.001922
.000471	.001194	.000571	.001438	.000671	.001682	.000771	.001926
.000472	.001197	.000572	.001441	.000672	.001686	.000772	.001930
.000473	.001201	.000573	.001445	.000673	.001689	.000773	.001934
.000474	.001205	.000574	.001449	.000674	.001693	.000774	.001937
.000475	.001209	.000575	.001453	.000675	.001697	.000775	.001941
.000476	.001213	.000576	.001457	.000676	.001701	.000776	.001945
.000477	.001216	.000577	.001461	.000677	.001705	.000777	.001949

